

ADOLO

CLASSIFICATION CLANCE

Ca. Unideassified

The sutherity of Mission Control Station, NATION Classified Document Master Control Station, NATION FRONTIES

Selentifie and Technical Test atten Facility.

ILABLE TO NASA HEADSUARTERS ONLY

(NASA-CR-11665C) GENERAL TEST PLAN FESEARCH AND DEVELOPMENT FOR PROJECT APCILC SPACECRAFT. VOLUME 3: GROUND QUALIFICATION TESTS (North American Aviation, Inc.) 190 p

145678 N75-70121

Unclas 00/98 06146

SINCLE COPY ONLY

This issue replaces and supersedes all previous issues of this book and SID 62-204.

Copy No. 48

Accession No. 51155

. SID 62-109-3-R-4

GENERAL TEST PLAN
RESEARCH AND DEVELOPMENT FOR
PROJECT APOLLO SPACECRAFT (U)
NAS9-150

Volume III. Ground Qualification Tests

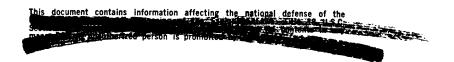
Reissued 30 June 1963

Rev 30 December 1963



Exhibit I, Paragraph 3.3

AVAILABLE TO NASA HEADQUARTERS ONLY



NORTH AMERICAN AVIATION, INC. SPACE and INFORMATION SYSTEMS DIVISION





List of Revised Pages*

iii ivix xv1-1 1-2 2-1 through 2-30 3-1 through 3-20 5-5 5-8 5-16 5-18 5-20 5-22 5-52 5 - 545 - 56 5-71 5-80 5-94 5-98 5-99 7 - 1

Includes revised, reissued, and new pages. Revisions in original text are indicated by a bar on margin of page next to revised material.





CONTENTS

Section													Page
	INTRODU	CTION .	•	•		•	•	•	•	•	•		xv
1.0	SCOPE .		•	•			•	•	•	•	•		1-1
	1.1	PURPO	SE.			•	•		•		•	•	1-1
	1.2	OBJEC	TIVE	•	•	•	•		•	•	•	•	1-1
	1.3	CONFO	RMAN	CE	•	•	•	•	•	•	•	•	1-1
	1.4	REVISION	ONS AI	ND A	MEN	DME	NTS	•	•	•	•	•	1-2
2.0	GROUND	QUALIFI	CATION	V PRO	GRA	М	•	•	•	•	•		2-1
	2.1	QUALIE	FICATI	ON F	ROC	GRAN	1 LO	GIC	•		•	•	2-2
	2.2	RELIA	BILITY	ASS:	ESSI	MEN:	r Lo	GIC		•	•	•	2-2
	2.3	SUBSYS	TEM (QUAL	IFIC	CATIO	ON P	HAS	SES-				
		SPACE	CRAFI	•		•	•	•	•	•			2-3
		2.3.1	Design	n Pro					•		•		2-3
	•	2.3.2				•			•				2-5
		2.3.3	The M	lissio	n Si	mula	tion	Life	Tes	st.			2-11
	2.4	THE CO											2-19
		2.4.1	Logic		•	•	•	•		•			2-19
		2.4.2	Deriva	ation	•		•		•	•			2-20
		2.4.3	Applic	ation		•	•	•	•				2-25
	2.5	THE M				FICA	TION	PR	OGE	RAM			2-27
	2.6	QUALIF	FICATI	ON P	ROC	RAN	1 CO	NTI	NGE	NCIE	ES		2-29
	.2.7	TESTIN	G CRI	TERL	A	•	•		•		•		2-29
		2.7.1	Test E	Equip	men	t	•				•	•	2-29
		2.7.2	Failur	e Re	port	ing,	Anal	ysis	and				
			Feedb	ack S	yste	m	•	•	•	•			2-30
		2.7.3	Adjust	tment	s an	d Re	pairs	. Du	ring	Tes	t		2-30
		2.7.4	Waive	r of	Γest	s	•						2-30
		2.7.5	Hardw	are o	of Te	ests	••		•	•	•	•	2-30
3.0	QUALIFIC	CATION S	SCHEDU	ILES	•	•	•		•	•	•	•	3-1
	3.1	CONCE	\mathtt{PT}	•		•	•		•	•			3-1
	3.2	APPLIC	CATION	1		•	•		•	•		•	3-1
		3.2.1	Explai	nation	ı	•	•	•	•	•	•	•	3-1
		3.2.2	Examp	ole	•	•	•	•	•	•	•		3-1
	3.3	SUBSYS	TEM S	CHE	DUL	ES	•			•		•	3-2
		3.3.1	Servic	e Pr	opul	sion	Syste	em	•	•			3-2
		3, 3, 2			_		•						3-2



•	
10.70 Day	

Section					Page
		3.3.3	Launch Escape System		3-2
		3.3.4	Earth Landing System		3-2
		3. 3. 5	Environmental Control System		3-8
		3. 3. 6	Electrical Power System		3-8
		3.3.7	Guidance and Navigation System	Ĭ.	3-8
		3. 3. 8	Stabilization and Control System	•	3-8
		3. 3. 9	Communications and Instrumentation	•	5 0
		3. 3. 7	Systems		3-8
		2 2 10	Life Systems	•	3-8
			•	•	3-8
			Thermal Protection System	•	3-8
			Structure	•	
			Mechanical Systems	•	3-18
		3. 3. 14	Electronic Systems	•	3-18
4.0	ENVIRO	NMENTAL	CRITERIA		4-1
	4.1	ENVIRO	NMENTAL CONSIDERATIONS		4-1
		4.1.1	Prelaunch Environments		4-1
		4.1.2	LOR Mission Environments		4-1
		4.1.3	GSE Environments		4-1
	4.2	ENVIRO	NMENTAL LEVELS		4-1
		4.2.1	Prelaunch Environmental Levels		
			Anticipated		4-7
		4.2.2	Transportation, Ground Handling, and		
			Storage		4-7
		4.2.3	Post-Launch Environmental Levels .	_	4-10
		4.2.4	Ground Support Equipment Environmental	•	1 10
			Levels	_	4-28
	4.3	ENVIR	NMENTAL TEST PROCEDURES	•	4-31
	1. 3	4. 3. 1	Application of Environments in	•	1-31
		1. 3. 1	Qualification Testing		4-31
		4.3.2	Acceleration	•	4-31
		4. 3. 3	Shock	•	4-31
			Oxidation	•	
		4.3.4 4.3.5		•	4-34
			Vacuum	•	4-35
		4.3.6	Temperature (Low or High)	•	4-35
		4.3.7	Vibration	•	4-37
		4.3.8	Acoustics	•	4-46
		4.3.9	Humidity (Application Limited)	•	4-47
		4.3.10	Electromagnetic Interference	•	4-47
		4.3.11	Sand and Dust (Application Limited) .	•	4-47
		4. 3. 12	Salt Fog (Application Limited)		4-48
	4.4		NED ENVIRONMENTAL TESTS	•	4-48
		4.4.1	Temperature-Vacuum	•	4-48
		4.4.2	Vibration-Acceleration	•	4-48
		4.4.3	Temperature-Vibration	•	4-48





11	,	``, ` `,``	

Section									Page
5.0	SUBSYST	EM QUAL	IFICATION T	ESTS .					. 5 - 1
	5.1		E PROPUL		STEM	_	_		5-1
		5.1.1	Scope .		•				5-1
		5.1.2	Reliability						5-1
			Criticality				ment	s .	5-2
			Qualification						5-2
	5.2		ION CONTR			•	•	•	5 - 6
		5. 2. 1	Scope .			•	•	•	5 - 6
			Reliability			• •1.	•	•	5 - 9
		5.2.3	Criticality				• ment	• •	5 - 9
		5.2.4	Qualification			•			5 - 15
	5.3		H ESCAPE				•	• •	5-19
	3.3	5. 3. 1	Scope .		-	•	•	•	5 - 19
			Reliability				•	•	5 - 19
			Criticality				-		5 - 19
			Qualification			_		S .	5-19
	5.4		LANDING S			•	•	• •	
	J. T					•	•	•	5-33
			Scope . Reliability			.1			5-33
			•						5-34
			Criticality : Qualificatio			quire			5-34
	5.5		NMENTAL			33.6.41	•	• •	5-34
	3. 3		ENIC SUBSY)T 21211	LM A	עט		
					• •	•	•		5-42
			Scope .			•	•		5-42
			Reliability				•		5-42
			Criticality			quire	ment	s.	5-44
	. /		Qualificatio			•			5 - 45
	5.6		RICAL POW	ER SYST	'EM AND	FUE	L		
		CELLS	• •	• •	• •		•	• •	5 -4 5
			Scope .	• •			•	•	5 - 45
			Reliability						5-49
			Criticality a			quirer	nent	s .	5-49
			Qualification			•	•	• •	5-53
	5.7		CE AND NA				•		5-55
			Scope .				•		5-55
			Reliability A				•	• •	5-55
			Criticality a					s .	5-55
			Qualification						5-55
	5.8		ZATION AN	ID CONT	ROL SYS	TEM			5-57
			Scope .						5-57
			Reliability A						5-57
		5.8.3	Criticality a	ınd Hardv	ware Req	uiren	nents		
		5.8.4	Qualification	n Test Sc	hedule				5-60



Section										Page
	5.9	COMMU	JNICATION	s and	INSTR	UMEN	TA TIO	N		
	J.,	SYSTEN						•		5-60
		5.9.1				•				5-60
			Reliability	Asses	sment	Model				5-63
		5 9 3	Criticality	and H	ardwar	e Regi	nireme	nts		5-63
			Qualificati							5-69
	5 10	-	YSTEMS	011 100	, c Democ				_	5-72
	5.10		Scope .	•	•	•			•	5-72
			Reliability	Acces	sement	· Model		•	•	5-80
			Criticality					nts		5-80
			Qualificati						•	5-80
	5 11		IAL PROTE				•	•	•	5-80
	5.11						• •	•	•	5-80
								•	•	5-80
			Reliability					•	•	5-80
			Criticality			_		nts,	•	
	-	-	Qualificati				• •	•	•	5-83
	5.12		TURAL SYS		•	•	• •	•	•	5-85
			Scope .		•	MJ.1	• •	•	•	5-85
			Reliability					•	•	5-85
			Criticality					nts	•	5-85
			Qualificati			iule	• •	•	•	5-85
	5.13		NICAL SYS	STEMS	•	•	• •	•	•	5-85
			Scope .		•			•	•	5-85
			Reliability					•		5-87
			Criticality					nts	•	5-87
			Qualificati		st Sched	lule	• •	•	•	5-92
	5.14	ELECT	RONIC SYS	TEMS	•	•		•	•	5-94
			F			•		•	•	5-94
			Reliability						•	5-94
		5.14.3	Criticality	and H	ardwar	e Req	uireme	nts	•	5-97
		5.14.4	Qualificati	on Tes	st Sched	lule	• •	•	•	5-97
6.0	GROUNE	SUPPOR	RT EQUIPMEN	NT.		•		•		6-1
	6.1				•	•				6-1
			ALIFICATI							6-1
	0.2		Phase A,					•	•	6-2
			Phase B,	_					•	6-3
	6.3		TIONAL RE				•			6-3
	0.5		Reliability				•	•.	•	6-3
			Availabilit		,01110116	•	•	•	•	6-3
	6.4		TEGORIES	,	•	•	•	•	•	6-4
	0.4		Concept			•	• •	•	•	6 - 4
			Definition		eion Fe	cantis	. / / / \ r =	٠,	•	6-4
		0.4.4	Deliminon	OT MITS	PION EP	SCIILIT	rr (TATE) E	4]	•	J- 1





Section								Page
	6.5 GSE ENVIRO	NMENTS.	•				•	6-4
	6.6 QUALIFICAT	TION FOR M	ISSIO	N ESSE	NTLA	L		
	EQUIPMENT	(MEE) .	•		•			6-6
	6.6.1 Desig					•	•	6-6
	6.6.2 Life 7							6-8
	6.7 QUALIFICAT							
	NONESSENT	IAL EQUIPM	MENT		•			6-11
	6.7.1 Desig							6-11
	6.7.2 Life					•		6-11
	6.8 QUALIFICAT						·	
	TYPE EQUI	PMENT .	•					6-11
	6.8.1 Test		•	•	•	•	•	6-12
7.0	INTEGRATED SYSTEMS	QUALIFICATI	ON					7-1
	7.1 SCOPE .			•	•	•	•	7-1
	7.1.1 Purpo	Se .	•	• •	•	•	•	7-1
	7.1.2 Metho		•	•	•	•	•	7-1
	7.2 FLIGHT/QUA		N ELC	· · ·	· ABT	•	•	7-1
	7. 2. 1 Flight						•	7-2
	7.2.2 Nonfly							7-2
	7.2.3 Flow							7-2
	7.2.4 Sampl			 			•	7-2
	1.2.4 Sampi	e Application	n	• •	•	•	•	1-2
	NOMENCLATURE.		•		•	•	•	8-1
	DEFINITION OF TERMS		•		•	•	•	9-1
	REFERENCES							10-1







ILLUSTRATIONS

Figure		Page
2-1	The Off-Limit Test for Safety Margin	2-7
2-2	The Off-Limit Test for Performance Margin	2-9
2-3	Reliability From Off-Limit Testing	2-10
2-4	Typical Apollo S/C Checkout Profile	2-13
2-5	Apollo LOR Mission Profile	2-15
2-6	Mission Simulation Life Test Profile	2-17
2-7	Service Module Reaction Control System Helium	
	Supply Schematic	2-23
2-8	Reliability Logic Diagram Service Module Reaction	
	Control System Helium Supply	2-24
2-9	Criticality Versus Total Test Time	2-26
3-1	Service Propulsion System Component Schedules	3-3
3-2	C/M RCS Component Schedules	3-4
3-3	S/M RCS Component Schedules	3-5
3-4	LES Component Schedules	3-6
3-5	ELS Component Schedules	3-7
3-6	ECS Schedule Constraints	3-9
3-7	EPS Component Schedules	3-10
3-8	Guidance and Navigation System Component Schedules	3-11
3-9	SCS Component Schedules	3-12
3-10	C&IS Component Schedule	3-13
3-11	LS Component Schedules	3-15
3-12	Thermo Protection System Component Schedules	3 - 16
3-13	Structural Test Schedule	3-17
3-14	Mechanical Systems and Component Schedules	3-19
3-15	Electronic Systems Component Schedules	3-20
4-1	Apollo S/C Prelaunch Environments	4-3
4-2	Apollo LOR Mission Phase Environments	4-5
4-3	Spacecraft Zones, Location and Title	4-11
4-4	Ninety Five- and Ninety Nine- Percent Wind Speed Envelopes.	4-22
4-5	Ninety Nine-Percent Wind Shear Spectrum	4-23
4-6	Ninety Five-Percent Wind Speed, 99-Percent Wind Shear	
	Profiles (Altitudes of Concern, 5 and 12 KM)	4-24
4-7	Ninety Nine-Percent Wind Speed, 99-Percent Wind Shear	
	Profiles (Altitudes of Concern, 12 and 62 KM)	4-25
4-8	Relationship Between Established Gust Characteristics	
	and the Idealized Wind Speed Profile Envelope	4-27
4-9	Design Proof Level	4-38





many Digital

Figure			Page
4-10	Mission Simulation Life Application		. 4-39
5-1	SPS Reliability Assessment Model		. 5-3
5-2	SPS Engine Test Schedule		. 5-5
5-3	SPS Propellant Feed Component (Less Tanks)		
	Qualification Test Schedule		. 5-7
5-4	C/M RCS Reliability Assessment Model		. 5-11
5-5	S/M RCS Module Configuration		. 5-13
5-6	C/M RCS Engine Test Schedule		. 5-16
5-7	C/M RCS Propellant Feed (Less Tanks)		
	Qualification Test Schedule		. 5-17
5-8	S/M RCS Engine Test Schedule		. 5-20
5-9	S/M RCS Propellant Feed (Less Tanks) Qualification		
	Test Schedule		. 5-21
5-10	Test Schedule	•	. 5-23
5-11	LES Tower Jettison Motor Qualification Test Schedule		. 5-25
5-12	Launch Escape Motor Qualification Test Schedule .		. 5-27
5-13	Pitch Control Motor Qualification Test Schedule .		. 5-29
5 - 14	ELS Reliability Assessment Model		. 5-34
5-15	ELS Main Parachute Disconnects Qualification		
		•	. 5-35
5-16	ELS Drogue and Parachute Mortars Qualification		
	Test Schedule	•	. 5-37
5-17	ELS Sequence Controller Qualification Test Schedule		. 5-38
5-18	ELS Parachute Fabric Samples Qualification Test		
	Schedule		. 5-39
5-19	ELS Main Cluster Harness Assembly Qualification		
	Test Schedule		. 5-40
5-20	ELS Reefing Line Cover Qualification Test Schedule		. 5-4]
5-21	ECS Test Oriented Reliability Logic Diagram .		. 5-42
5-22	Cryogenic Reliability Assessment Model		. 5-43
5-23	ECS Qualification Test Schedule		. 5-46
5-24	Cryogenic Subsystem Qualification Test Schedule,		
	Phase A	•	. 5-47
5-25	Cryogenic Subsystem Qualification Test Schedule,		
	Phase B	•	. 5-48
5-26	EPS Reliability Assessment Model (Less Fuel Cell)		. 5-50
5-27	Fuel Cell Reliability Assessment Model	•	. 5-50
5-28	EPS Typical Qualification Test Schedule	•	. 5-52
5-29	EPS Fuel Cells Qualification Test Schedule		. 5-54
5-30	Guidance and Navigation Reliability Assessment Model	•	. 5-56
5-31	Guidance and Navigation Qualification Test Schedule	•	. 5-56
5-32	SCS Reliability Assessment Model	•	. 5-58
5-33	SCS Qualification Test Schedule		. 5-61
5-34	CTU Reliability Assessment Model	•	. 5-64





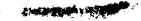


Figure

5-35	Telemetry Assessment Model			5-6
5-36	Near-Earth Assessment Model			5-6
5-37	Deep-Space Assessment Model			5-6
5-38	Recovery Assessment Model			5-65
5-39	Recovery Antenna Assessment Model			5-66
5-40	High-Gain Antenna Assessment Model			5-6
5-41	TV Equipment Qualification Test Schedule		•	5-70
5-42	CTE Qualification Test Schedule		-	5-7
5-43	CDS Qualification Test Schedule (Criticality 2) .			5 - 73
5-44	CDS Qualification Test Schedule (Criticality 3) .		•	5-74
5-45	HF Recovery Qualification Test Schedule			5 - 75
5-46	VHF Recovery Qualification Test Schedule			5-76
5-47	VHF Recovery (Back-Up) Qualification Test Schedule			5-77
5-48	Two-kmc High-Gain Qualification Test Schedule .			5-78
5-49	C-Band Beacon Qualification Test Schedule		•	579
5-50	Life Systems Qualification Test Schedule			5-82
5-51	TPS Reliability Assessment Model			5-83
5-52	TPS Qualification Test Schedule			5-84
5-53	Pressure Cartridge Reliability Assessment Model.		•	5-88
5-54	Reliability Assessment Models Launch Escape Tower			
	Separation System			5-89
5-55	Reliability Assessment Model C/M to S/M Separation		•	3 0 ,
	System			5-91
5-56	Pressure Cartridge Qualification Test Schedule .	•	•	5-93
5-57	Explosive Bolt Qualification Test Schedule		•	5-95
5-58	IFTS Reliability Assessment Model			5-96
5-59	D&C Qualification Test Schedule			5-98
5-60	In-Flight Test System Qualification Test Schedule.	-	•	5-99
6-1	Distribution of Essential and Nonessential Ground	•	•	3-77
	Support Equipment			6-2
6-2	Life Test Application		•	6-10
7-1	Boilerplate Flight/Qualification Flow Chart		•	7-3
7-2	Airframe Flight/Qualification Flow Chart			7-5







TABLES

Table		Page
2-1	Reliability Assessment Data Sources	. 2-3
2-2	Stresses Analyzed in Off-Limit Tests	. 2-8
2-3	Criticality Classification	. 2-25
2-4	Minimum Hardware Per System	. 2-28
4-1	Ground Support Equipment Environments	. 4-7
4-2	Flight Mission Phases	4-12
4-3	Flight Mission Phases, Temperature Environmental	•
	Criteria	. 4-20
4-4	Qualification Test Summary by Test Phase	. 4-32
4-5	Vibration Test Criteria for Design Proof Tests	. 4-40
4-6	Vibration Test Criteria for Design Proof Tests, Max q	. 110
	Abort	. 4-41
4-7	Vibration Test Criteria for Off-Limit Tests	. 4-42
4-8	Vibration Test Criteria for Mission Simulation-Life Tests	
4-9	Acoustic Test Criteria for Design Proof and Mission	. 1-13
•	Simulation-Life Tests	. 4-44
4-10	Assuration May 1 C 14	. 4-45
5-1	CDC Province Demonstrate for Constitution Province	
5-2	SPS Propellant Feed Parameters for Qualification Testing	
5-3	C/M RCS Engine Parameters for Qualification Testing	. 5-9
5-4	C/M RCS Propellant Feed Parameters for Qualification	· 3-7
	•	. 5-14
5-5	Testing	. 5-14
• •		. 5-14
5-6	Testing	. J-14
-	Testing	. 5-15
5-7	LES Rocket Motor Criticality and Hardware Requirements	
5-8	Program for Test Articles, Tower Jettison and Launch	.)-27
	Escape Motors	. 5-31
5 - 9	Program for Test Articles, Pitch Control Motor	. 5-31
5-10	Program for Test Articles, Hot Wire Igniter Cartridge	. 5-32
5 - 11	ELC Demonstrate for O. 1161 - 41 - F.	
5-12	W/CC Demonstrate Con Osselification Mr. 41	
5-13	Cryogenic Subsystem Parameters for Qualification Testing	. 5-44
5 - 14	EDC Demonstrate for O 1100 at the At	
5 - 15	Fuel Cell Parameters for Qualification Testing	
J - 13	ruct deli ratameters for Qualification Testing	. 5-53







Table					Page
5-16	G&N S Parameters for Qualification Testing .				5-55
5-17	System Parameters for Qualification Testing .	•	•	•	5-59
5-18		•	•	•	5-67
5-19	CDS Parameters for Qualification Testing		•	•	5-68
5-20	Antenna Systems Parameters for Qualification Test	ing	•	•	5-69
5-21	Life Systems Parameters for Qualification Testing		•	•	5-81
5-22	TPS Parameters for Qualification Testing	•	•		5-83
5-23	System Parameters for Qualification Testing .		•	•	5-92
5-24	ES Parameters for Qualification Testing		•		5-100
6-1	GSE Qualification Test Environments and Sequence		•		6-5
6-2	Vibration Tests for Items Over 1000 Pounds .			•	6-7

^{*}Information for Tables 7-1 and 7-2 will be supplied for 30 September revision.



C

INTRODUCTION

Volume III of SID 62-109 presents the Apollo ground qualification test plan which was briefly described in Section 3.0 of Volume I. The qualification test plans define the manner in which subcontractors and S&ID will accomplish that testing required to qualify subsystems for inclusion in the Apollo spacecraft and to qualify the associated ground support equipment. The integrated systems qualification test section defines the manner in which that testing required to qualify the total Apollo system for the successive missions will be accomplished.

The Apollo test program conforms with the intent of the definitive contract, NAS9-150, Exhibit I, MIL-R-27542 and NPC-200-2 as modified by the negotiations with NASA during the past year. It reflects the philos-ophy delineated in the Apollo qualification-reliability test plan, SID 62-204, as modified by the reoriented qualification test program approved by NASA during the Big 4 exercise of November 1962 and as delineated in SID 62-1405.

The ground qualification test program has been planned for each subsystem to achieve qualification with minimum hardware testing through the delineation of subcontractor requirements and the integration with S&ID test programs into progressively advancing qualification status. This will permit complete qualification in simulated mission environments while eliminating duplication of testing at various assembly levels. This test plan will utilize design, development and qualification data from all test areas for equipment qualification and reliability assessment. Ground qualification of major subsystems, subassemblies or components peculiar to these subsystems will be done by the subcontractor. Responsibility for ground qualification for combined system compatibility and integration will remain with S&ID. The qualification program for the ground support equipment (Section 6) is being revised to incorporate the requirements of MSC GSE-1A, Apollo Ground Support Equipment General Environmental Criteria and Test Specification, dated 18 October 1963, and will be included in subsequent revisions of this document.







1.0 SCOPE

1.1 PURPOSE

This document establishes the ground qualification test program for Project Apollo spacecraft and its associated GSE. This program's purpose is to prove the design intent and flight worthiness of each subsystem to and beyond specification limits of functional and environmental stresses by ground simulation of critical mission requirements. Programs, schedules, and environmental criteria are delineated for all Apollo spacecraft subsystems and associated ground support equipment. The individual qualification of each subsystem is meticulously planned by clearly defining the scope of each test program, delineating the tests to be performed with the hardware required, and establishing minimum test criteria consistent with equipment criticality. The ground qualification test program culminates in the operational integration of all subsystems as an entity to assure dimensional and functional compatibility.

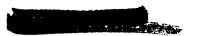
1.2 OBJECTIVE

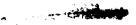
The objective of the ground qualification test plan is to present a program which delineates the philosophy to be employed to verify the capabilities of S&ID designed Apollo spacecraft subsystems and its associated GSE relevant to accomplishing the intended mission. Further, the implementation of this philosophy is presented in as much detail as is possible at this time. Ground qualification will be achieved by demonstration of system capability to perform within specification requirements and that functional performance and quality provisions are repeatable on randomly selected test articles. The program will show a properly oriented step by step qualification plan from one level of assembly to the next, and from one mission phase to the next. Ultimate qualification for the lunar mission is achieved just prior to the launch date. Qualification for each preliminary step in the flight program is achieved just prior to its relevant launch date.

1.3 CONFORMANCE

The ground qualification test plan is submitted as partial fulfillment of the Apollo documentation requirements delineated in NASA contract NAS9-150, Exhibit I, entitled Research and Development for Project Apollo Spacecraft. The test plan conforms to the requirements of the Apollo spacecraft development contract, and has been guided by the provisions of NASA







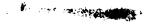
quality publication NPC 200-2, dated 20 April 1962, entitled Quality Assurance Provisions for Space System Contractors; and MIL-R-27542 (USAF), dated 21 May 1963. This volume details the reoriented Apollo qualification test plan as presented to and agreed upon by NASA MSC in November 1962.

1.4 REVISIONS AND AMENDMENTS

This volume will be revised and amended as required to reflect the current status of the qualification test plan of the project Apollo General Test Plan.







2.0 GROUND QUALIFICATION PROGRAM*

2.1 QUALIFICATION PROGRAM LOGIC

The ground qualification program provides an optimum compromise from a statistically rigorous demonstration of all required design parameters to a reasonable program that can be done within development constraints. The program consists of a logical combination of tests designed to verify the elimination of all potential weak points or failure modes and to demonstrate the existence of suitable design margins to environment and time domains.

No attempt is made to demonstrate the reliability of the system or any of its components through conventional techniques. This is an impractical task within the time allotted for the program and reasonable financial limits. The program provides a sound engineering approach toward securing adequate system reliability. This is done by designing a development test program which will explore all of the potential causes of unreliability and eliminate them early in the program. The qualification tests verify that this process has been done, and that the components and systems will work together in the anticipated environments.

The qualification test program is divided into two phases:

Phase A. Design proof tests

Phase B. Mission simulation life tests

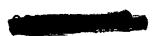
The design proof phase is conducted in two parts. The first part follows procedures specified in MIL-STD-810 except that levels of environments applied are those commensurate with the anticipated maximum level for a typical Apollo mission. Each environment is applied at this maximum level, in sequence and in ascending order of severity to avoid prejudicing a test by a deleterious effect of a prior test. These are applied at the component level to verify that it is able to perform the required function without failure under single worst case conditions.

Design proof tests proceed to the second part of Phase A, where the off-limit test is applied to verify design margin. Both structural and functional design margins are verified here by a stress-to-failure test at the component level. Failure is defined as the inability to perform any required function. Critical failure modes are first determined through the failure mode analysis. The off-limit test verifies the existence of an adequate design

...

^{*}Entire section reissued





margin, thereby, reducing or eliminating conditions that are potentially unreliable. These tests are essential to the Apollo reliability program.

Phase B of the qualification test program consists of the mission simulation life test. It demonstrates system characteristics, but particularly, life under simulated mission conditions. This test includes the application of combined environments as facilities permit and provides the following essential data regarding the system performance as it affects reliability.

Component compatibility
Combined environment compatibility
Life characteristics
Repeatability

Through the application of the combined environments in the sequence and at the normalized levels anticipated for an actual mission, a comprehensive demonstration of the system capability is attained.

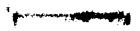
2.2 RELIABILITY ASSESSMENT LOGIC

The Apollo test program does not have as one of its requirements or for that matter an objective, the demonstration of the ultimate reliability of Apollo to any reasonable confidence level. From the beginning of the program, it was evident that this would be a task outside the time available and the milestones imposed on the program. It has been necessary to depart from the normally accepted practice of demonstrating reliability in a statistically rigorous manner. For Apollo, S&ID has adopted a new concept of reliability assurance where calculating and/or predicting failure rates of equipments from tests designed to accumulate operating time only becomes a secondary objective.

The Apollo qualification program does not yield the necessary data to show the over-all program reliability objectives to a satisfactory degree of confidence. A base line of reference must, therefore, be established in order to make an assessment of reliability at any given time. This base must apply to each separate functional area in order to estimate the potential reliability of a given function. For example, the group of components involved in providing the deep space communications (S-band equipment) may be considered a separate function and should be assessed independently of all other functions. Intelligent assessment below this level is impractical because of the low probability of a failure occurring. To describe this probability the expression mean- (or average) time-to-failure (MTTF) is an applicable term for Apollo. Since this must be related to the reliability objective associated with mission success, i.e., 0.96, it can only be done by applying it







at the functional level, such as deep space communications, propulsion, dc power, etc. In most cases this is below the subsystem level. This will establish the base line of an 8400 hours mean-time-to-failure for the group of components making up a function. This applies where no redundancy exists exclusive of the grouping. With the base line established, it is now possible to state the ramifications relevant to the assessment of reliability within the qualification program.

The assessment of the reliability of the Apollo will be done without additional test time or equipment. The reliability assessment program will be based on the use of attribute data from all phases of the testing activity incorporating data generated from the moment of design freeze to the moment before the final launch. Table 2-1 shows the data sources to be used in deriving an assessment and the percentage of data considered applicable from each source. When data becomes available from one of these areas, an assessment will be made (based on that data) and will be related to the 0.96 as applied to the function and to the spacecraft level. No confidence level will be given until late in the program when this may become possible.

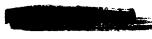
Source	Percent of Data Applicable for Reliability Assessment	Percent of Required Reliability Data Supplied
Development	10	5
Design proof	80	25
Mission life	100	40
Acceptance	40	5
Boilerplates	30	5
Spacecrafts	80	20

Table 2-1. Reliability Assessment Data Sources

2.3 SUBSYSTEM QUALIFICATION PHASES - SPACECRAFT

2.3.1 Design Proof for Apollo

The Apollo design proof tests (DPT) are environmental tests conducted in sequence and at the maximum levels anticipated for a given environment



1.5 g^2/cps the DPT level may be 1.33 g^2/cps .



anywhere and/or at anytime during a normal or abnormal mission if it is within the design criteria. Abnormal may be considered a situation such as max q abort where crew safety is essential and subsystem integrity a secondary consideration. The test safety margin used in these tests is about 1.33 times the level anticipated in more than 90 percent of the possible situations. The test safety margin is defined as a test level somewhat above the normally anticipated level for a given environment, but below the designer's margin. For example, if the normally anticipated vibration level for a given component was 1 g²/cps and the component was designed to withstand only

The primary purpose of a test safety margin is to assure that the distribution of parameter measurements has been encompassed in the test level of each anticipated environment. A secondary purpose is to include test equipment operating tolerances. The value of 1.33 times the anticipated level has been established to cover the multiplying effects of both variables and to provide simultaneously a reliability factor of approximately 10 percent.

The design proof tests are conducted in a MIL-STD-810 manner for all spacecraft equipment except that the levels imposed are those applicable to the Apollo mission. (See Section 4.0.) There are two exceptions which are applied to Apollo: the explosion proof and the electromagnetic interference tests. The explosion proof test is applied to all components of the command module interior and is designed to simulate the oxygen atmosphere. Propellant vapors are imposed on the remaining components, but only when necessary. The electromagnetic interference tests are designed according to S&ID specification MC 999-0002B.

One additional constraint imposed on the qualification test program is the special handling restriction applied to Apollo during the Big 4 exercise. This allowed spacecraft and associated equipment to receive any special handling needed to properly move, operate and preclude the detrimental effects of these actions and the associated weather. The test program takes advantage of this wherever possible, reducing the test requirements in those areas where the anticipated prelaunch environment was more stringent than the post launch counterpart. Typical of these environments are humidity, which is now only a requirement for some service module components, and shock, which is very light for equipment that need not work after reentry.

The program is based on the assumption that no failures will be encountered during the qualification tests apart from the off-limit tests. This is an optimistic point of view, but it does serve as a base line for the program. Any contingencies will change the nature and complexity of the qualification program relevant to the particular component involved. This approach concentrates the effort where it is needed, but also raises the requirement for a quick reaction capability when the contingency does arise.





The design proof tests will consist of, and be limited to the following applied environments, in sequence, at the levels delineated in Section 5 under specific subsystems:

2.3.1.1 Command Module and Associated Equipment

Vibration
Acceleration
Temperature extremes
Acoustics
Shock (two levels and types)
Vacuum
Electromagnetic interference
Explosion (O₂ atmosphere)

2.3.1.2 Service Module and Associated Equipment

All of 2.3.1.1 except oxygen Humidity Salt fog Sand and dust

Minor exceptions to this criteria are applied to those items on the exterior such as umbilicals. The specific levels of environments applied are in Section 4.

2,3,2 The Off-Limit Test

2.3.2.1 Application

The off-limit test is considered a part of the design proof phase, but successful demonstration of a given design margin is not held as a contingency for qualification of any component under test. The tests will determine the design margin relevant to any critical failure mode. The intent is to verify that there are no cumulative tolerance situations which the tests indicate may contribute to unreliability.

2.3.2.2 Characteristics of the Off-Limit Test

The off-limit test determines design margins and further enables the engineer to predict the potential reliability of a given characteristic or component. There are two distinctly different types of Apollo off-limit tests and they are associated with verifying either stress or performance margins. The first may involve stress to destruction. The tests are accomplished by determining the stress-strength margin related to each characteristic or failure mode and then algebraically summing them up. Some of this work







will be done during the development program on the lower levels of assembly but there is a definite need to verify the results and to examine the effects of interfaces during qualification.

2.3.2.2.1 Off Limit Tests for Safety Margins. Figure 2-1 shows typical off-limit tests on a rocket motor. Two of the possible failure modes are analyzed by stressing the test sample to failure (see Part A, Figure 2.1). The case is pressurized to burst point, and the nozzles are operated until burn through occurs. If one of these conditions were depicted graphically and the test were conducted many times, the results would be much like Part B, Figure 2-1. The test should be conducted on ten or more samples for reasonable accuracy.

To satisfactorily analyze the failure mode, as the plot indicates, the characteristics of the stress, in this case pressure, though it could be any environment, and that of the strengths of all the components to be utilized must be known. In most cases the stress can be determined within fairly close tolerances. Knowing the accurate stress, the probability of a failure relevant to that stress is a function of the safety margin and the distribution of strengths associated with the stress. Since establishing an adequate design margin is not the complete answer, the verification of its magnitude and the assurance of a restricted distribution around the mean is also essential. In theory, it is possible to determine the safety or design margins, with a very few samples when distribution of strengths approaches a single value.

Since many samples at the subsystem level are impractical in Apollo, strict control measures must be used to limit the possibility of critical parameter variation to within very close tolerances. This is done during the design phase by careful design analysis at all assembly levels. Distribution control is further augmented by employing 100 percent screening of parts and material through the use of destructive and non-destructive testing techniques. For additional data see SID 62-109, Volume IV, Acceptance Test Plan.

If the parameter variations are held to close tolerances, and a reasonable safety margin exists between the expected stress and the known strength, then the predictable reliability of the unit is very high. In fact, it should be so high as to make it impractical to assess its integrity in terms of the usual mean time between failure because wearout would occur in most items long before encountering a mission degrading failure.

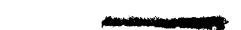
2.3.2.2 Off-Limit Tests of a Function. The function off-limit test works in much the same manner as that used for determining margins of safety. (See Figure 2-2 where the rocket engine is being operated in a test stand.) This test determines the thrust impulse characteristic or operating

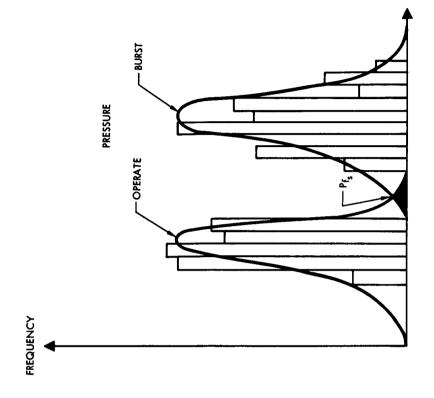






STRESS





STRESS MARGIN

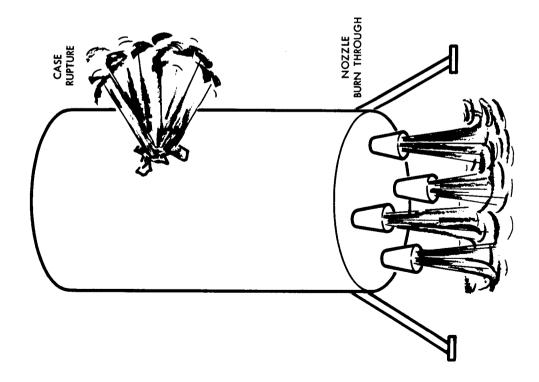


Figure 2-1. The Off-Limit Test for Safety Margin





limits of the engine. A plot of the characteristic is made after many firings. The performance margin is the difference between what is considered minimum acceptable and the mean of the distribution. This test is especially suitable for electrical and electronic equipment where performance variations must be expected, and be mutually tolerable within functions and subsystems.

2.3.2.2.3 The Off-Limit Test for Electronic Equipment. The off-limit test as applied to electronic equipment, is basically a functional off-limit test where design margins relative to line and input voltage variations are extremely important. If part parameters are held to close tolerances and a reasonable design margin is found during the off-limit test, component reliability will be very high, and impossible to predict by normal means. If malfunctions do occur they would probably be caused by a parameter strength distribution drifting toward the stress value (see Figure 2-3). Regardless of this, the actual probability of a failure is a function of the design margin which must be verified by tests.

2.3.2.3 Characteristics Examined by Off-Limit Testing

The exact characteristics to be tested for by off-limit stressing or test to destruction is a function of the failure-mode analysis which will be performed on every component used in the Apollo. The more critical modes will be analyzed by the off-limit techniques. Some characteristics to be explored during these tests are given in Table 2-2.

Table 2-2. Stresses Analyzed in Off-Limit Tests

Electronic Devices	Mechanical Devices
Temperature	Flow
Input Signal	Pressure Regulation
Supply Voltage and Power	Voltage Regulation
Vibration	Burst Pressure
Acceleration	Engine Thrust Chamber Burn- Through
Acoustics	Temperature





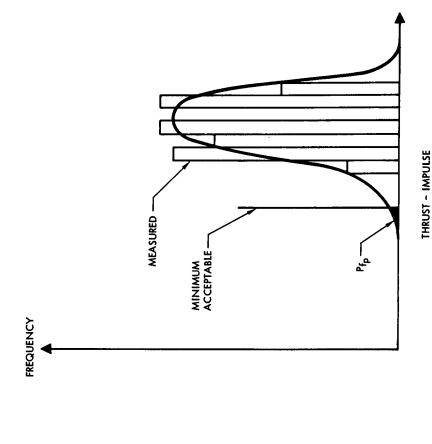
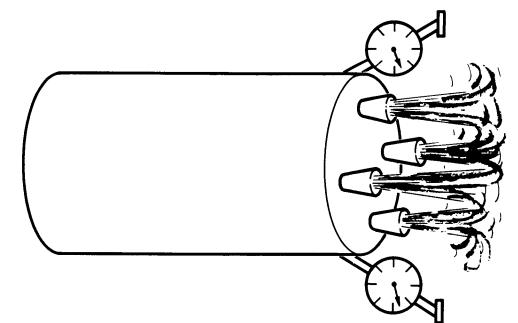


Figure 2-2. The Off-Limit Test for Performance Margin



PERFORMANCE MARGIN-THRUST

PERFORMANCE



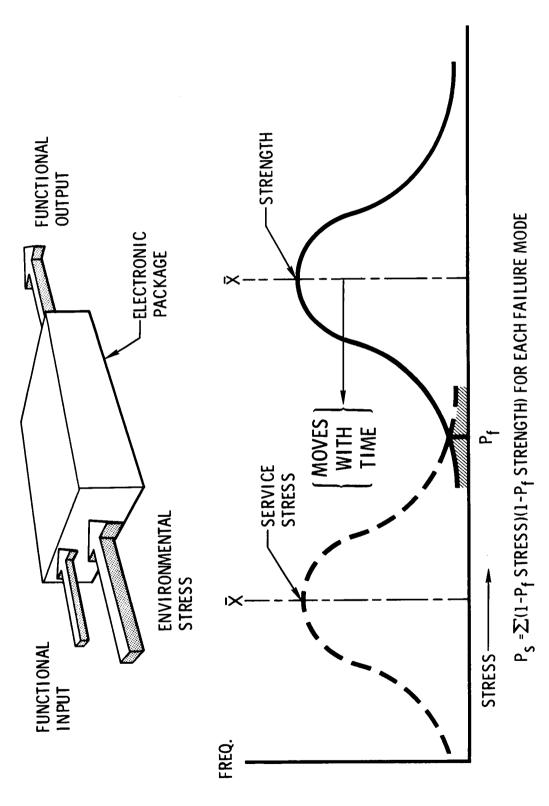
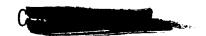


Figure 2-3. Reliability From Off-Limit Testing







2.3.3 The Mission Simulation Life Test

2.3.3.1 Concept

The Apollo mission simulation life test simulates the normalized value of expected environments and the operational duty cycle for all phases of operation from the first checkout through recovery. The tests are to be conducted at subsystem or functional levels to insure that there are no component interface problems. They will include a natural combination of environments wherever practical, that is, where facilities and schedules permit.

Figures 2-4 and 2-5 depict the types of combined environments that may be expected relative to any given phase of the mission. Those pertinent to a mission simulation life test are:

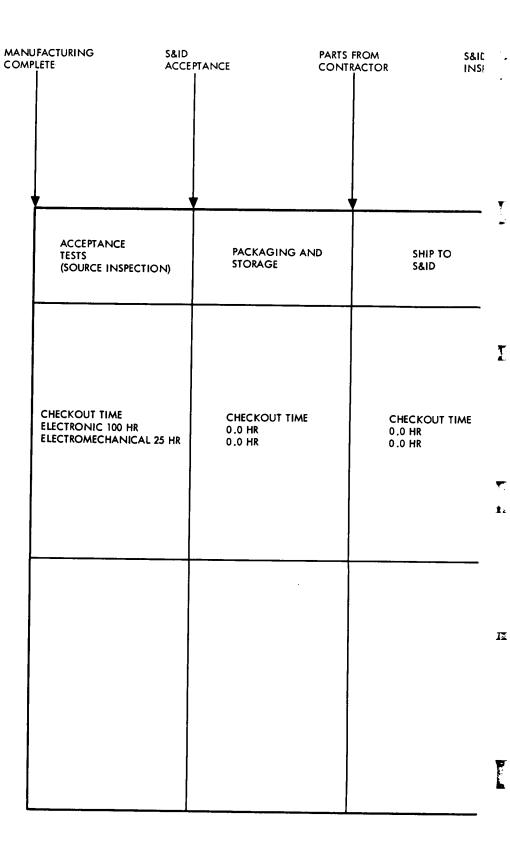
Vacuum - Vibration Acceleration - Vibration Temperature - Vacuum

These may be produced in existing facilities, however, there are some weight and size limitations which may modify test planning.

Combined environmental tests of more than two environments will seldom serve a purpose for Apollo equipment that the combined environmental tests listed above cannot fulfill. Environmental tests conducted simultaneously with three or more Apollo environments increase test costs to a point that the need for and the usefulness of the derived data must be weighed against the test costs. Equipment that will operate in a combined environment of vacuum, vibration, and temperature and the exposure of which could be critical to the operation of the equipment will be so tested. Such tests will be designated in the specific test plans of Section 5.

The mission cycle (See Figure 2-6) is composed of two phases. One simulates activities during the prelaunch operations; that is from the time a unit completes fabrication until launch is initiated. The second phase simulates the post-launch period to and including the recovery operation. For the prelaunch phase all of the different testing and handling operations are simulated, including environments which are not compensated for by special handling, and the total aggregate test time anticipated for this phase. The post launch or in-flight time is simulated as closely as possible by the use of combined environmental facilities and the operation of the system in a manner which closely simulates the actual mission duty cycle.

For minimum-type systems, two complete mission simulations will be accomplished for qualification. Where more than one system is designated



Ţ

		. .		RECEIVING T ECTION AND TEST P	EST REPARATION	
Division of			₹77 1. 2.	STORAGE	INSTALLATION 7.6 WK	INDIVIDUAL SYSTEMS
T	V.T.	हुनक ⁻¹ क्रम	• • • • • • • • • • • • • • • • • • •	-	7.6 WK	7.0 WK
. 4 3	₩~ 1 4 ±	я ч А.	₽ **	CHECKOUT TIME 0.0 HR 0.0 HR	CHECKOUT TIME 0.0 HR 0.0 HR	CHECKOUT TIME 3 WEEKS OF TEST 5 DAYS/WK 4 HR/DAY TOTAL TIME 60 HR
Ľ	Ľ.	X T	Ε			
₹ ₹			↓ •			

		SHIP TO	O AMR	
				1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
;	;	INTEGRATED SYSTEMS CHECKOUT 6.4 WK	INSPECTION AND MODIFICATION 2.4 WK	INDIVIDUAL SYSTER CHECKOUT 3.4 WK
		CHECKOUT TIME 3 WEEKS OF TEST 5 DAYS/WK 4 HR/DAY TOTAL TIME 60 HR	CHECKOUT TIME 0.0 HR 0.0 HR	CHECKOUT TIME 3 WEEKS OF TEST 5 DAYS/WK 4 HR/DAY TOTAL TIME 60 HR
				1.2
				Œ

I

NORTH AMERICAN AVIATION

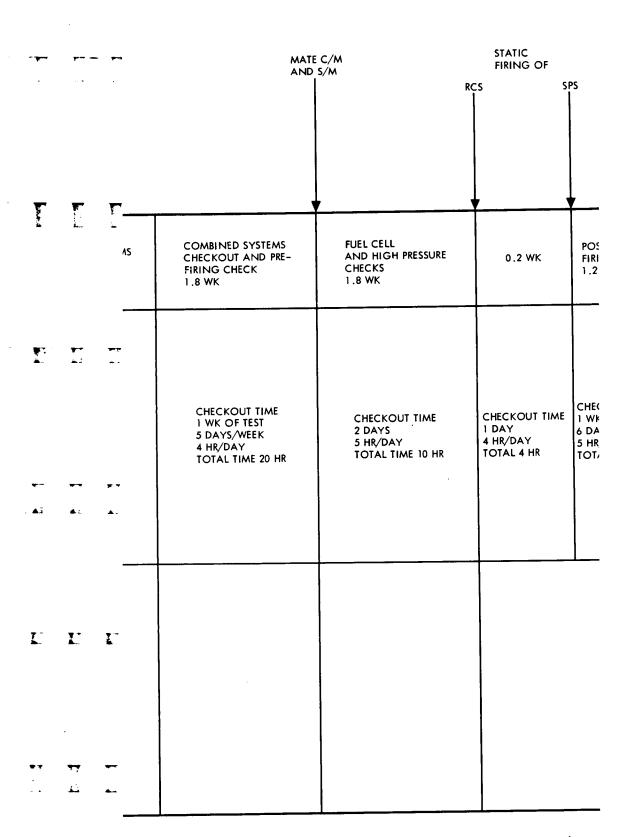


Figure 2-4.

MOV VACI CHA		MOVE TO LAUNCH AREA	
IT STATIC NG CHECKS WK	VACUUM CHAMBER CHECKS 1.4 WK	INTEGRATED SY CHECKOUT-CO AND LAUNCH 7.0 WK	
CKOUT TIME (.YS/WK /DAY AL TIME 30 HR	CHECKOUT TIME FUEL CELL 1 DAY 10 HR/DAY TOTAL TIME 10 HR ECS 2 DAYS 5 HR/DAY TOTAL TIME 10 HR SUIT CHECK 2 DAYS 5 HR/DAY TOTAL TIME 10 HR	CHECKOUT 5.5 WK 6 DAYS/WI 5 HR/DAY TOTAL TIM	<

Cypical Apollo S/C Checkout Profile



0 LAUNG	0.042 JETTIS CH LET	
		¥
	BOOST TO 100,000 FEET AND LET JETTISON	2ND STAGE BOOST 0.098
ENVIRONMENTAL CONTROL SYSTEM	OPERATING ON FREON UP TO 100,000 FT	OPERATING ON WATER BOILER
FUEL CELL SYSTEM	HYDROGEN VENT FOR COOLING UP TO 100,000 FT	HYDROGEN VENT FOR COOLING UP TO 100,000 FT
COMMUNICATIONS SYSTEM C-BAND	SYSTEM ON FROM BOOST TO TRANSLUNAR COAST	SYSTEM ON FROM BOOST TO TRANSLUNAR COAST
TRANS PONDER DSIF TRANSPONDER	SYSTEM ON FROM BOOST TO TRANSLUNAR COAST	SYSTEM OFF FROM BOOST TO TRANSLUNAR COAST
VHF RECOVERY BEACON		SYSTEM OFF FROM BOOST TO ENTRY PHASE DSES ONLY. TIME LINE REVISI
	*FOR ILLUSTRATION PORTS	,525 O. 12 17 18

-	*				
		HORBIT CTION 4.1	700 4.	780 5. d	8 8
-	¥_,		1313		
		EARTH ORBIT STAY 4.500	TRANSLUNAR INJECTION 0.080	LEM TRANSFER 0.870	TRANSLUNAR COAST AND MIDCOURSE CORRECTIONS 76. 130
	P	OPERATION ON BOTH RADIATORS AND BOILERS EXCEPT DURING THE NIGHT AND/OR DARK SIDE AT WHICH TIME HEATING IS ACCOMPLISHED BY GLYCOL AND ELECTRONIC LOAD	OPERATING ON SPACE RADIATORS	OPERATION ON BOTH RADIATORS AND BOILERS EXCEPT DURING THE NIGHT AND/OR DARK SIDE AT WHICH TIME HEATING IS ACCOMPLISHED BY GLYCOL AND ELECTRONIC LOAD	OPERATION ON BOTH RADIATORS AND BOILERS EXCEPT DURING THE NIGHT AND/OR DARK SIDE AT WHICH TIME HEATING IS ACCOMPLISHED BY GLYCOL AND ELECTRONIC LOAD
• · · A ä		OPERATION NORMAL WATER GLYCOL FOR COOLING	OPERATION NORMAL WATER GLYCOL FOR COOLING	OPERATION NORMAL WATER GLYCOL FOR COOLING	OPERATION NORMAL WATER GLYCOL FOR COOLING
		SYSTEM ON FROM BOOST TO TRANSLUNAR COAST	SYSTEM ON FROM BOOST TO TRANSLUNAR COAST	SYSTEM ON FROM BOOST TO TRANSLUNAR COAST	SYSTEM OFF DURING THIS PERIOD
L	1	SYSTEM OFF FROM BOOST TO TRANSLUNAR COAST	SYSTEM OFF FROM BOOST TO TRANSLUNAR COAST	SYSTEM OFF FROM BOOST TO TRANSLUNAR COAST	SYSTEM ON DURING THIS PERIOD
₩ ₩		SYSTEM OFF FROM BOOST TO ENTRY PHASE	SYSTEM OFF FROM BOOST TO ENTRY PHASE	SYSTEM OFF FROM BOOST TO ENTRY PHASE	SYSTEM OFF FROM BOOST TO ENTRY PHASE
					

1.780 89	123.700 EQUAL P	MISSION 129. PERIOD LAND	
LUNAR ORBIT INJECTION 0.090	LUNAR ORBIT COAST 41.830	EQUAL PERIOD ORBIT STAY, HOVER & TOUCHDOWN 6.290	LUNAR SUR- FACE STAY 32.000
OPERATION ON BOTH RADIATORS AND BOILERS EXCEPT DURING THE NIGHT AND/OR DARK SIDE AT WHICH TIME HEATING IS ACCOMPLISHED BY GLYCOL AND ELECTRONIC LOAD	AND/OR DARK SIDE AT WHICH TIME HEATING IS	OPERATION ON BOTH RADIATORS AND BOILERS EXCEPT DURING THE NIGHT AND/OR DARK SIDE AT WHICH TIME HEATING IS ACCOMPLISHED BY GLYCOL AND ELECTRONIC LOAD	OPERATION ON BOTH RADIATORS AND BOILERS EXCEPT DURING THE NIGH: AND/OR DARK SIDE AT WHICH TIME HEATING IS ACCOMPLISHED BY GLYCO AND ELECTRONIC LOAD
OPERATION NORMAL	OPERATION NORMAL	OPERATION NORMAL	OPERATION NORMAL WATER GLYCOL FOR COOLING
WATER GLYCOL FOR	WATER GLYCOL FOR	WATER GLYCOL FOR	
COOLING	COOLING	COOLING	
SYSTEM OFF DURING	SYSTEM OFF DURING	SYSTEM OFF DURING	SYSTEM OFF DURING
THIS PERIOD	THIS PERIOD	THIS PERIOD	THIS PERICO
SYSTEM ON DURING	SYSTEM ON DURING	SYSTEM ON DURING	SYSTEM ON DURING THIS PERIOD
THIS PERIOD	THIS PERIOD	THIS PERIOD	
SYSTEM OFF FROM	SYSTEM OFF FROM	SYSTEM OFF FROM	SYSTEM OFF FROM
BOOST TO ENTRY	BOOST TO ENTRY	BOOST TO ENTRY	BOOST TO ENTRY
PHASE	PHASE	PHASE	PHASE

		:M			730 25 	50.090
T						
			LEM ASCENT 1.040	APOLLO-LEM RENDEZVOUS & DOCKING 7.700	LUNAR ORBIT COAST & NAVIGATION 79.360	TRANSEARTH INJECTION 0.040
**	¥* æ.i		OPERATION ON BOTH RADIATORS AND BOILERS EXCEPT DURING THE NIGHT AND/OR DARK SIDE AT WHICH TIME HEATING IS ACCOMPLISHED BY GLYCOL AND ELECTRONIC LOAD	OPERATION ON BOTH RADIATORS AND BOILERS EXCEPT DURING THE NIGHT AND/OR DARK SIDE AT WHICH TIME HEATING IS ACCOMPLISHED BY GLYCOL AND ELECTRONIC LOAD	OPERATION ON BOTH RADIATORS AND BOILERS EXCEPT DURING THE NIGHT AND/OR DARK SIDE AT WHICH TIME HEATING IS ACCOMPLISHED BY GLYCOL AND ELECTRONIC LOAD	OPERATING ON SPACE RADIATORS
▼ . A ä		1	OPERATION NORMAL WATER GLYCOL FOR COOLING	OPERATION NORMAL WATER GLYCOL FOR COOLING	OPERATION NORMAL WATER GLYCOL FOR COOLING	OPERATION NORMAL WATER GLYCOL FOR COOLING
			SYSTEM OFF DURING THIS PERIOD	SYSTEM OFF DURING THIS PERIOD	SYSTEM OFF DURING THIS PERIOD	SYSTEM OFF DURING THIS PERIOD
Ľ	X.		SYSTEM ON DURING THIS PERIOD	SYSTEM ON DURING THIS PERIOD	SYSTEM ON DURING THIS PERIOD	SYSTEM ON DURING THIS PERIOD
₹ ₹			SYSTEM OFF FROM BOOST TO ENTRY PHASE	SYSTEM OFF FROM BOOST TO ENTRY PHASE	SYSTEM OFF FROM BOOST TO ENTRY PHASE	SYSTEM OFF FROM BOOST TO ENTRY PHASE

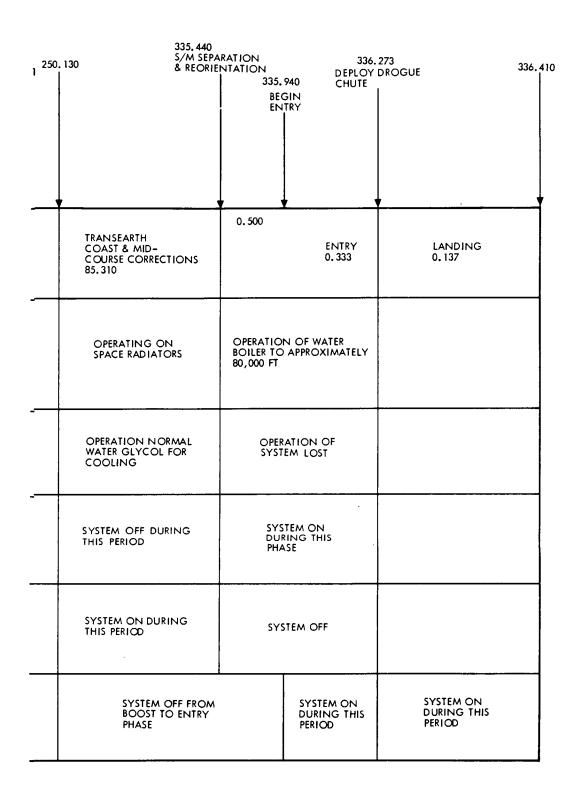
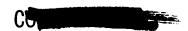
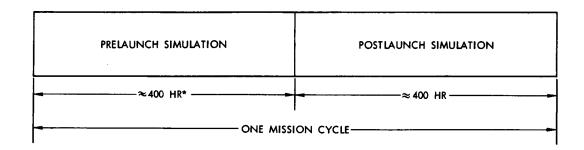


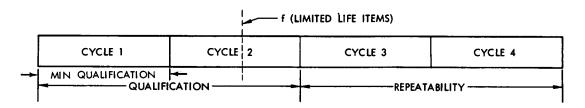
Figure 2-5. Apollo LOR Mission Profile







* PRELAUNCH TIME WILL VARY WITH SUBSYSTEM



QUALIFICATION PROGRAM

Figure 2-6. Mission Simulation Life Test Profile







for qualification, up to two mission simulations will be utilized to satisfy this requirement. Where additional repeatability data are required, more mission simulation cycles will be performed.

The number of subsystems to be subjected to the mission simulation life test was determined a function of the criticality of the component function relevant to the intended mission and crew safety. The number of components required to support the systems in mission life tests were based on the expected life of the component. Therefore when any component within a given subsystem would reach its life limit before completing the test, a replacement was planned to assure four full test cycles.

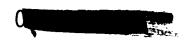
2.3.3.2 The Requirement

The number of systems required to qualify a system under the mission simulation life test concept was determined to be a function of its criticality to the system and its anticipated duty cycle. Criticality is defined as a numerical index which relates the contribution of a given system to mission success and crew survival with all the other Apollo systems contributions. It is an approach toward equalizing the risk in testing and insures test emphasis in the more critical areas, but in proper relation to its contribution. The concept of criticality is covered in paragraph 2.4 of this volume. Its application to a specific subsystem is covered in the paragraph on the relevant subsystem in Section 5. In order to understand the application at this point, it is sufficient to state that the higher the criticality indices and the higher the duty cycle, the more tests are required to qualify the system. Much of the data required to complete the mission-life test analysis will be derived from attribute data obtained from other phases of the Apollo test program. It was necessary to use this data because of the magnitude of data required to qualify Apollo for the lunar flight.

2.3.3.3 Accumulated Operating Hours

The operating hours accumulated on a system from its fabrication to recovery were synthesized by considering every phase of component life. A mission profile was prepared depicting the prior-to-launch phases (see Figure 2-4) and the post launch phases (see Figure 2-5). These figures were used to derive the individual subsystems or function operating time for prelaunch and duty cycle for post-launch. The total operating time to be imposed during each mission life cycle on a given subsystem is the sum of both. total for any given subsystem will be different and is given in the relevant paragraph of Section 5. Some typical examples are shown on the profiles. The environments expected in each phase and to be applied during the tests are covered in detail in Section 4.0.







2.3.3.4 Attribute Hours

The attribute hours used to reduce the over-all tests required to assure the mission life capability are derived in much the same manner as those used for the assessment of reliability. Table 2-1 may be used to determine the percentage of useful data obtained from these sources. This alone does not provide the necessary data to accomplish qualification to the mission life requirements, because there is still doubt concerning the validity and applicability of the data sources. It was also necessary to establish a minimum program for the mission life tests. In the minimum program, strict control could be exercised and a base of reference established to compare with other data to assure validity. The minimum mission life test is given in paragraph 2.5.

2.4 THE CONCEPT OF CRITICALITY

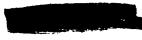
2.4.1 Logic

The logic employed to derive numerical values for criticality and the functional relationship between criticality and test time is predicated on the following facts:

- a. Product integrity, as measured by mean-time-between-failures (MTBF), is improved as the amount of experience acquired from testing is increased, i.e., MTBF is some function of test time and is equivalent to the ratio of operating time to failures experienced.
- b. More testing is required on systems of higher criticality than on those of lesser criticality.
- c. More tests are required on systems that cannot be improved through analytical techniques.
- d. Criticality is a function of the relative orders of redundancy, alternate modes of operation, and spares incorporated in a given subsystem design, i.e., test time on subsystems composed mainly of series components must be greater than that employed on subsystems with parallel components, spares, and/or alternate modes of operation.

The foregoing suffices to reduce the risk that high criticality or series components will contribute to loss of the crew or failure to accomplish the mission. In fact, the trend at the ultimate state is such that there is no greater risk on critical items than there is on hardware of lesser criticality, i.e., equalization of or constant risk is the aim of the test program outlined herein.







CONTRACT OF

2.4.2 Derivation

2.4.2.1 The Indices

The criticality indices were derived on the basis of equalizing risk. Risk can be defined as crew or system losses per mission. Mathematically it can be expressed as:

$$Risk = \frac{crew \text{ or system losses}}{component \text{ failure}} \times \frac{component \text{ failures}}{mission}$$
 (1)

The first term of this expression, crew or system losses/component failure, defines the criticality of the component with respect to its influence on crew survival or success of the spacecraft. The second term, component failures/mission, is inversely proportional to the MTBF. Introducing these relationships into (1) results in the following equation:

Risk = Criticality
$$\times \frac{C}{MTBF}$$
 (2)

where

C = A proportionality constant

From the functional relationship between MTBF and test time (reference Paragraph 2.4.1a).

Risk = Criticality
$$\times \frac{C}{f(\text{test time})}$$
 (3)

For a constant risk, C divided by the constant risk results in a new constant which can be symbolized by C'. Equation (3) then reduces to:

Test time =
$$C' \times f$$
 (criticality) (4)

Before equation 4 can be translated into practical terms, the criticality equation must be derived. Repeating the previous definition:

$$Criticality = \frac{crew \text{ or system losses}}{component \text{ failure}}$$
 (5)

Equation (5) may be modified to express design criticality, which is defined as the probability of crew losses because of component failure, or the number of crew losses per mission because of the unreliability of a component. Stated explicitly, design criticality is proportional to the change in crew safety or system reliability with respect to the change in component reliability due to the amount of component unreliability. This statement may be expressed mathematically as follows:

Design criticality =
$$\frac{\partial R_{cs}}{\partial R_{comp}} \times (1 - R_{comp})$$
 (5a)









Total State of the last

Test criticality is defined as the rate of change of crew safety or system reliability with respect to the change of component reliability, i.e., the effect of component unreliability on crew or system loss. Mathematically stated:

Test criticality =
$$\frac{\partial_{\cdot} R_{cs}}{\partial_{\cdot} R_{comp}}$$
 (5b)

Test criticality is a measure of the amount of increase in crew safety or system reliability to be gained by a change in component reliability. The component that will give the largest crew safety or system reliability increase should be tested the most, i.e., its reliability determined more carefully. In effect, this will concentrate test effort in the areas that will minimize crew loss or system unreliability. This concept will be applied to the test program to determine the systems and components with unit change of reliability that has greatest effect on crew safety or mission reliability and classes of criticality established for them.

Equation 5 can be written in terms of partial derivatives of probabilities of failure, as follows:

Criticality =
$$\frac{\partial P}{\partial P}_{component failure}$$

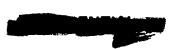
= $\frac{\partial P}{\partial P}_{component failure}$ x $\frac{\partial P}{\partial P}_{component failure}$ (6)

But, failure = l-success, and $\partial P_{failure} = -\partial P_{success}$; wherein the probability of success is equal to reliability R, and equation 6 can be restated in the form:

Criticality =
$$\frac{\partial P_{\text{crew survival or mission success}}}{\partial R_{\text{module}}} \times \frac{\partial R_{\text{module}}}{\partial R_{\text{component}}}$$
(7)

The latter permits a numerical evaluation of the effect of component reliability on mission success or crew survival. Criticality is, therefore, the rate of change of spacecraft reliability or crew safety with respect to the reliability of any component.





in a conservação

2.4.2.2 Sample System

As an example of the application of equation 7, consider the helium supply within the service module reaction control system. A schematic of one of four modules within the spacecraft is shown in Figure 2-7. From the referenced schematic, the reliability logic diagram of Figure 2-8 may be synthesized. With the four module quad concept employed in the design of the reaction control system, mission success is assured if any three of the four modules function satisfactorily. Crew survival is assured if any two of the four modules are functioning. These criteria can be translated into an equation for probability of crew survival, which is equal to the sum of the probabilities of four, three and two modules operating, or for $R_{\rm M}$ = module reliability:

$$P_{\text{crew survival}} = R_{\text{m}}^4 + 4R_{\text{m}}^3 (1-R_{\text{m}}) + 6R_{\text{m}}^2 (1-R_{\text{m}})^2$$
. (8)

The partial derivative of the probability of crew survival with respect to the reliability of the module is given by

$$\frac{\partial P_{\text{crew survival}}}{\partial R_{\text{m}}} = 12R_{\text{m}}^{3} - 24R_{\text{m}}^{2} + 12R_{\text{m}}$$
 (9)

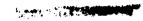
Equation 9 represents the criticality of the module with respect to the spacecraft. When the reliability of the module $(R_m = 0.987)$ is substituted in equation 9, the following is computed:

$$\frac{\partial P_{\text{crew survival}}}{\partial R} = 0.00207 \tag{10}$$

Similarly, when the criticality of the crew operated helium valve with respect to the module is calculated, employing a valve reliability of 0.999989:

$$\frac{\partial R_{m}}{\partial R_{He \text{ solenoid valve}}} = 0.00193$$
 (11)

The criticality of the crew-operated solenoid valve with respect to the spacecraft is, therefore, the product of the results of 10 and 11, or:



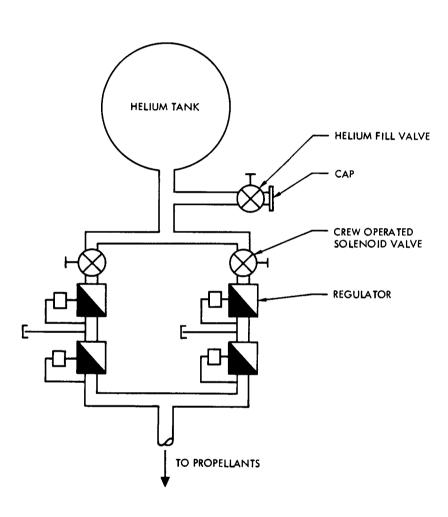
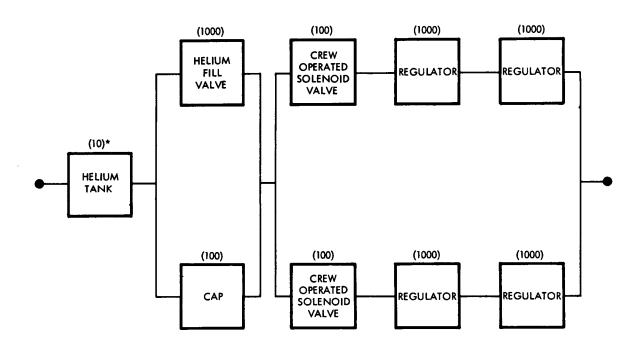


Figure 2-7. Service Module Reaction Control System Helium Supply Schematic (One of Four Modules)







*PARENTHETIC NUMBERS ARE FAILURES PER 10⁶ MISSIONS

Figure 2-8. Reliability Logic Diagram Service Module Reaction Control System Helium Supply





2.4.3 Application

2.4.3.1 Classification

Upon calculating the criticalities of the major components of the space-craft, it was observed that the numerical values could be grouped into three basic order-of-magnitude classes, with a gross simplification in determining the functional relationship between test time and criticality, as expressed in equation 4. Additional justification for grouping criticalities was found in the fact that items with similar order-of-magnitude values not only contained similar degrees of redundancy, alternate modes, etc., but also were responsible for similar ramifications in crew survival or mission success. The criticality was grouped into the classes as shown in Table 2-3 with definitions and classifications.

Class	Index Range	Possible Effect on Mission	Functional Relation
1	0.8 to 1.0	Impair crew survival (catastrophic)	No redundancy
2	0.01 to 0.08	Impair mission success or safe abort	Dual redundancy
3	Less than 0.008	Maintenance problem or nuisance	Triple redundancy of some form or non-essential equipment

Table 2-3. Criticality Classification

2.4.3.2 Application to Test Time

The transition from the criticality classification to the choice of an optimum test time must be based on sound engineering practice and program constraints. With this and the bare minimum program of paragraph 2.5 as the objectives, the plan depicted in Figure 2-9 was devised.

The plan presented closely conforms to the AGREE ¹, task group 3 definitions for absolute minimum test time. The AGREE report recommends that the minimum test time be equal to or greater than three times the required MTBF in order to:

Reliability of Military Electronic Equipment. The Advisory Group on Reliability Electronic Equipment Office of the Assistant Secretary of Defense (Research and Engineering) June 1957.









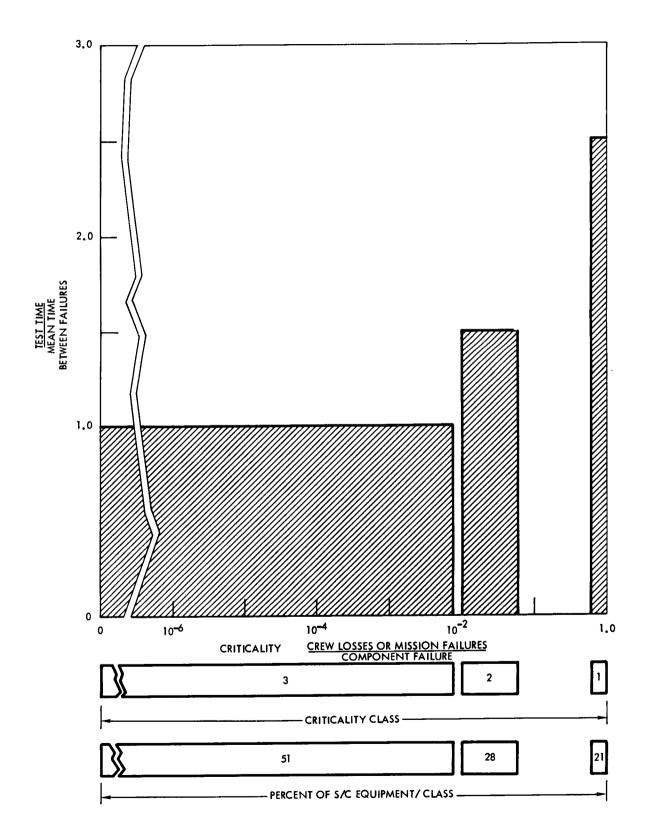
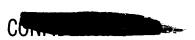
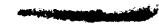


Figure 2-9. Criticality Versus Total Test Time







- 1. Provide additional data in case of dispute
- 2. Provide information for corrective action in case equipment is rejected

This level is also subscribed to by industry as a whole and is made a requirement in most present military specifications. It is based on the premise that if the reliability or mean-time-before-failure (MTBF) is much greater than the time during which it is tested, the chances of a failure occurring during the prescribed test cycle are negligibly small. All of the subsystems associated with Apollo fall into this category since the required reliability is between one and three orders of magnitude greater than the proposed test level.

On the most critical items, those in criticality class one, the plan imposes a program that is less than the minimum proposed by AGREE. Specifically, 2.5 times the mean-time-before-failure (MTBF) was chosen because it can be shown that it is the lowest possible test time that can be imposed on a system and still give any reasonable assurance that the system will approach the objective. This is true only if no failures are encountered during the formalized test period.

For criticality class 3 items, a much reduced program has been established. It has been established at one times the MTBF on the premise that, if it could not make this, it could not comply inherently with the program objectives for the component.

For criticality class 2 components, the program is based on an objective of 1.5 times the MTBF, representing a reasonable compromise between the other two criticality classes.

These factors are used to compute the total units of hardware required for the respective test plans in Section 5. The number of systems, equivalent systems, and/or components required for each qualification test plan are determined by multiplying the test level MTBF by the factor corresponding to the criticality of the system or component and dividing this product by the equipment service life. In the case of criticality class 3, however, hardware requirements for mission simulated life tests were established at one system, as described in the minimum qualification program. The number of hours for the minimum qualification program is established at one mission cycle, as depicted in Figure 2-6.

2.5 THE MINIMUM QUALIFICATION PROGRAM

In addition to the criticality constraint a minimum qualification program was established to represent a base point on which all subsystem qualification programs could be built. Anything less than this would com-









promise the objectives of the program and yield little intelligible data relevant to the qualification of the subsystems. The minimum program utilizes multiple hardware usage. It also assumes that no failures will be encountered. All failure modes that are potentially critical must be designed out of the systems and the tests must verify that the problem does not exist. The tests are planned and scheduled carefully to insure that a previous test conducted on a component will not prejudice the results of a following test. Refurbishment of components and systems is planned where multiple tests are scheduled and detrimental effects expected during the early phases.

The minimum qualification program is defined to include three components or lower levels of assembly for sequential single environmental, explosion proof, and electromagnetic interference tests. At least one of these components or lower-level assemblies is required for off-limit tests. One complete subsystem is scheduled for mission simulation and life tests, with necessary replacements on high criticality, limited life, or other items which require refurbishment prior to completion of any test phase. Table 2-4. summarizes the minimum hardware requirements.

Table 2-4. Minimum Hardware Per System

Test Phase	No. of Black Boxes and Lower Assemblies	No. of Subsystems
Phase A. Design proof	3	0
Part 1. Environmental	(3)	(0)
Part 2. Off-limits (from Part 1)	(1)	(0)
Phase B. Mission simulation and life	0	1*
Total	3	1*

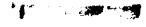
Hardware requirements, above this minimum program, will be justified on the basis of criticality, expected mission life, and service life. Since service life may cause the minimum program hardware requirements to vary considerably, service life has been selected and defined very closely.

*Plus replacements on critical and limited life items

Refurbish others requiring such action







At the completion of the mission simulated life tests, post-test examinations will be performed to investigate the possibilities of equipment degradation that are not normally discernible. Similarly, post-test examinations will be performed on equipment that has been subjected to off-limits testing.

2.6 QUALIFICATION PROGRAM CONTINGENCIES

The Apollo qualification program is considered a bare minimum and, therefore, will be carefully controlled by Apollo reliability to assure maximum applicability of each test and the data derived from it.

The probability and effects of a failure have not been provided for in the selection of numbers of hardware for tests and facilities planning. Any failure during qualification is considered a contingency which will necessitate additional hardware, test time and facilities rescheduling. It is most probable that failures will be encountered but to provide accent on the needy areas, planning for them must wait until failures are encountered. It is anticipated that as a failure occurs, a preliminary analysis will be made immediately. The program will be designed to determine the cause and insure proper corrective action. In order to reach this objective, a fast reaction cycle must be set-up between NASA and S&ID for the resolution of contingencies not included in the program, and to prevent serious slippages in schedules.

Reliability demonstration to any level of reliability or confidence is not considered a prerequisite to qualification and is beyond the scope of this program. An assessment will be attempted when time and data permit. It is anticipated that there never will be enough data to accurately determine the Apollo system reliability before flight time.

Ine test program, as applied to ground qualification of flight articles, is planned so that as each progressive step in the flight test program is executed, the individual components will have undergone some testing that will facilitate a decision as to its flight worthiness. Individual launch constraints corresponding with each intended flight article have been generated to define what must be accomplished relative to qualification of each component scheduled for the boilerplate or spacecraft prior to launch.

2.7 TESTING CRITERIA

2.7.1 Test Equipment

Equipment measuring item parameters will not introduce an error greater than ten percent of the tolerance on the parameter. If a parameter tolerance is plus or minus 10 percent, the equipment error will not be greater than plus or minus 1 percent of the parameter nominal value.



2.7.2 Failure Reporting, Analysis and Feedback System

Detailed malfunction data will be recorded as a part of normal equipment testing operations. All failures will be analyzed for corrective action requirements. The designation, retest OK will not be considered acceptable. A complete analysis will be performed on all failures to determine the cause of the failure or the reason for the symptoms reported.

2.7.3 Adjustment and Repairs During Test

No adjustments, repairs or maintenance will be done during tests unless they are part of a scheduled maintenance plan or not due to faults in design, materials, workmanship, or test conditions imposed. This condition will be imposed on all equipment during qualification. After qualification is accomplished this will be modified for mission simulation life tests.

2.7.4 Waiver of Tests

If evidence can be furnished of equipment or component compliance to requirements of the procurement specification, or evidence is provided certifying that similar equipment or components have successfully passed tests to equivalent or greater criteria than those required, the applicable portion of these tests will be waived. The required evidence to support partial or complete qualification by similarity includes the following:

- 1. Complete description of similar item, including photographs, drawings and performance data
- 2. Test reports and test data of previously conducted functional and environmental tests (actual and similar equipment)
- 3. Supplier's comparison of the proposed article and that for which similarity is claimed; listing reasons for similarity claims

2.7.5 Hardware for Test

The hardware allocation for qualification testing based on the test criticality computed for each system or component of the system where the criticality classification may vary within the system is shown below:

Criticality class	1	2	3
Number of hardware items	7	5	3









3.0 QUALIFICATION SCHEDULES*

3.1 CONCEPT

The qualification schedules are graphical presentations of the anticipated test status for components of all Apollo subsystems. They show the time phasing of the Apollo master development schedule (see Figure 1, Volume I), with respect to boilerplate and airframe vehicle launch dates, and the phasing of component qualification relative to system qualification. The intent is to present test schedules in conjunction with flight schedules in order to foresee the need for launch constraints for each flight article. These constraints should specify the degree of success in development and qualification tests that each component must meet to assure reasonable success for the boilerplate or airframe mission.

3. 2 APPLICATION

3. 2. 1 Explanation

The following describes how the qualification schedules foresee the need of launch constraints for a particular mission.

Prior to the mission, to the extent that ground qualification permits, it is desired to ascertain if a certain component has been qualified, in order to proceed to the flight qualification level.

The component in question is located in the applicable system schedule. The boilerplate or airframe launch dates, indicated by the labeled vertical lines, are compared with the phase of component qualification. If the launch date falls within the component development testing phase, constraints, consisting of a statement setting a minimum standard to be reached such as a success to failure ratio, will establish the degree of qualification required for that component. A launch date falling within the qualification test phase would require similar constraints to be established for components in question. If a component has completed qualification prior to the launch date, launch constraints will not be required.

3. 2. 2 Example

B-12 scheduled for flight in February 1964, will serve as an example, It will contain components of the launch escape, earth landing and structural

^{*}Entire section reissued.







subsystems. In the LES the launch escape motor, (see Figure 3-4) has completed 17 development tests, but no qualification tests. Similar conditions apply to the jettison and pitch control motors with 23 and 28 development tests, respectively. Including the amount of testing accomplished prior to launch, S&ID will state the degree of success to be met by each component, commensurate with assurance of flight success. The abort sequencer, tower structure, tower insulation, and explosive bolts will be treated similarly. The components of the Earth Landing System (see Figure 3-5) and Structures Subsystems (see Figure 3-13), shown as onboard equipment for B-#23, are qualified prior to the launch date and therefore do not require any launch constraints.

3. 3 SUBSYSTEM SCHEDULES

(Note: Schedules will be expanded as additional information becomes available).

3. 3. 1 Service Propulsion System

Figure 3-1 shows that the SPS will be on-board AFRM 009 and AFRM 011. The SPS will have completed qualification prior to installation.

3. 3. 2 Reaction Control System

From Figure 3-2, it may be seen that the C/M RCS will be installed on B-22 and AFRM's 009 and 011. The system will be qualified for use prior to the launch date of B-22. Those components without schedules have not been released for manufacture.

Figure 3-3 shows that the S/M RCS is used on AFRM 009 and 011 only and will be qualified for those flights.

3. 3. 3 Launch Escape System

Examination of Figure 3-4 reveals the fact that launch constraints will be required for boilerplate flights B-6, B-12, B-13, B-23, and B-15. Although the jettison motor and hot wire initiators are qualified for use on B-15, the system is not qualified for use until the flight of B-22.

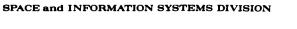
3. 3. 4 Earth Landing System

Figure 3-5 illustrates the fact that the ELS is installed as a system on B-6, B-12, B-23, B-22, and AFRM's 010, 009, 002, and 011. The system will be qualified for use prior to the launch of B-22.









	ی ا	1		בו	ا ي
	1966	<u>"</u>		4	1966
		_		「一	-
		_	II0 JV	۵	ヿ
		z		Z	ı
		-			1
		s		ш	
		\ <	010 4A	8	- 1
	l	⊢		<u> </u>	
	1965	_			1965
	-	_		_	-1
	l	Σ		Σ	
	l	<		4	- 1
	l	Σ	z-4	Σ	
		L		1	
	١,	_	•	-	- 1
	-	٥	0.0	-+	-
		\vdash	91-8	의	- 1
		z		z	
		٥		0	
		S	,	S	
		. <		<	-
	4.	J	βγ	ᅱ	4
	1964	_	51-8	╗	1964
	ı	Σ	74	-	
		<u>-</u>		Σ	1
				٧	
		Σ	ει- 1	Σ	1
		-	214	<u>u</u>	
		_		-	
		٥		٥	7
	[z		z	1
	1	0		0	ŀ
	Ì	s		s	
	ŀ	<		_	1
	_ }	\neg		<u> </u>	
	1963			긔:	1963
	-	긔		_	-
		≥		Σ	1
1	_	<		⋖	1
	L	Σ		Σ	
		4		_	
ST23T NOITADIF	אחכ	>	4 to 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4		7
OPMENT TESTS	EVEL	ı T	www.4		7
3/ \$	TEMS	,	-4 - 0044 -0000 - 000		1



Service Propulsion System Component Schedules

Figure 3-1.

GIMBAL ACTUATOR & THRUST MOUNT ASSY

PROPELLANT FEED LINES

PROPELLANT FEED SUBSYSTEM

HEAT EXCHANGERS

CONNECTORS
PROPELLANT DISCONNECTS
CHECK VALVES

MAIN ENGINE SUBSYSTEM PROPELLANT VALVE ASSY

SERVICE PROPULSION SYSTEM ENGINE

He TANKS OXIDIZER TANKS FUEL TANKS

SPS QUANTITY INDICATING AND MIXTURE RATIO SUBSYSTEM

TANKAGE

TEST POINT COUPLINGS

SOLENOID VALVES
PRESSURE REGULATOR

HELIUM DISCONNECTS RELIEF VALVES PRESSURIZATION SUBSYSTEM







C/M RCS Component Schedules

Figure 3-2.

	1966	FM	——————————————————————————————————————	∑	1966
	1	_		「「	-
		a		_	П
		z		z	
		0		0	
		s		s	
		«		<	
	r.	<u>_</u>		_	9
	1965	_		_	1965
		Σ		Σ	-
		×		<	ı
		Σ		Σ	
	•	L.			
		_		-	
	_		91-8	۵	\dashv
		z		z	
		0		0	1
		s		s	
	i	4		4	
	4	\neg		-	4
	1964	-		-	1964
		Ξ	ε-4	Σ	
		<	የ የ የ የ	⋖	
		Σ	E1-4	Σ	ı
		ш		4	i
		-	21-4	_	
		_	1111 8 8 999	۵	
		z	_ 94	z	
		0		0	
		S		S	
		<		٧	
	1963	_		_	1963
	6	-		ſ	2
	[Œ		W	
		<		٧	
		¥		Σ	1
		<u>u</u>		ч	╝
ST23T MOITADIF	I TYN	٥	5 <u>4</u> 44 8000 00 044		\Box
OPMENT TESTS	13A3	٥	444 44 000		\Box
J/2 2M3TI GGGGGGV44 204 0400			5555544544 4454 666		

□ DEVELOPMENT TESTS○ QUALIFICATION TESTS● ON-BOARD ITEMS

RELIEF VALVE VENT VALVE (O2 AND FUEL)

FILL AND DRAIN VALVE (He, O₂ AND FUEL) REGULATOR SQUIB VALVE

BURST DISC TANKAGE

PROPELLANT FEED SOLENDID VALVE, HELIUM SOLENDID VALVE, PROPELLANT CHECK VALVE

COMBUSTION CHAMBER
INJECTOR HEADS
OXIDIZER VALVES
FUEL VALVES

C/M REACTION CONTROL SYSTEM

ENGINES

HELIUM TANK OXIDIZER TANK FUEL TANK

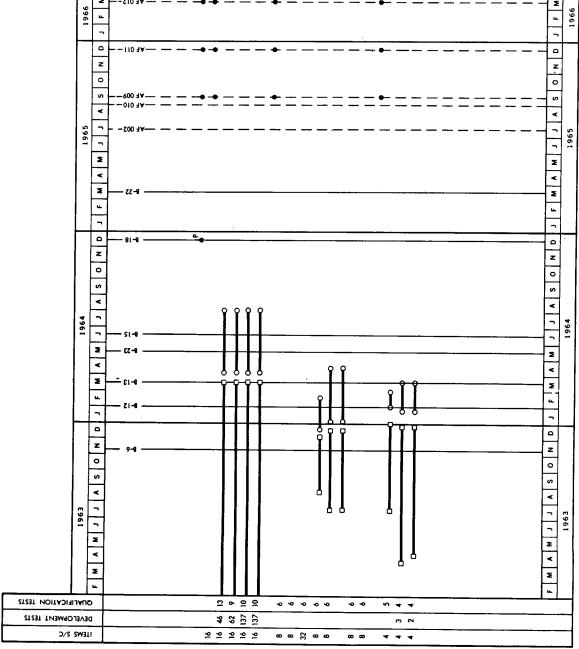






S/M RCS Component Schedules

Figure 3-3.



□ DEVELOPMENT TESTS
 ○ QUALIFICATION TESTS
 ● ON-BOARD ITEMS
 P PARTIAL SYSTEM





He SOLENOID VALVE CHECK VALVE

SOLENOID VALVE

PROPELLANT FEED

VENT VALVE (O2 AND FUEL)

RELIEF VALVE

COMBUSTION CHAMBER

INJECTOR HEADS FUEL VALVES OXIDIZER VALVES

S/M REACTION CONTROL SYSTEM

ENGINE

FILL AND DRAIN VALVE (He, O₂ AND FUEL) PRESSURE REGULATOR

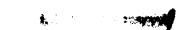
OXIDIZER TANKS FUEL TANKS

HELIUM TANKS

TANKAGE







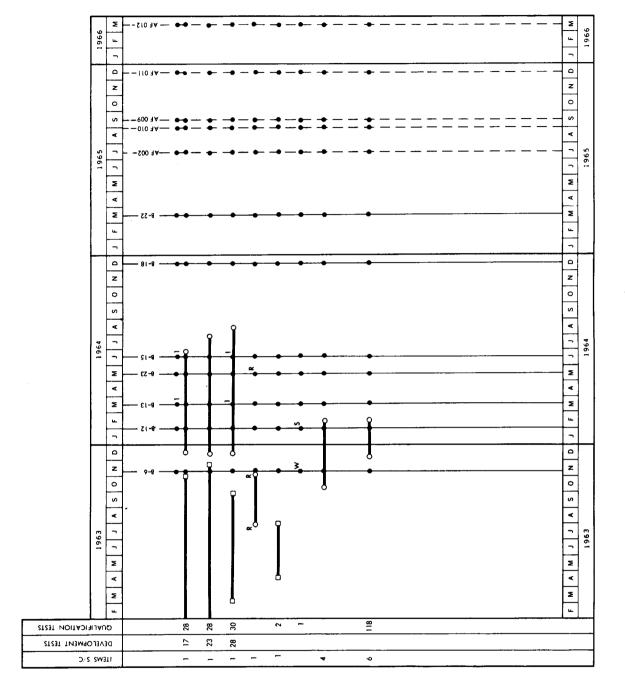


Figure 3-4. LES Component Schedules

LAUNCH ESCAPE AND LAUNCH ESCAPE MOTOR

JETTISON MOTOR

PITCH CONTROL MOTOR

ABORT SEQUENCER

LES TOWER STRUCTURE

TOWER INSULATION

EXPLOSIVE BOLTS

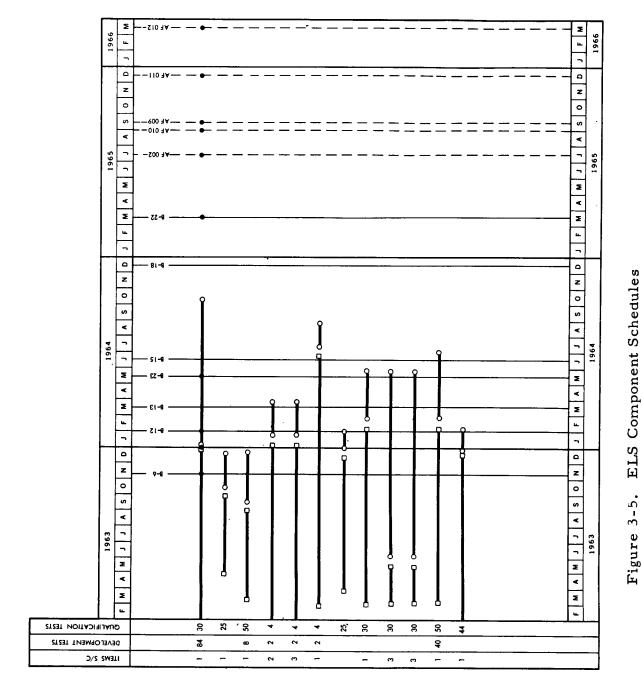
PYROTECHNICS

HOT WIRE IGNITER CARTRIDGE

NUMBER FIRED TO 8-23-63
O QUALIFICATION TESTS
O DEVELOPMENT TESTS
NON-BOARD ITEMS
R RELAY TYPE
I INERT
S SPRAYED
W WRAPPED

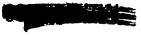






D DEVELOPMENT TEST
O QUALIFICATION TEST
O ON-BOARD ITEMS
QUALIFIED





CHUTE FABRIC, SAMPLES SEQUENCE CONTROLLER

DROGUE CHUTE

MAIN CHUTE PILOT CHUTE

DROGUE DISCONNECT

MAIN DISCONNECT DROGUE MORTAR

PILOT MORTAR

EARTH LANDING SYSTEM

MAIN CLUSTER HARNESS ASSY

REEFING LINE CUTTER





3. 3. 5 Environmental Control System

Figure 3-6 shows that the ECS is installed as a complete system in AFRM's 009 and 011. The system is not scheduled for completion of qualification until shortly after the launch of AFRM 011. Launch constraints will be required for the two flights of this system.

3. 3. 6 Electrical Power System

A study of Figure 3-7 shows that the fuel cells are not flown until AFRM 009 and that the complete system will be qualified shortly prior to the flight of B-18. Launch constraints will not be required for AFRM's 009 and 011 for the EPS.

3. 3. 7 Guidance and Navigation System

Figure 3-8 shows that the G&N system will be qualified for use for the first manned flight. Launch constraints, however, will be required for AFRM 009 for that portion of the G&N system installed on that flight vehicle.

3. 3. 8 Stabilization and Control System

Figure 3-9 shows that the SCS will not be qualified for use on any of the planned flights. Launch constraints will be required for B-22, AFRM 009, and AFRM 011 for the SCS.

3. 3. 9 Communications and Instrumentation Systems

Figure 3-10 shows qualified systems available for planned flight usage.

3. 3. 10 Life Systems

Figure 3-11 indicates the initial usage of the life systems on AFRM 011 with the system having completed qualification prior to that date.

3. 3. 11 Thermal Protection System

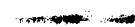
The information contained in Figure 3-12 reveals that the thermal protection systems is to be included on only AFRM's 009 and 011 with system qualification being accomplished considerably prior to that time.

3. 3. 12 Structure

Figure 3-13 portrays the usage of some portion of the primary structure on all flight vehicles. Structural development will be accomplished prior

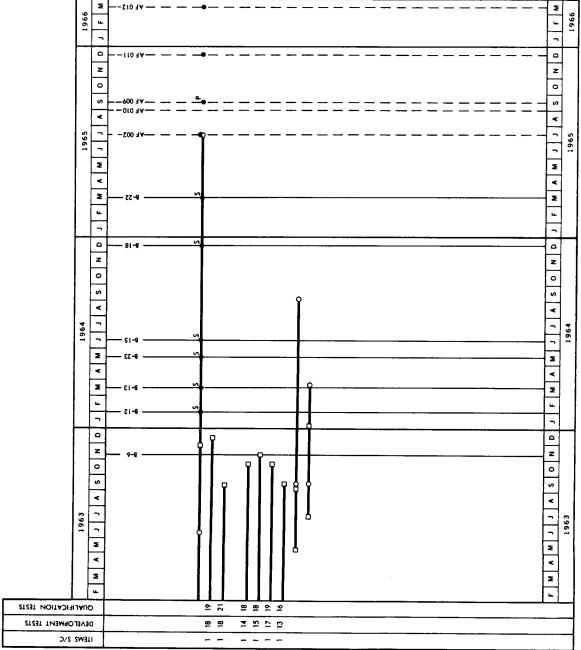


--- VE 015-



ECS Schedule Constraints

Figure 3-6.



© DEVELOPMENT TESTS
© QUALIFICATION TESTS
© OUALIFICATION TESTS
S OF COOLING EQUIPMENT
P PARTIAL SYSTEM □0 • v •





COLD PLATES SPACE RADIATORS TRANSDUCERS

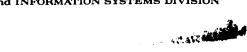
C/M TEMPERATURE CONTROL SYSTEM

O2 SUPPLY SYSTEM

WATER GLYCOL CIRCUIT

ENVIRONMENTAL CONTROL SYSTEM PRESSURE SUIT CIRCUIT





1966	N W		- - -	1 9 1
19	-		-	┤╩╽
H	۵	II03A	-	П
	z		z	1
	0		0	1
	s	600 dv	<u>~</u>	1
	4		<	1 1
92	-		٦-	9
1965	7		_	1965
j	Σ		Σ	1
	٨		<	
	Σ	<u> </u>	Σ	
	•		4	
	7		-	
	۵	- 81-6	<u> </u>	
	z	1	Z]
	0		Ŀ	
	s] γ	S	
	٧		4	
1964		z 9	L	1964
=		- si-4	上	-
	Σ		≥	
			<	-
	Σ		Σ	
		ZI-4	۴.	
<u> </u>	-		ļ-	Н
			Z	1
	Z	├── ^{१4} ── ──│◆─[─] ◆── │ │	1-	
	0 8		s	}]
	\ \ \		< X	
_			F	ا ۾ ا
1963			一	1963
	Σ		Σ	
	«		▼	1
	Σ		Σ	
	ш		<u>_</u>	
ST23T NOITADIALA	on	R R	-	\dashv
VELOPMENT TESTS	·30	9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9		
D/S SW	311	п-пп п		

Figure 3-7. EPS Component Schedules

STATIC INVERTER

DISTRIBUTION SYSTEM

BATTERY CHARGER

BATTERY CHARGER

BATTERS

UMBILICALS

C/M TO S/M

C/M TO S/M

C/M TO S/M

C/M TO LES

SINGLE CELL

31 CELL CONFIGURATION

H2 REHEATER

O2 REHEATER

ACCUMULATOR

N2 TANK

CONTROLS, VALVES,

AND REGULATORS

REMARY PUMP SEPARATOR UNIT

RADIATOR LOOP SEPARATOR UNIT

RADIATOR LOOP SEGENERATOR

SEALS

RADIATOR LOOP REGENERATOR

SEALS

RADIATOR

SEALS

RADIATOR

OAUALIFICATION ONLY

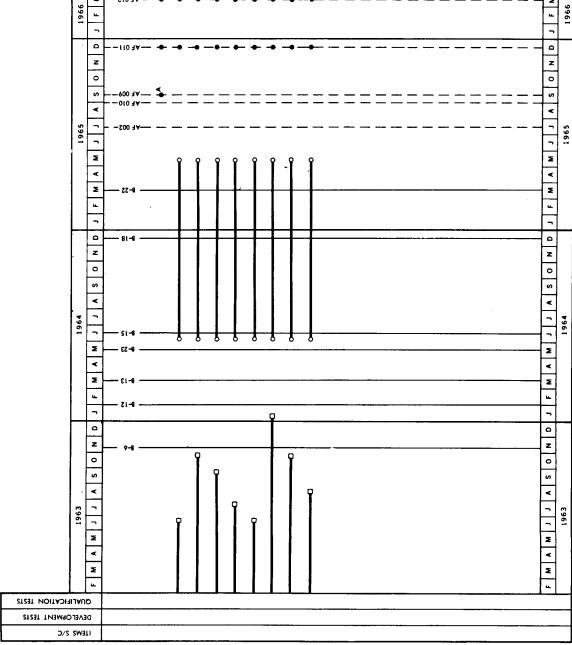
ELECTRICAL POWER SYSTEM

VF 015-



Guidance and Navigation System Component Schedules

Figure 3-8.



DEVELOPMENT TESTS
OQUALIFICATION TESTS
ON-BOARD ITEMS
A SPECIAL ATTITUDE
PROGRAMMER SEQUENCER SYSTEM □o●◀

DISPLAYS AND CONTROLS

NAVIGATION BASE

COUPLING DISPLAY UNIT

OPTICS

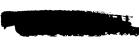
MAP AND DATA VIEWER

POWER AND SERVO ASSEMBLY

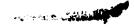
GUIDANCE AND NAVIGATION

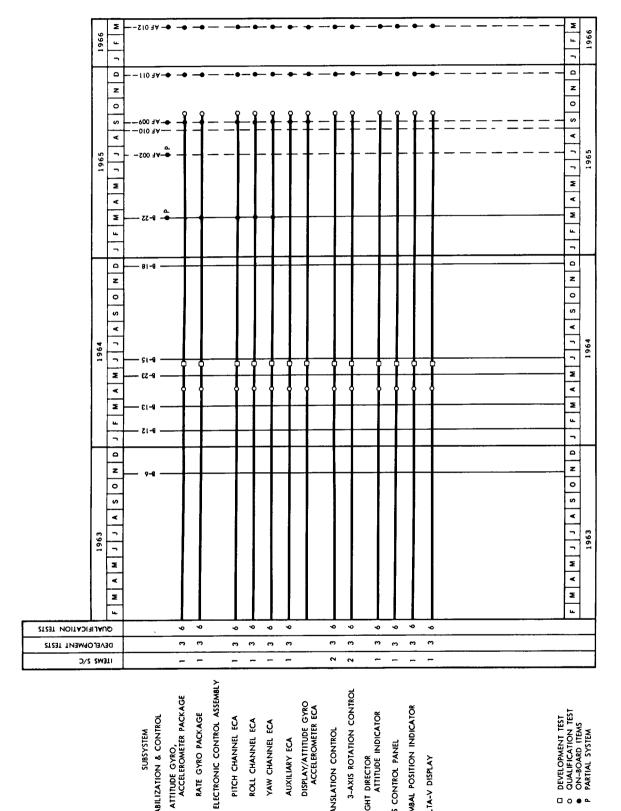
INERTIAL MEASURE UNIT

COMPUTER AGC









SCS Component Schedules Figure 3-9.

DEVELOPMENT TEST QUALIFICATION TEST ON-BOARD ITEMS PARTIAL SYSTEM □ 0 • •

TRANSLATION CONTROL

DISPLAY/ATTITUDE GYRO ACCELEROMETER ECA

AUXILIARY ECA

RATE GYRO PACKAGE

PITCH CHANNEL ECA ROLL CHANNEL ECA YAW CHANNEL ECA

STABILIZATION & CONTROL

SUBSYSTEM

m # 4

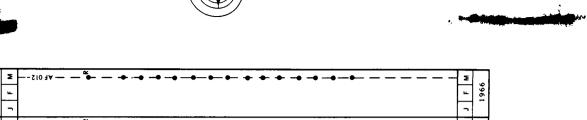
GIMBAL POSITION INDICATOR

DELTA-V DISPLAY

SCS CONTROL PANEL

FLIGHT DIRECTOR
ATTITUDE INDICATOR





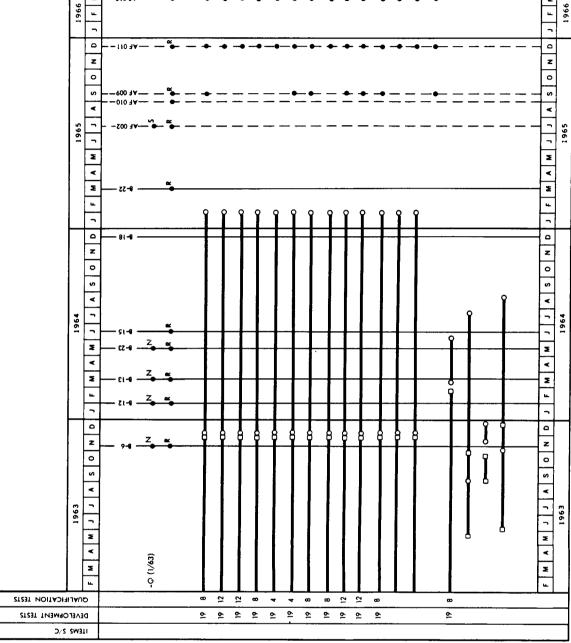


Figure 3-10. C&IS Component Schedules (Sheet 1 of 2)

VHF-FM TRANSMITTER

COMMUNICATION CONTROL PANEL

VHF/AM TRANSMITTER RECEIVER

PREMODIFICATION PROCESSOR

UNIFIED S-BAND POWER AMPLIFIER

WHF RECOVERY BEACON

PCM TELEMETRY

HF TRANSCEIVER

UNIFIED S-BAND EQUIPMENT

OPERATIONAL RF EQUIPMENT

TELECOMMUNICATIONS

NSTRUMENTATION

Q-BALL

C-BAND TRANSPONDER

SIGNAL CONDITIONING EQUIPMENT

OPERATIONAL DATA EQUIPMENT

DATA STORAGE

TV EQUIPMENT

AUDIO CONTROL PANEL

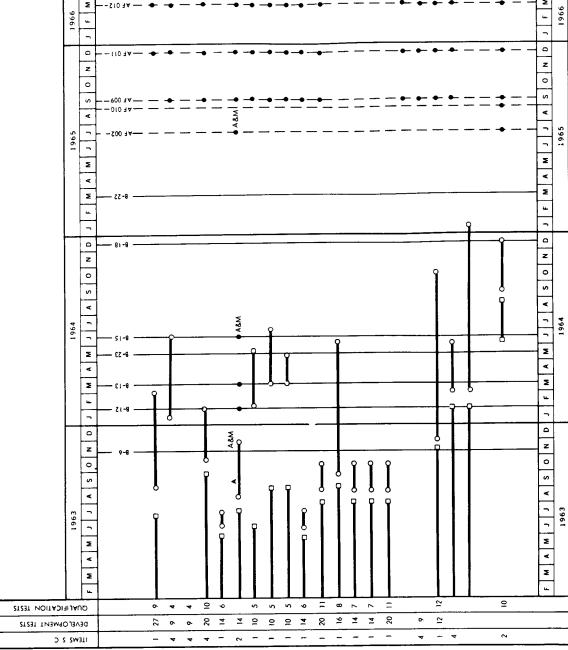
AUDIO CENTER

DATA PATCH PANEL EQUIPMENT

CENTRAL TIMING EQUIPMENT







7 C&IS Component Schedules (Sheet 2 of Figure 3-10.

DEVELOPMENT TEST
 O QUALIFICATION TEST
 ● ON-BOARD ITEMS
 A-ANTENNA ONLY
 A&M-ANTENNA AND MULTIPLEXER
 ONLY

FLASHING BEACON

TELECOMMUNICATIONS (CONT)

ANTENNA SYSTEMS

R&D C-BAND ANTENNA

R&D TELEMETRY

2-KMC HIGH GAIN

OPERATIONAL BEACON

VHF /2 KMC SCIN

R&D RADOME

VHF ANTENNA SWITCH

VHF MULTIPLEXER

R&D FILTER

DIPLEXER

VHF B U RECOVERY

VHF RECOVERY HF RECOVERY

R&D VHF OMNI

AUDIO CONTROL CENTER AUDIO CONTROL PANEL

TRANSCEIVER LOCATION AIDS

HEAD SET

2 KMC ANTENNA SWITCH

INTERCOM EQUIPMENT







Figure 3-11. LS Component Schedules

_	_			
. ا	Σ		2	ء ا
1966	<u> </u>		<u>_</u>	1966
	-		<u>_</u>	
	٥	II03V	-	
	z		z	1
ŀ	0		0	1
	s		ļ.,	1
	<		 	ł
	<u> </u>	700 3V	F	4
1965	-		├-	1965
	<u> </u>		E	ļ [—]
1	₹		2	ļ
	⋖		<	Į
	2		Σ	1
	<u>"</u>		<u>"</u>	
L	- ا		_	
	٥	81-6	-	
	z		z	
ĺ	0	l i î	0	١.
	S		s	
	<		-	
4	-		╚	4
1964	-	514	├	1964
	Σ	- cz - q	⊢	
	4	- "	2	
	-		<	
İ	Σ		3	
	-	21-9	-	
	<u> </u>		_	Ц
1	٥		٥	
 	Z		z	j
	0		0	
	s	l l o l l o	S	
	∢	-	۷	
1963	_		-	1963
61			_	6
	Σ		Σ	
	<		<	
	Σ		Σ	
			L	
DALIFICATION TESTS	סו			\vdash
VELOPMENT TESTS				\dashv
2/s sw	\rightarrow			⊣

☐ DEVELOPMENT TEST
○ QUALIFICATION TEST
● ON-BOARD ITEMS

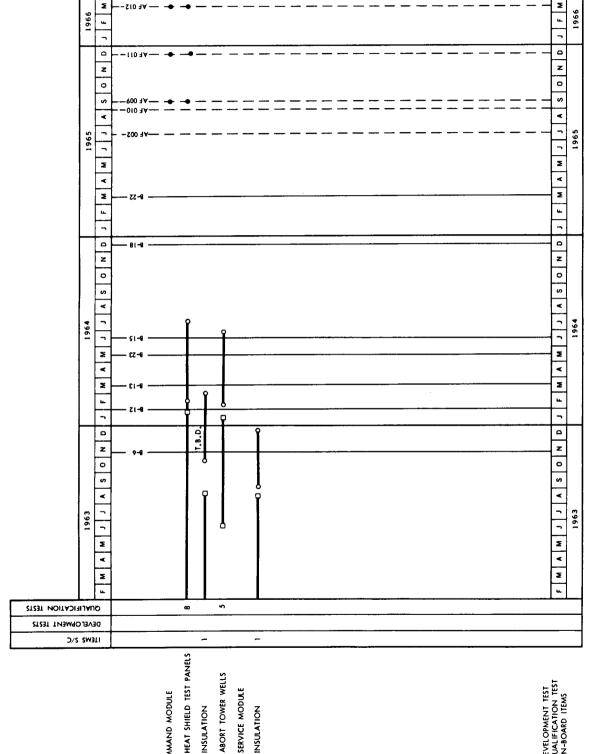
SURVIVAL PROVISIONS ASSEMBLY WASTE MANAGEMENT ARTICLES CREW PROVISIONS BIO-MEDICAL CLOTHING FIXTURES FOOD

3-15









Thermal Protection System Component Schedules Figure 3-12.

□ DEVELOPMENT TEST○ QUALIFICATION TEST● ON-BOARD ITEMS

ABORT TOWER WELLS

INSULATION

COMMAND MODULE

SERVICE MODULE

INSULATION





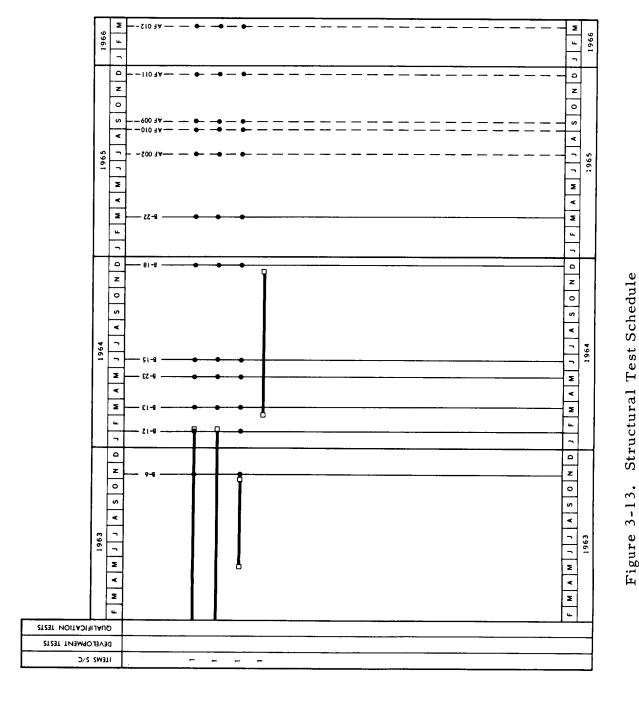
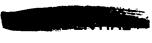


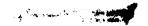
Figure 3-13.

LAUNCH ESCAPE TOWER COMMAND MODULE COMBINED MODULE SERVICE MODULE STRUCTURAL









to B-18. A test objective of B-18 is to qualify the physical and flight compatibility of the launch vehicle and spacecraft for manned flight.

3. 3. 13 Mechanical Systems

The mechanical systems, as included in Figure 3-14, will be used in all flight vehicles after B-15. Although launch constraints will be required for B-6, -12 and -23, all components of the system will have completed qualification prior to the flight of B-22.

3. 3. 14 Electronic Systems

Figure 3-15 shows that launch constraints will not be required for the planned flight usage of electronic systems.









_ ا		Σ	اي
1966		L	1966
- -			-1
		-	\dashv
_	4	의	. 1
z		z	ļ
0		0	i
s		s	. [
		.∢	. 1
	4	\vdash	. [
1965		니	: 965
= -			
Σ	γ	Σ	
₹		4	. 1
2	22-0	₹	
		┝╌┤	
		14	
-		_	
٥	81-8	۵	\neg
z	i i i	z	
	1 p + + +	0	
		┝╾┥	
S		s	
<		<	
5 7	8	-	2
1964	S1-8	-	1964
2	1	Σ	- 1
\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	1	\ \	
 		ш	
2		Σ	
<u> </u>	21-9	"	
-		ſ	
	5 0	۵	ヿ
z	1	z	
! ⊢			
•		0	
σ		s	H
<		∢	
, n	1	5	m
1963	1 1 1 1	「一	1963
₹	,	Σ.	
1 -			- 1
<		<	- 1
Σ		Σ	
L.		4	
QUALIFICATION TESTS			\neg
DEVELOPMENT TESTS			\dashv
ITEMS 5/C			\dashv
∆\2 2M3TI			

☐ DEVELOPMENT TEST
O QUALIFICATION TEST
• ON-BOARD ITEMS

Figure 3-14. Mechanical Systems and Component Schedules

PRESS. CARTRIDGE, FWD HEAT SHIELD

LIGHT BEACON, FLASHING

CREW COUCH SHOCK STRUTS FWD COMPARTMENT HEAT SHIELD SEPARATION SYSTEM

SEPARATION SYSTEM S/M - ADAPTER

C/M - S/M LES - C/M

MECHANICAL SYSTEMS

EXPLOSIVE BOLT, DUAL MODE ACTUATING SYSTEM ASTROTRACKER SEXTANT DOOR

BOMB, SOUND FIXING AND RANGE ASSY - C/M

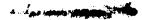
REMOTE MANUAL AND MECHANICAL CONTROL

MARKER, LOCATION

DETONATOR CARTRIDGE CREW HATCH ACTUATING SYSTEM

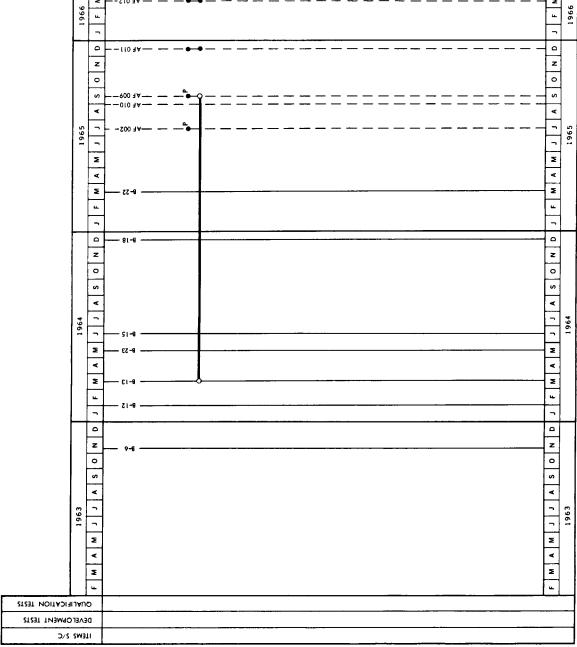
LINEAR SHAPED CHARGE





Electronic Systems Component Schedules

Figure 3-15.



DEVELOPMENT TEST
O QUALIFICATION TEST
● ON-BOARD ITEMS
P PARTIAL SYSTEM

ELECTRONIC SYSTEMS
DISPLAY AND CONTROLS
INFLIGHT TEST SYSTEM





4.0 ENVIRONMENTAL CRITERIA

4.1 ENVIRONMENTAL CONSIDERATIONS

Section 4 defines the applicable Apollo program environmental criteria. These are defined in their order of occurrence, that is by prior-to-launch (prelaunch) phases and by mission phases, in Section 4.1. Section 4.2 describes in detail the specific environments and levels of environmental severity to be encountered during each of the prelaunch and mission phases.

The environmental criteria for the Apollo project have been separated into two major areas for consideration and treatment—the prior-to-launch environments and the post-launch or in-flight environments.

4.1.1 Prelaunch Environments

Figure 4-1 displays the environments to be encountered from completion of equipment manufacture to the actual point of launch. Specific environments are listed for each phase. The extent of equipment testing is indicated by phase.

4.1.2 LOR Mission Environments

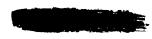
Figure 4-2 displays the mission environments as they occur successively by phase. Generally, they exist as combined environments and are treated accordingly in the specific subsystem qualification test plans of Section 5. The combined environments to be employed during the mission-life tests are shown and related to the pertinent phase.

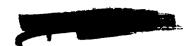
4.1.3 GSE Environments

Table 4-1 lists the environments anticipated for the GSE equipment. These items of equipment have been classified into two categories relevant to the imposed environments, sheltered and unsheltered. The environments to be imposed on them are tailored to fit these groups.

4.2 ENVIRONMENTAL LEVELS

This section delineates the levels of the different environments anticipated for the Apollo systems by program and mission phase.





MANUFA COMPLET	CTURING S&ID IE ACCEP	PARTS F TANCE CONTR	FROM S&ID RECEIV ACTOR INSPECTION	P'NG I AND TEST
	ACCEPTANCE TESTS (SOURCE INSPECTION)	PACKAGING AND STORAGE	SHIP TO S&ID	STORA
	ENVIRONMENTS PRODUCTION AMBIENT CONDITIONS	ENVIRONMENTS SHOCK TEMPERATURE HIGH AND LOW HUMIDITY	ENVIRONMENTS SHOCK TEMPERATURE HIGH AND LOW HUMIDITY VIBRATION	ENVIRONA SHOCK TEMPERAT HIGH A HUMIDIT

		TEST PREPA	ARATION		
Ende d		GE	INSTALLATION	INDIVIDUAL SYSTEMS CHECKOUT	
₩7. •	₩	IENTS URE ND LOW	ENVIRONMENTS PRODUCTION AMBIENT CONDITIONS	ENVIRONMENTS PRODUCTION AMBIENT CONDITIONS	E
				EXTENT OF TEST TESTED TO SUBSYSTEM PERFORMANCE SPECIFICATIONS - WITH ALL APPLICABLE VARIATIONS OF INPUTS AND LOADS	EXTI TEST PERF SPEC WITH COT
					<u> </u>

KKK

SHIP TO	O AMR			
INTEGRATED SYSTEMS CHECKOUT	INSPECTION AND MODIFICATION	INDIVIDUAL SYSTEMS CHECKOUT		▼ : *
NVIRONMENTS PRODUCTION AMBIENT CONDITIONS	ENVIRONMENTS SHOCK TEMPERATURE HUMIDITY VIBRATION RAIN SALT SPRAY SAND AND DUST	ENVIRONMENTS PRODUCTION AMBIENT CONDITIONS WHICH WILL INCLUDE HIGH HUMIDITY	E.	Σ
	FUNGUS		: : : : : : : : : : : : : : : : : : :	₹ .
ENT OF TEST ED TO VEHICLE ORMANCE LIFICATIONS 1 ALL SUBSYSTEMS NNECTED		EXTENT OF TEST TESTED TO SUBSYSTEM PERFORMANCE SPECS WITH ALL APPLICABLE VARIATIONS OF INPUTS AND LOADS	EX.	ΙΞ

E.

Ī

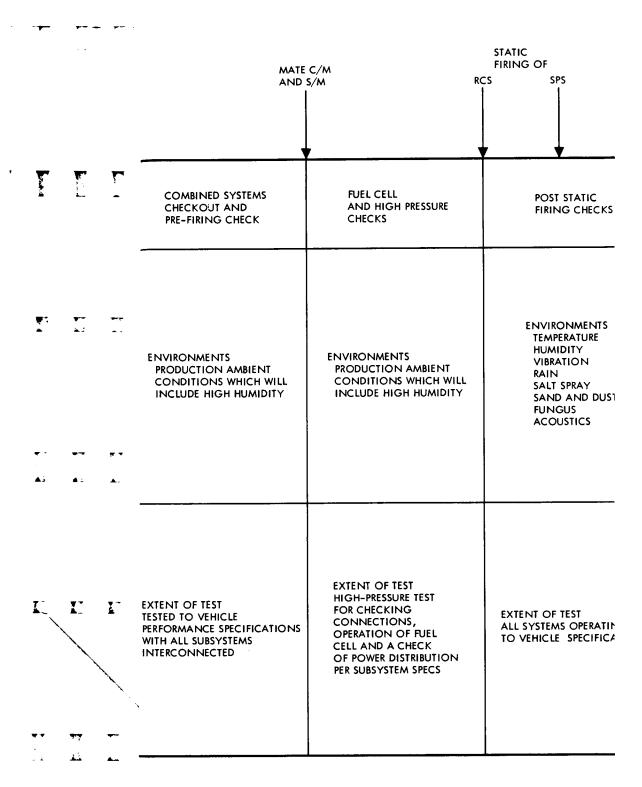
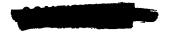


Figure 4-1. A

MOVE TO VACUUM CHAMBER		MOVE TO LAUNCH AREA
	VACUUM CHAMBER CHECKS	INTEGRATED SYSTEMS CHECKOUT-COUNTDOWN AND LAUNCH
ſ	ENVIRONMENTS ALTITUDE	ENVIRONMENTS TEMPERATURE HUMIDITY SALT SPRAY FUNGUS RAIN
1G TIONS	EXTENT OF TEST LEAKAGE TEST ONLY	EXTENT OF TEST ALL SYSTEM CHECKOUT TO VEHICLE SPECIFICATIONS

.pollo S/C Prelaunch Environments

4-3,4-4



LAUNC	H JETT LET	ISON SECOND- BURNOUT	STAGE
	FIRST-STAGE BOOST	SECOND-STAGE BOOST	EARTI ORBIT
	ANTICIPATED ENVIRONMENTS		,
	ACOUSTIC VIBRATION ACCELERATION	ACOUSTIC VIBRATION ACCELERATION	Y
			VACUUA HIGH TE LOW TEI ZERO 9
	SI MULATED MISSION LIFE ENVIRONMENTS VIBRATION AND ACOUSTICS VIBRATION AND ACCELERATION	VIBRATION AND ACOUSTICS VIBRATION AND ACCELERATION	VIBRA ACOU VIBRA ACCEI

I

	-	-		LEM ACTUATION				
_	T	-			7			
			PARK	TRANSLUNAR INJECTION	LEM TRANSFER	TRANSLUNAR COAST		
* *.	¥.	, . .		ACOUSTIC VIBRATION ACCELERATION				
	₹ * .	≅ ₹	I MPERATURE APERATURE	VACUUM HIGH TEMPERATURE LOW TEMPERATURE ZERO g	VACUUM HIGH TEMPERATURE LOW TEMPERATURE ZERO g	VACUUM HIGH TEMPERATURE LOW TEMPERATURE ZERO g		
I.	K	Ĭ.			SHOCK			
₩₹ 	## ##	-	TION AND STICS TION AND ERATION	VIBRATION AND ACOUSTICS VIBRATION AND ACCELERATION	VIBRATION AND ACOUSTICS VIBRATION AND ACCELERATION	VIBRATION AND ACOUSTICS VIBRATION AND ACCELERATION		

	LEA Eje		DING #	•
	,			
LUNAR ORBIT INJECTION	LUNAR ORBIT			∯error (m)
ACOUSTIC VIBRATION ACCELERATION			Z	7
VACUUM HIGH TEMPERATURE LOW TEMPERATURE ZERO 9	VACUUM HIGH TEMPERATURE LOW TEMPERATURE ZERO g	VACUUM HIGH TEMPERATURE LOW TEMPERATURE ZERO 9	VACUUM HIGH TEMP LOW TEMPE ZERO g	₹ .
VIBRATION AND ACOUSTICS VIBRATION AND ACCELERATION	VIBRATION AND ACOUSTICS VIBRATION AND ACCELERATION	VIBRATION AND ACOUSTICS VIBRATION AND ACCELERATION	VIBRATIO ACOUSTIC VIBRATIO ACCELER#	



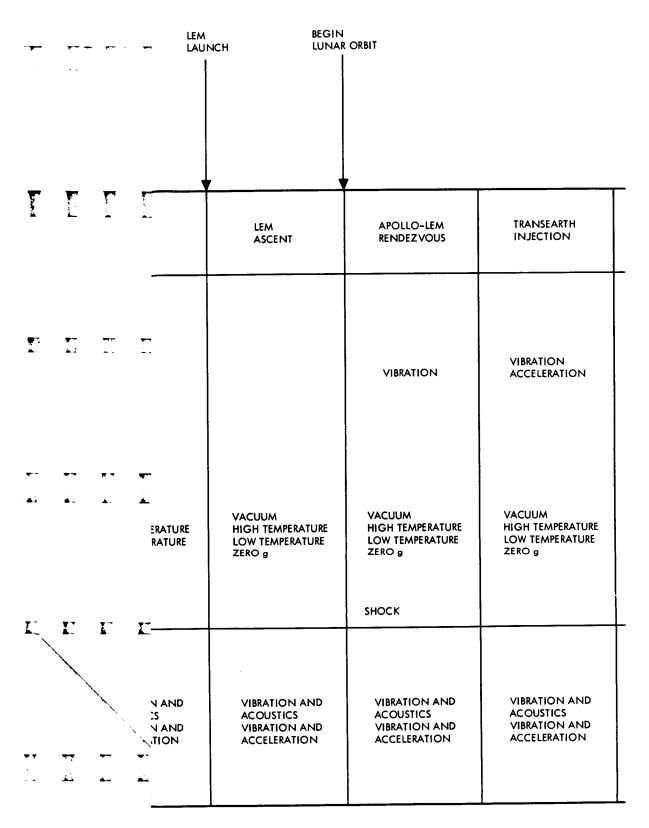


Figure 4-2. Apo

4000 TO E	MILES BEGIN LANI NTRY ENTRY	DING
,	,	
TRANSEARTH COAST	ENTRY	RECOVERY
	VIBRATION DECELERATION	
VACUUM HIGH TEMPERATURE LOW TEMPERATURE ZERO g	HIGH TEMPERATURE	
-	SHOCK	
VACUUM HIGH TEMPERATURE VACUUM LOW TEMPERATURE	VERY HIGH TEMPERATURE ACCELERATION	

llo LOR Mission Phases Environments

11

1





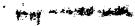


Table 4-1. Ground Support Equipment Environments

Unsheltered Equipment	Sheltered Equipment
High temperature	Operating temperature
Low temperature	Humidity
Low pressure	Vibration
Humidity	Shock
Vibration	Electromagnetic interference
Shock	
Salt fog	
Sand and dust	
Operating temperature	
Electromagnetic interference	

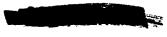
4.2.1 Prelaunch Environmental Levels Anticipated

Some of the environments anticipated for the prior-to-launch phases will be considered only as a design requirement and will not be imposed during the testing phase. This is based on the premise that the packaging and/or shipping medium will compensate for the difference between the anticipated environment of paragraph 4.2 and the test levels of paragraph 4.3.

4.2.2 Transportation, Ground Handling, and Storage

These criteria represent the natural and induced environmental design criteria associated with transportation, ground handling, and storage. However, when a severe cost penalty or airborne weight penalty is imposed by one or more of these environmental criteria upon the design of Apollo equipment, the deviation from these criteria will be incorporated into the detail equipment specification. Shipping packages or special handling and transportation or storage provisions will be developed to prevent exposure to environmental conditions in excess of those which the equipment item is capable of withstanding.









4.2.2.1 Natural Environments

1. Temperature

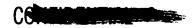
- a. Air Transportation. -20 F minimum to +140 F maximum for 8 hours
- b. Ground Transportation. -20 F minimum to +140 F maximum for 2 weeks
- c. Storage. +25 F minimum to +105 F maximum for 3 years
- d. Launch Base Area. +25 F minimum to +105 F maximum air temperature for 30 days, plus solar radiation of 360 Btu/ft²/hr for a 6-hour period each day

2. Altitude

- a. Air Transportation. Up to 35,000 feet for 8 hours
- b. Storage. Up to 6000 feet for 3 years
- 3. Humidity. 95 ± 5 percent relative humidity, including conditions wherein condensation takes place in the form of water
- 4. Sunshine. Solar radiation at 360 Btu/ft²/hour for 6 hours per day for 2 weeks
- 5. Rain. Up to 0.6 inches/hour for 12 hours
- 6. Sand and Dust. As encountered in desert and ocean beach areas, equivalent to 140 mesh silica flour, with particle velocity up to 500 feet per minute
- 7. Fungus. As experienced in tropical climates. The use of nonnutrient materials is recommended wherever possible. Where materials which are nutrients for fungi are used, such materials will be treated with an approved fungicidal agent. Fungus resistant materials are as defined in Specification MIL-E-5400.
- 8. Salt Spray. Salt atmosphere as encountered in coastal areas, the effect of which is simulated by 20 percent salt solution for 50 hours.
- 9. Ozone. Up to 3 years exposure to 0.05 parts/million concentration







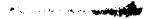
- 10. Ground Winds. These ground wind criteria consist of a description of Cape Canaveral wind data for the height intervals of 10 to 400 feet.
 - a. Free Standing. The design peak wind speeds for structural loading studies of the Saturn and Nova-type vehicles (fueled or unfueled) provides a free-standing capability 99.9 percent of the time during the strongest wind month at Cape Canaveral. The gradient to provide this capability is presented in the following tabulation.

Height	Steady State Wind	Peak Wind *
10	23.0 knots	32.2 knots
30	28.8	40.3
60	33.6	47.0
100	37.5	52.5
200	42.6	59.6
300	46.0	64.4
400	48.3	67.6

^{*}Gust Characteristics. For the effects of gusts, a linear build up from the steady-state winds to the peak winds will be assumed. The period of this build up and decay will be taken as 4 seconds for all height levels, i.e., build up of 2 seconds and 2 seconds for decay to steady-state wind speed.

b. Storm Conditions. The 99.9-percent peak wind speeds may be exceeded during severe thunderstorm or hurricane conditions at Cape Canaveral. During such periods, the vehicle must be placed in a service structure, shelter, or tied in such a manner that wind loading conditions greater than those for the 99.9-percent winds will not be experienced by the vehicle. The vehicle protective structures should be designed to withstand wind loads resulting from a probable maximum wind speed of 108 knots while containing the vehicle. Wind speeds apply from 10 to 400 feet heights.





4.2.2.2 Induced Environments

1. Shock. As experienced in each of three mutually perpendicular axes

Equipment Weight	Shock Level	Time
Less than 250 lbs	30 g	ll±1 milliseconds
250 lbs to 500 lbs	24 g	ll±1 milliseconds
500 lbs to 1000 lbs	21 g	ll±l milliseconds
Over 1000 lbs	18 g	ll±1 milliseconds

2. Vibration. As experienced in each of three mutually perpendicular axes

Equipment Weight	5 to 27.5 cps	27.5 to 52 cps	52 to 500 cps
Less than 50 lbs	±1.56 g	0.043 in double amplitude	±6.0 g
50 to 1000 lbs	±1.30 g	0.036 in double amplitude	±5.0 g
Over 1000 lbs	±1.04 g	0.029 in double amplitude	±3.33 g

4.2.3 Post-Launch Environmental Levels

The post-launch environments are presented as a function of mission phase and spacecraft zone. Figure 4-3 illustrates the four zones of the spacecraft as a function of station number and function.

The vibration, acceleration, acoustic, and shock environments are shown in Table 4-2.

The temperature environments are described in Table 4-3.

Other environments, such as oxidation, hazardous gases, radiation, pressure, winds, humidity, radio interference, and meteoroids, are as follows:

1. Oxidation. Command module equipment will withstand an atmosphere of 100 percent oxygen at 5 psia for 400 hours (includes ground and flight time).





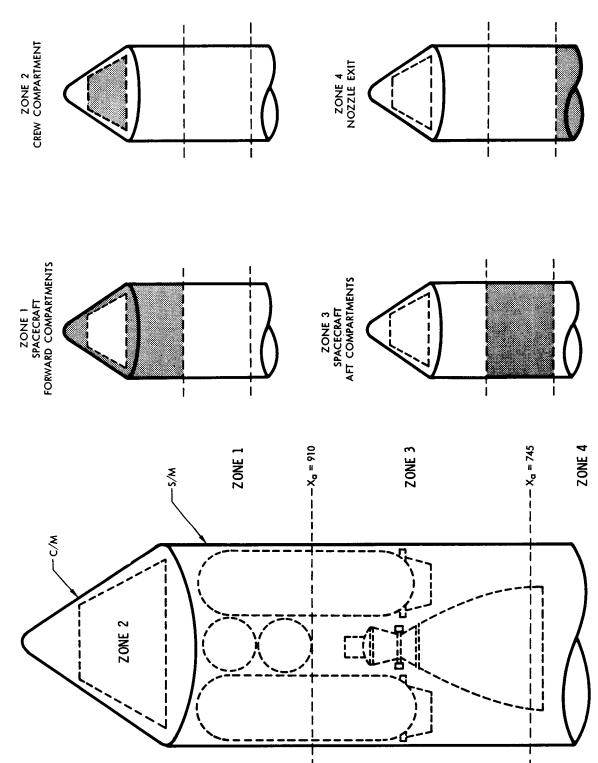


Figure 4-3. Spacecraft Zones, Location and Title



(Sheet 1 of 8) Flight Mission Phases Table 4-2.

The vibration levels shown are for basic structure and packages rigidly mounted thereon. For rigidly mounted packages with weight in excess of 10 pounds, the vibration levels at frequencies above one-half of the first local response mode will diminish in accordance with the following: (g) A₂ = A₁ (1.5 - 1/2 10g W₂) Where A₁ = noted vibration level A₂ = A₁ (1.5 - 1/2 10g W₂) Where A₃ = noted vibration level of package All references to linear increases or decreases in environments

All references to linear increases or decreases in environments

(g) A₂ = vibration levels at the vibration level at

All references to linear increases or decreases in environments are predicated on log - log scale relationships

		;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;		30	<u>.</u>	10 10 10 10 10 10 10 10 10 10 10 10 10 1	Trans-Lunar Injection and		Trans-Earth Injection and	, , , , , , , , , , , , , , , , , , ,	Earth		Max q	Very High Altitude
		Criteria		110-1117	2008	arm Orbit		Lunar Oron	COASI	Earth Entry Landing Fad Abort	Landing	Fad Abort	Abort	Abort
ы	ACOUSTICS (Sound Press Level-db-Ref, 0002 dynes per cm ²)	ind Press Leve es per cm ²)	1-db-Ref. 0002											
SERVICE MODULE Forward of	Frequency	External	Internal	\$	1					200				
Station Ad - 710	4.7 - 9.4	155 db	145 db	-	} :									
	9.4 - 18.8		153											
	18.8 - 37.5		150											
	37,5 - 75	161	150											
	150 - 300		145											
	300 - 600		140											
	600 - 1200	145	132											
	2400 - 4800		120											
	4800 - 9600	129	116											
	Overall	168.5	158											
	RANDOM VIBRATION	TION												
	Linear increa	use from 0,007	g /cps at 5 cps											
	to 0, 122 g ² /c ₁	ps at 50 cps 0.	to 0,122 g ² /cps at 50 cps 0,122 g ² /cps from	-180 sec	1					120 sec.				
	50 to 150 cps 0.007 g ² /cps	50 to 150 cps with a linear decrease to $0.007~\rm g^2/cps$ at $2000~\rm cps$.	ecrease to											
	PEAK VIBRATION ACCELERATION	ON ACCELERA	TION									·		
	Linear increase from 0.3 at 100 cps. 10 g from 10	Linear increase from 0.3 g at 5 cps to at 100 cps. 10 g from 100 to 2000 cps.	g at 5 cps to 10 g 0 to 2000 cps.	-180 sec.	1					120 sec.				
	RANDOM VIBRATION	TION	•											
	Linear increa	18e from 0,007	Linear increase from 0,0075 g ² /cps at 5 cps											
	to 0.052 g ² /c ₁	to 0.052 g ² /cps at 100 cps. 0.052 g ² /cps	0.052 g ² /cps				40 sec.	433 sec.	176 sec.					410 sec.
	to 0.035 g2/cj	from two to 550 tps with a linear decrease to $0.035 g^2/cps$ at $2000 cps$.	inear decrease											
	PEAK VIBRATION	NC												
	Linear increase from 0, 1 5,2 g from 300 to 2000 cp	Linear increase from 0.16 g 5.2 g from 300 to 2000 cps.	i6 g at 5 cps to											







Table 4-2. Flight Mission Phases (Sheet 2 of 8)

		Criteria		Lift-Off	Boost I	Lift-Off Boost Earth Orbit	Trans-Lunar Injection and Coast	Lunar Orbit	Trans-Earth Injection and Coast	Earth Entry Landing		Pad Abort	Max q Abort	Very High Altitude Abort
	ACOUSTICS													
	Frequency	External	위											
	9.4 - 18.8	15 4 162	144									8 sec.	30 sec	
	18.8 - 37.5	165	151		•									
	37.5 - 75	161	150											
	150 - 300	159	149								•			
	300 - 600	157	144											
	1200 - 2400	158	147											
	2400 - 4800	157	144											
	4800 - 9600 Overall	155 171	142 158											
	RANDOM VIBRATION	NO	·			•					-			
	•													
	Linear increase to 0.155 g2/cps from 60 to 500 c	Linear increase from 0.006 g^2/cps at 5 cps to 0.155 g^2/cps at 60 cps. 0.155 g^2/cps from 60 to 500 cps with a linear decrease	cps at 5 cps 5 g ² /cps decrease			\								
	PEAK VIBRATION ACCELERATION	ACCELERATION	z						-					
	Linear increase at 15 cps. Anot at 100 cps. Ano 25 g at 1000 cps.	Linear increase from 0.3 gat 5 cps to 2 g at 15 cps. Another linear increase to 11 g at 100 cps. Another linear increase to 25 g at 1000 cps. 25 g from 1000 to	cps to 2 g ase to 11 g ase to 0 to											
	2000 cps.						-							
Crew Compartment	ACOUSTICS													
	Frequency	위	•											
	9.4 - 18.8	131		-180 sec.	j					120 sec.				
	18.8 - 37.5	133				V-18								
	75 - 150	131												
	150 - 300	127												
	300 - 600 600 - 1200	122												
	1200 - 2400	109												
	2400 - 4800	101					•							
	Overall	140												
		2.2.7			1			_	-	_	_	_	_	_







Table 4-2. Flight Mission Phases (Sheet 3 of 8)

Very High Altitude Abort			410 sec.	410 sec.		
Max q Abort					30 sec	
Pad Abort					ပ် မ ဆ ထ	
Earth Landing						
Earth Earth Entry Landing Pad Abort	120 sec.	120 sec.				
Trans-Earth Injection and Coast			176 sec.	176 sec.		
Lunar Orbit			433 sec.	433 sec.		
Trans-Lunar Injection and Coast			40 sec.	40 sec.		
Lift-Off Boost Earth Orbit	·					
Boost	Ť.	<u>;</u>				
Lift-Off						<u></u>
Criteria	RANDOM VIBRATION Linear increase from 0.0063 g ² /cps at 5 cps to 0.095 g ² /cps at 50 cps. 0.095 g ² /cps from 50 to 150 cps with a linear decrease to 0.0035 g ² /cps at 2000 cps.	PEAK VIBRATION ACCELERATION Linear increase from 0.3 g at 5 cps to 8.5 at 100 cps. 8.5 g from 100 to 300 cps with a linear decrease to 5 g at 2000 cps.	RANDOM VIBRATION Linear increase from 0,007 g ² /cps at 5 cps to 0.040 g ² /cps at 100 cps. 0.040 g ² /cps from 100 to 200 cps with a linear decrease to 0.015 g ² /cps at 2000 cps.	PEAK VIBRATION Linear increase from 0.16 g at 5 cps to 3.5 g at 300 cps, with a linear decrease to 2.5 g at 2000 cps.		600 - 1200 130 1200 - 2400 129 2400 - 4800 126 4800 - 9600 122 Overall 142





Table 4-2. Flight Mission Phases (Sheet 4 of 8)

	Lift-Off Boost		Earth Orbit	Trans-Lunar Injection and Coast	Lunar Orbit	Trans-Earth Injection and Coast	Earth Entry	Earth Landing	Pad Abort	Max q Abort	Very High Altitude Abort
RANDOM VIBRATION Linear increase from 0.006 g ² /cps at 5 cps to 0.13 g ² /cps at 60 cps. 0.13 g ² /cps from									8 se c.	30 sec.	
60 to 200 cps with a linear decrease to 0,006 g ² /cps at 2000 cps.											
PEAK VIBRATION ACCELERATION Linear increase from 0,3 g at 5 cps to 2 g at 15 cps. Another linear increase to 11 g at 100 cps. 11 g from 100 to 2000 cps.									8 sec.	30 sec.	
ACOUSTICS				_							
		į.					120 sec.	****	· · ·		
300 - 600 132 600 - 1200 122 1200 - 2400 119 2400 - 4800 113 6800 - 9600 107 Overall 148											
RANDOM VIBRATION			·								
Linear increase from 0.005 g ² /cps at 5 cps to 0.086 g ² /cps at 50 cps. 0.086 g ² /cps from 50 to 150 cps with a linear decrease to 0.005 g ² /cps at 2000 cps.	-180 sec.	†					120 sec.				
PEAK VIERATION ACCELERATION Linear increase from 0.3 g at 5 cps to 7 g at 100 cps. 7 g from 100 to 2000 cps.	——180 sec.—	ţ			•		120 sec.				· · · · · · · · · · · · · · · · · · ·
					•	- *					,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,





Very High Altitude Abort	410 sec.	410 sec.			
Very q Alti	410	410		· · · · · · · · · · · · · · · · · · ·	
Max q t Abort					
Pad Abor					
Earth Landing					-
Earth Entry Landing Pad Abort			120 sec.	120 sec.	120 sec.
Trans-Earth Injection and Coast	176 sec.	176 sec.			
Lunar Orbit	433 sec.	433 sec.			
Trans-Lunar Injection and Coast	40 sec.	40 sec.			
Lift-Off Boost Earth Orbit					
Boost			§	į	<u> </u>
Lift-Off		·	- 180 e c -	——————————————————————————————————————	180 sec.
Criteria	RANDOM VIBRATION Linear increase from 0.0086 g ² /cps at 5 cps to 0.070 g ² /cps at 100 cps. 0.070 g ² /cps from 100 to 550 cps, with a linear decrease to 0.050 g ² /cps at 2000 cps.	PEAK VIBRATION ACCELERATION Linear increase from 0,23 g at 5 cps to 9 g at 400 cps. 9 g from 400 to 2000 cps.	ACOUSTICS Frequency db 4.7 - 9.4 136 9.4 - 18,8 142 18.8 - 37.5 141 37.5 - 75 141 75 - 150 138 150 - 300 134 300 - 600 130 600 - 1200 123 1200 - 2400 110 2400 - 4800 1104 Overall 147	BRATION crease fro , 025 g ² /cr cps from lecrease to	PEAK VIBRATION ACCELERATION Linear increase from 0.3 g at 5 cps to 5 g at 120 cps. 5 g from 120 to 2000 cps.
			Adapter AFT of Station Xa = 745		





Table 4-2. Flight Mission Phases (Sheet 6 of 8)

ort Abort Abort	20g 4 sec.						
Earth Entry Landing Pad Abort	20g 4 sec.	20g 4 sec. Appli- cable	· · · · · · · · · · · · · · · · · · ·			•	•
	20g 120 sec.	20g 120 sec.	20g 120 sec.	20g 120 sec.	· · · · · · · · · · · · · · · · · · ·	,	,
Lunar Orbit Coast					433 ecc. 176 ecc.		
Injection and Coast	•				10 sec.		1.
Lift-Off Boost Earth Orbit	1	+		•	•	•	•
Lift-Off Boo	7 g 147 sec.						
Criteria	ACCELERATION (Sustained) Applied along longitudinal axis of vehicle: Peak Acceleration Total Duration	ACCELERATION (Sustained) Applied along longitudinal axis of vehicle: Peak Acceleration Total Duration SHOCK 78 This shock environment is expected to exist as a result of C/M structural response to an emergency earth landing condition. No hazard to crew. Only recovery aids, operate after.	ACCELERATION (Sustained) Applied along longitudinal axis of vehicle: Peak Acceleration - Total Duration - SHOCK 78 This shock environment is expected to exist as a result of C/M structural response to an emergency earth landing condition. No hazard to crew. Only recovery aids, operate after. ACCELERATION (Sustained) Applied along longitudinal axis of vehicle: Peak Acceleration - Total Duration -	TION (Sustained) long longitudinal Acceleration - Duration - I teault of C/M s I to an emergency No hazard to c aids, operate aff TION (Sustained) long longitudinal Acceleration - Duration -	TION (Sustained) long longitudinal Acceleration - Duration - I result of C/M s I result of C/M s I result of C/M s I no an emergency I no hazard to c aids, operate af TION (Sustained) long longitudinal Acceleration - Duration - Duration all c reces shall not ex Z dynes/cm² lin interference leve b.	TION (Sustained) long longitudinal Acceleration - Duration - Le environment is to an emergency . No hazard to c aids, operate af TION (Sustained) long longitudinal Acceleration - Duration - Duration - Duration - Duration - Long longitudinal Acceleration - Long longitudinal Acceleration - Long longitudinal Acceleration - Long long long interference leve b. Li is defined as t veras edula to accelerate of the acceleration interference leve b. Li is defined as t verage of the acceleration interference leve b. Li is defined as t verage of the acceleration interference leve b. Li is defined as t verage bands was accelerate interpretencies were an irrequencies.	TION (Sustained) long longitudinal Acceleration - Duration - Leaving Color of to an emergency . No hazard to caids, operate affaits, of the acceleration - Duration - Duration - Duration - Duration - C dynes/cm ²) in cres shall not ex 2 dynes/cm ²) in cres shall not ex 2 dynes/cm ²) in terference leve bo. It is defined as the account occave bands werage of the account occave bands and 3200 cp
			4	ENT	ENT	COMMAND MODULE ACCELERA Peak J Total SHOCK 78 This shoc exists as a response condition or recovery SERVICE MODULE ACCELERA Applied a Peak J Total CREW COMPARTMENT ACOUSTICS For exter levels rein noise sou (re 0.000 range of a speech than 55 dl NOTE: S	ENT

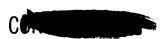




Table 4-2. Flight Mission Phases (Sheet 7 of 8)

	Criteria	Lift-Off	Boost	Lift-Off Boost Earth Orbit	Trans-Lunar Injection and Coast	Lunar Orbit	Trans-Earth Injection and Coast	Earth Entry Landing Pad Abort	Earth Landing	Pad Abort	Max q Abort	Very High Altitude Abort
COMMAND MODULE	EARTH LANDING IMPACT ACCELERATIONS											
	Crew Couch											
	x-x (eyeballs in) 26.6g's-Crew capacity x-x (eyeballs out) 19.5g's-Tumbling-Launch		z-z (e) z-z (e) y-y (e)	reballs up) l reballs down reballs side)	z-z (eyeballs up) 15.0 g/s - System Launch z-z (eyeballs down) 20.0 g/s - System Launch y-y (eyeballs side) 15.0 g/s - System Launch	em Launch stem Launch stem Launch						
	abort		:									
	Nominal for C/M		_									
	x-x (eyeballs in) 23.3 g's y-y (eyeballs side) 15.2 g's		z-z (e) z-z (e)	z-z (eyeballs down) 19.3 g's z-z (eyeballs up) 10.1 g's	.) 19.3 g's 0.1 g's							
	*Emergency for C/M - Internal Equip. Support											
	x-x (eyeballs in) 52.0 g's x-x (eyeballs out) 19.5 g's		z-z (e) z-z (e)	z-z (eyeballs down) 46.8 g's z-z (eyeballs up) 34.6 g'e) 46.8 g'e 4.6 g'e						· · · · · ·	
			y-y (e)	y-y (eyeballs side) 34.6 g's	34.6 g's							
Launch Escape System	RANDOM VIBRATION			-								
	Linear increase from 0.007 $\rm g^2/cps$ at 5 cps to 0.122 $\rm g^2/cps$ at 50 cps. 0.122 $\rm g^2/cps$ from 50 to 150 cps with a linear decrease to 0.007 $\rm g^2/cps$ at 2000 cps.	115	1								4 sec.	4 sec.
	PEAK VIBRATION ACCELERATION											
	Linear increase from 0,3 g at 5 cps to 10 g at 100 cps. 10 g from 100 to 2000 cps.	-115 sec.									4 sec.	4 sec.
*Based upon: Deletion	Deletion of earth landing impact attenuation system and no deployment of aft heat shield during earth landing; pitch orientation revised to -5° maximum variation about horizontal Y axis of C/M with respect to ground vertical.	no deploy 1.	rment o	f aft heat sh	ield during ea	rth landing; p	itch orientati	on revised to	-5° max	cimum varia	tion abou	±
Referen	Reference axes are parallel and perpendicular to the C/M. The above values are to be combined in an elliptical form to obtain off axis loading where critical. A factor of 1,5 is to be applied to above values to obtain ultimate loads.	/M. The e loads.	above 1	ralues are to	o be combined	in an elliptic	al form to ob	tain off axis lo	w guipe	here critica	l. A fac	tor





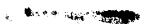
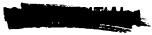


Table 4-2. Flight Mission Phases (Sheet 8 of 8)

	_					
Very High Altitude Abort						
Max q Abort						
Pad Abort						
Earth Landing						-
Earth Entry Landing Pad Abort				-		
Trans-Earth Injection and Coast						
Lunar Orbit						
Trans-Lunar Injection and Coast						•
Lift-Off Boost Earth Orbit						
Boost						
Lift-Off			1			
		LES Cone Area	137 db 136 132 134 139 144 146 148		a only. LES e kicker 8, ne shock	
Criteria		LES Skirt Area	143 db 144 145 147 149 153 156 160		This criteria applies to the instruments mounted in the nose cone area only. The transient response of the LES structure to the ingition of the kicker engine will approximate a 10 g, 50 millisecond, inverse cosine shock pulse.	
	ACOUSTICS	Octave Band Frequencies	37.5 - 75 75 - 150 150 - 300 300 - 600 600 - 1200 1200 - 2400 2400 - 24800 4800 - 9600 Overall	SHOCK	This criteria a mounted in the The transient is structure to the engine will app 50 millisecond pulse.	
1						



15 81





Flight Mission Phases, Temperature Environmental Criteria Table 4-3.

STORY WASHING

				Mission Phase			
Spacecraft Section	Condition	Lift Off and Boost	Earth Orbit	Translunar	Lunar Orbit	Transcarth	Re-Entry
Command Module Interior (Cabin Wall)	Nominal	75 ± 5°F	75 ± 5°F	75 ± 5°F	75 ± 5°F	75 ± 5°F	140°F (See Figure II-A)
	Minimum	75 ± 5°F	0°F* (See Figure II-B)	0°F* (See Figure II-B)	0°F* (See Figure II-B)	0°F (See Figure II-B)	0 ° F
	Maximum	150°F	150°F* (See Figure II-C)	150°F* (See Figure II-C)	150°F* (See Figure II-C)	150°F* (See Figure II-C)	200°F
Parachute Compartment	Nominal	75 ± 5°F	40 to 60°F	40 to 60°F	40 to 60°F	40 to 60°F	150 to 200°F
Cuter wall - Region of Parachute with Parachute	Minimum	60°F	-65°F	-65°F	-65°F	-65°F	€.0
Installed)	Maximum	175°F	120°F	120°F	120°F	120°F	250°F
Radome (Inner Wall)	Nominal	\		- DESIGN IN PROCESS	ESS		1
	Minimum	30∙F ←		- DESIGN IN PROCESS	ESS		^
	Maximum			- DESIGN IN PROCESS	ESS		→ 151°F Fused Silica 180° Duriod
							(See Figure II-D)
Command Module Exterior (Ablation Material - Outer	Nominal	60 to 200°F	150 to 225°F (See Figure II-E)	-200 to 225°F	-150 to 225°F (See Figure II-F)	-200 to 225°F	500°F (See Figure II-A)
Honeycomb Interface)	Minimum	30°F	-200*F	-290°F (See Figure II-B)	-200°F	-290°F (See Figure II-B)	-290°F
	Maximum	270°F	250°F	250°F (See Figure II-C)	250°F	250°F (See Figure II-C)	600°F (See Figure II-A)
Service Module Interior**	Nominal	60 to 80°F	40 to 80°F	40 to 80°F	40 to 80°F	40 to 80°F	-
	Minimum	40°F	30°F (See Figure II-G)	30°F	30°F (See Figure II-G)	40°F	1
	Maximum	100°F	130°F**	130°F**	130°F**	130°F***	-
Service Module Exterior	Nominal	60 to 320°F (See Figure II-H	-100 to 150°F (See Figure II-I)	-150 to 200°F	-100 to 150°F (See Figure II-I)	-150 to 200°F	1
	Minimum	30°F	-150°F	-250°F	-150°F	-250°F	•
	Maximum	390°F (See Figure II-H)	200°F	250°F	200°F	250°F	ı

*Under normal spacecraft operation, random orientation is assumed. However, for the emergency depressurized conditions it is assumed that an orientation will be imposed on the Command Module to maintain the cabin wall within the range 0° to 150°F.

**Assumes insulation is placed on inside surface of Service Module shell and radial shear panels.

***In vicinity of Service Module radiators

randok**eta ilu**



- 2. Radiation. This environment is not to be considered as design criteria.
- 3. Winds Launching. The wind criteria for launching of the Saturn and Nova-type vehicles consist of a steady-state and a peak wind. The wind gradients below provides a 95-percent and a 99-percent launch capability during the strongest wind month for C-1 and C-5 vehicles.

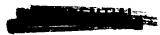
Steady-State Wind Knots

*	Peak	Winds	Knots
---	------	-------	-------

Hei ght	C-1 (95 percent)	C-5 (99 percent)	C-1 (95 percent)	C-5 (99 percent)
10	14.0	18.4	19.6	25.8
30	17.5	22.9	24.5	32.1
60	21.0	26.4	29.4	36.9
100	22.5	29.3	31.5	41.0
200	25.9	33.6	36.3	47.0
300	28.0	36.5	39.2	51.1
400	29.4	38.7	41.2	54.2

- *Gust Characteristics. For the effects of gusts, a linear build up from the steady-state winds to the peak winds will be assured. The period of this build up and decay will be taken as 4 seconds for all height levels, i.e., build up of 2 seconds and 2 seconds for decay to steady-state winds speed.
 - 4. Winds Gusts Aloft. The in-flight wind criteria for the Saturn vehicles will be employed for the lunar occupancy payload studies. These criteria consist of a wind speed profile envelope, a wind shear spectrum envelope, and an allowance for gust and/or embedded jet characteristics.

The wind speed profile envelopes for the 95-percent and a 99-percent probability level are illustrated in Figure 4-4 and the wind shears to be associated with these wind speeds are illustrated in Figure 4-5. The 95-percent wind speed and the 99-percent wind shears are the current (lunar orbit) criteria for the Saturn C-5 vehicle. Figures 4-6 and 4-7 illustrate how the above wind speed and wind shear data are combined to form a design synthetic wind profile. Winds are to be from the most adverse direction.



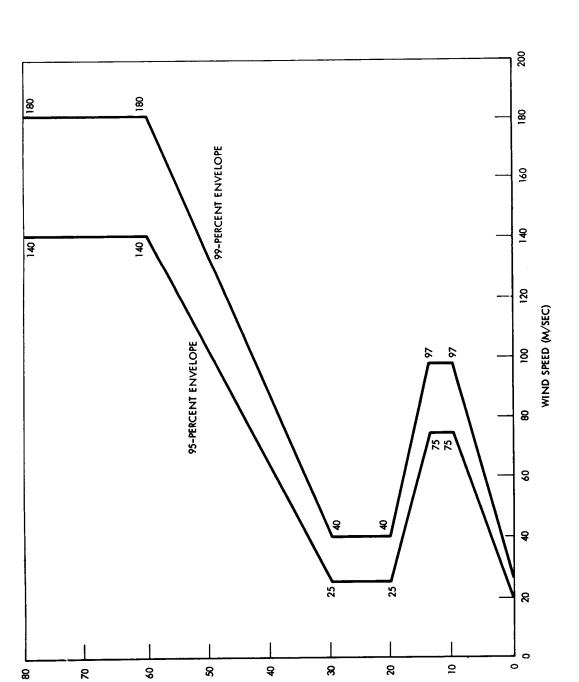
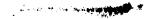


Figure 4-4. 95- and 99-Percent Wind Speed Envelopes

· : .





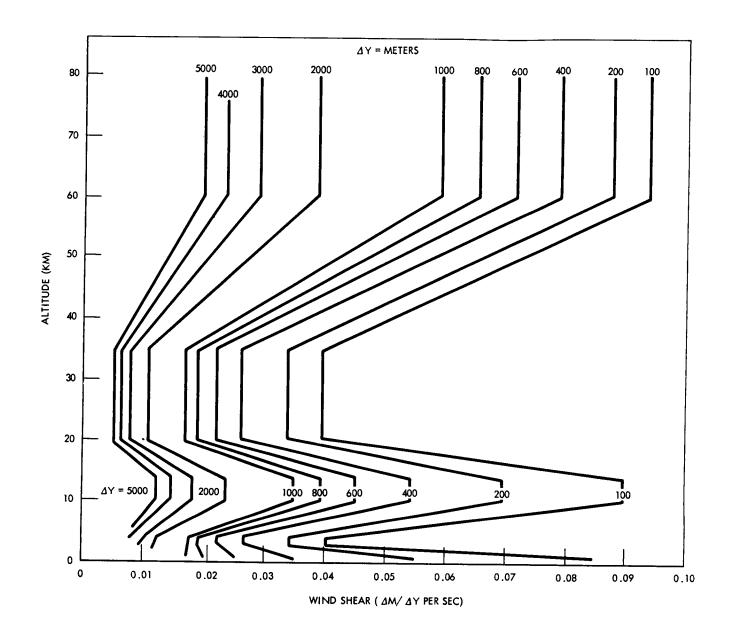


Figure 4-5. Ninety Nine-Percent Wind Shear Spectrum









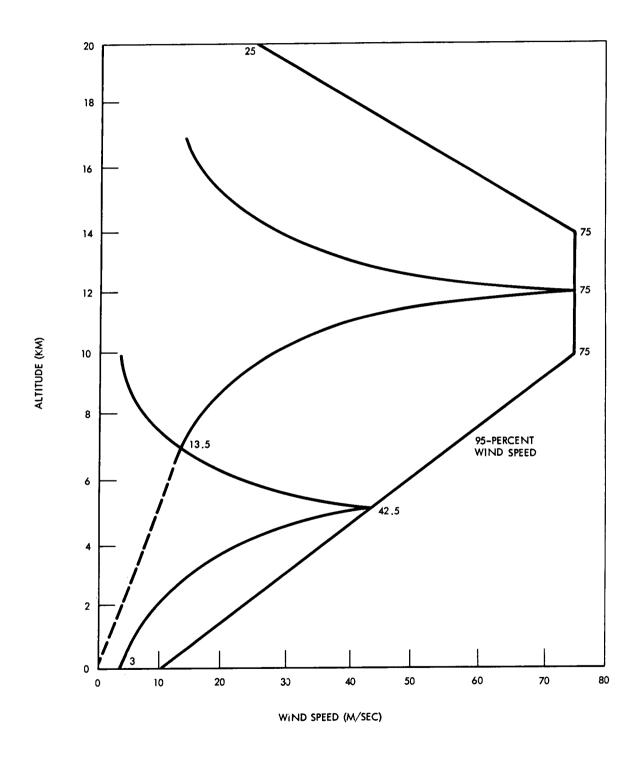


Figure 4-6. Ninety Five-Percent Wind Speed, 99-Percent Wind Shear Profiles (Altitudes of Concern, 5 and 12 KM)

56

60

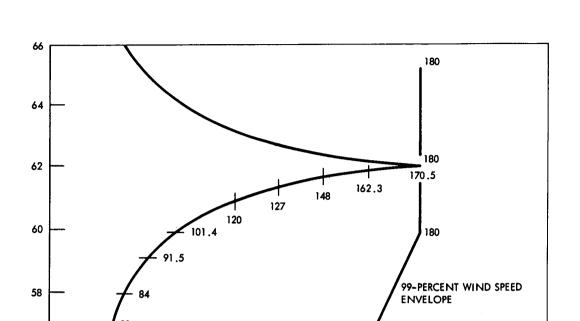
80

100

120

SAN PROPERTY OF THE PARTY OF TH





140

WIND SPEED (M/SEC)

161.5

180

200

220

160

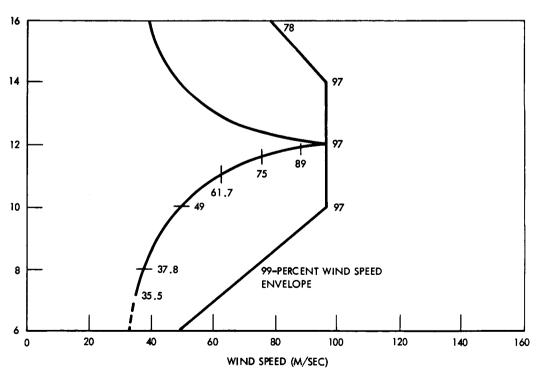
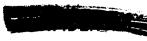


Figure 4-7. Ninety Nine-Percent Wind Speed, 99-Percent Wind Shear Profiles (Altitudes of Concern, 12 and 62 KM)





An allowance must be made in design (structural and/or control) for gust and/or embedded jet characteristics in the 4-to-15-kilometer high dynamic pressure interval. A discrete or multiple (two or three) quasi-square wave shape wind increase with an amplitude of 9 meters per second should be employed. (See Figures 4-8.) This gust is to be applied so that the speed within the gust will reach a peak wind profile speed which is 9 meters per second greater than that of the synthetic wind profile. Wave length should be chosen according to the characteristics (structural and/or control) of the vehicle system. The discrete gust will be assumed to act normal to the space vehicle.

- 5. Humidity. A relative humidity of 30 percent to 70 percent is applicable to C/M interior under normal conditions (shirt-sleeve environment). A relative humidity up to 100 percent is applicable to S/M interior only during launch phase.
- 6. Meteoroids. This environment is not to be considered as design criteria.
- 7. Radio Interference (EMI). The requirements for interference control in the basic design of all electronic and electrical components, equipment, assemblies and systems will be in accordance with Specification MC 999-0002B.
- 8. Ocean Waves. This environment is applicable only to sea landing of the command module.

a. Sea Conditions

Low seas -----1-to-3-foot waves

Medium seas-----3-to-8-foot waves

High seas-----8-foot or greater waves

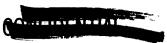
b. Swell Conditions

Low swell -----1 to 6 feet high

Medium swell -----6 to 12 feet high

High swell ------12 feet or higher





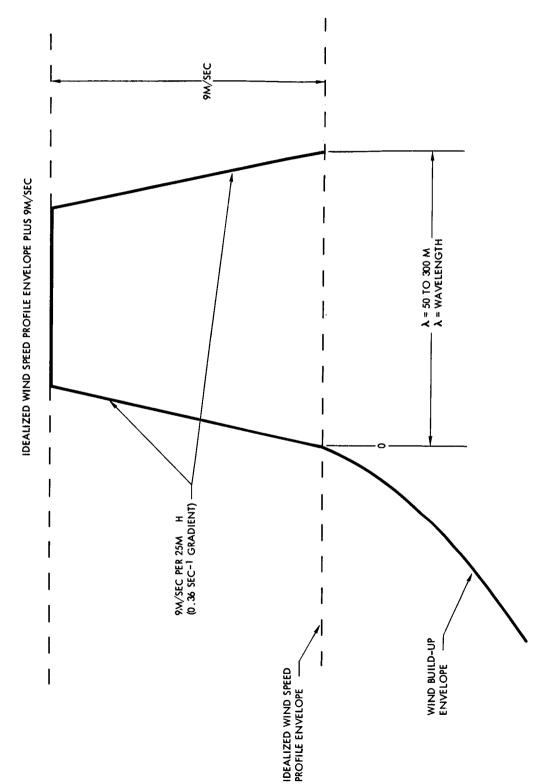


Figure 4-8. Relationship Between Established Gust Characteristics and the Idealized Wind Speed Profile Envelope





9. Pressure

a. Command Module - Crew Compartment Only

Emergency conditions: 1×10^{-4} mm Hg for 100 hours

Normal conditions: 5 psi with 100 percent oxygen

b. Service Module

 7.5×10^{-10} mm Hg for 360 hours

10. Pressure Differential

Command Module

Pressure Shell Burst: 9 psig

Crush: 8.3 psig

Fixed and Deployable H.S.

Burst: 3 psig Crush: 8.3 psig

11. Hazardous Gases - Explosion Proofing. Design of equipment will be in accordance with the requirements of MSFC 10M01071.

The vibration criteria described in Table 4-2 have been revised. Note that certain criteria cover both the command module (less crew compartment) and the portion of the service module forward of station Xa equals 910. The criteria for the portion aft of station Xa equals 910 of the service module to station Xa equals 745 of the adapter are defined.

Included in this revision are criteria for the adapter and for the crew compartment.

4.2.4 Ground Support Equipment Environmental Levels

4.2.4.1 Operational Areas Environmental Criteria

The following environments will be experienced by GSE in the operational areas located in continental United States. These criteria do not apply to GOSS equipment.







The equipment will be designed or protection provided to prevent damage or operational degradation during and/or after exposure to these environments for 3 years. This criterion supplements that defined in paragraph 4.2.1.

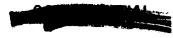
Operational areas are defined as follows:

- 1. Unsheltered Area. An area exposed to the elements with no form of protection, such as preparation areas, launch areas, engine run-up areas, and storage areas
- 2. Sheltered Area. An environmentally controlled facility center, remote station, laboratory, etc.
- 3. Sun-Shaded Area. An out-of-doors area protected from exposure to the direct overhead sunlight by some stable or portable cover, such as may be found in a vehicle test stand or launch site

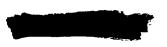
4.2.4.2 Unsheltered Area

- 1. Temperature. +15 to +105 F, plus solar radiation of 360 Btu/ft²/hr for 6 hours/day for 2 weeks
- 2. Altitude. 6000 feet maximum
- 3. Relative Humidity. Up to 100 percent
- 4. Fungus. As experienced in tropical climates. The use of nonnutrient materials is recommended wherever possible. Where
 materials which are nutrients for fungi are used, such materials
 shall be treated with an approved fungicidal agent. Fungus
 resistant materials are defined in Specification MIL-E-5400.
- 5. Sand and Dust. As encountered in desert and ocean beach areas, equivalent to 140 mesh silica flour with particle velocity up to 500 ft/minute
- 6. Salt Spray. Salt atmosphere as encountered in ocean coastal areas, the effect of which is simulated by a 20 percent salt solution for 50 hours.
- 7. Rain. Up to 0.6 inches per hour for 12 hours
- 8. <u>Hazardous Gases</u>. Explosion proofing requirements, as defined in MSFC drawing 10M01071









9. Ozone. Up to 3 years exposure to 0.05 parts per million concentration

4.2.4.3 Sheltered Area

- 1. Temperature. Controlled +60 to +80 F.
- 2. Temperature. Controlled but with environmental equipment out of commission +52 to +105 F for 1 hour maximum
- 3. Altitude. 6000 feet maximum
- 4. Relative Humidity. 60 (+0, -15) percent at 70±10 F

4.2.4.4 Sun-Shaded Area

- 1. Temperature. +15 to 105 F
- 2. Altitude. 6000 feet maximum
- 3. Relative Humidity. Up to 100 percent
- 4. Sand and Dust. As encountered in desert and ocean beach areas, equivalent to 140 mesh silica flour with particle velocity up to 500 feet per minute
- 5. Fungus. As experienced in tropical climates. The use of nonnutrient materials is recommended wherever possible. Where materials which are nutrients for fungi are used, such materials shall be treated with an approved fungicidal agent. Fungus resistant materials are defined in Specification MIL-E-5400.
- 6. Rain. Up to 0.6 inch per hour for 12 hours
- 7. Salt Spray. Salt atmosphere as encountered in ocean coastal areas, the effect of which is simulated by a 20 percent salt solution for 50 hours
- 8. Hazardous Gases. Explosion proofing requirements, as defined in MSFC drawing 10M01071
- 9. Ozone. Up to 3 years exposure to 0.05 parts per million concentration







4.3 ENVIRONMENTAL TEST PROCEDURES

4.3.1 Application of Environments in Qualification Testing

This section describes a typical application of the environmental qualification test criteria. The program delineated herein forms the basis of all the test programs as applied to the various subsystems and components. Specific application to any given subsystem is delineated under the pertinent paragraph of Section 5. A complete qualification test summary is shown by test phase in Table 4-4. The table also shows the manner in which each test component is scheduled and controlled by sample or serial number.

4.3.2 Acceleration

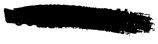
4.3.2.1 General

- 1. <u>Levels</u> design proof
 - a. Equipment (S/M) 7 g
 - b. Equipment subjected to reentry (C/M) 20 g applied only to those which must operate during or after abort and 7 g applied to all other C/M equipment
- 2. <u>Time</u> 5 minutes in both directions in each of the three mutually perpendicular axes
- 3. Levels off-limit
 - a. Equipment (S/M) 10 g
 - b. Equipment subjected to reentry (C/M) 26 g applied only to those which must operate after abort and 10 g applied to all others

4.3.2.2 Detail

The test specimen will be mounted on the centrifuge in the position specified in the applicable equipment specification. If the starting position is not specified, the bottom and front of the test unit will be arbitrarily assigned, and the specimen will be mounted upright facing in the direction of angular motion. The centrifuge will be brought up to the rotational speed required to produce the radial acceleration, and this acceleration will be stabilized and maintained for a period of not less than 5 minutes. The test specimen will then be rotated, so that it will be subjected to the









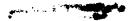


Table 4-4. Qualification Test Summary by Test Phase

	-		NOTE: (1) (2) (3) and (4)	Specimen Utilization Total Samples			
Phase		Test Title	indicate S/C zones which apply.	4	6	8	10
Climatics and Checkout		Acceptance Humidity Sand and Dust Salt Fog Explosion Electromagnetic Interference	(1) (2) (3) (4) (1) (2) (3) (4) (Exterior of S/C only) (Exterior of S/C only) (1) (2) (3) (4) (1) (2) (3) (4)				
Design Proof	Mission Sequential Maximum Levels	Acceleration Vibration Acoustics High Temperature Low Temperature Vacuum O2 Atmosphere Thermal Shock	(1) (2) (1) (2) (3) (4) (1) (2) (3) (4) (1) (2) (3) (4) (1) (2) (3) (4) (1) (2) (3) (4) (2) (1) (2) (3) (4) (2) (2)	Sample No. 1	Sample No. 1 & 2	Sample No. 1, 2, 3	Sample No. 1, 2, 3
Phase A	Off-Limit	Vibration High Temperature Low Temperature Operation to Failure Shock	(1) (2) (3) (4) (1) (2) (3) (4) (1) (2) (3) (4) (1) (2) (3) (4) (2)	Sample No. 2 & 3	Sample No. 3 & 4	Sample No. 4 & 5	Sample No. 4, 5, 6
Phase B - Life	Mission Sequential Normal Levels	Acceptance Checkout Life Acceleration Vibration Acoustics Vacuum High Temp. Vacuum Low Temp. O2 Atmosphere Thermal Shock Shock	(1) (2) (3) (4) (1) (2) (3) (4) (2) (1) (2) (3) (4) (2)	Sample No. 3 & 4	Sample No. 5 & 6	Sample No. 6, 7, 8	Sample No. 7, 8, 9 & 10



required acceleration in each direction along each of the mutually perpendicular axes. If any special axis is considered significant with respect to acceleration effects, the axis will be defined and the acceleration specified applied to the geometric center of the specimen. The centrifuge arm (measured to the geometric center of the specimen) will be at least five times the dimension of the specimen (measured along the arm).

4.3.3 Shock

4.3.3.1 General (C/M only)

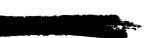
l. Levels

- a. Design proof 78 g
- b. *Mission life ____g (Where applied, the test level will be determined by S&ID as a function of the component's specific location.)
- 2. Waveform. Sawtooth with linear rise time of 11 ± 1 milliseconds and decay time 1 ± 1 milliseconds

3. Application

- a. Design proof. One direction in each of the three mutually perpendicular axis
- b. *Mission life. Once in each of the two major axes (longitudinal and radial) anticipated during impact
 - *This test is applied only to equipment that is required to function after landing impact.
- 4.3.3.2 Detail. The test fixture is to be designed such that any resonances inherent in the fixture are minor. The test specimen will be attached to a fixture capable of transmitting the shock conditions specified to the equipment under test. The attachment to the test fixture will be the space vehicle mounting or simulate it, where necessary. The shock pulse will be monitored on the test fixture near the specimen mounting points. During the shock tests, the shock waveform timing pulses, shock amplitude calibration line, and, if required, the operation of test specimen shall be monitored and recorded either on a photograph or a recording oscillograph. The shock wave, the timing pulses, and the operation of the test specimen shall be recorded simultaneously. There shall be a complete record of each shock pulse.





4.3.4 Oxidation

4.3.4.1 General

- 1. Pressure. For design proof equals 1 atmosphere and for mission simulation life equals 5 psia
- 2. <u>Time</u>. For design proof equals 4 hours and for mission simulation life equals one mission duty cycle
- 3. Gas. 100 percent 0_2

4.3.4.2 Detail

....

- Preparation. Due to the possible hazard, the test equipment will be an explosion test chamber built to MIL-E-5272C requirements. The equipment to be tested will be installed in the test chamber in such a manner that normal electrical operation is possible and mechanical controls may be operated through the pressure seals from the exterior of the chamber. All external covers of the test specimen will be removed or opened to insure circulation of the 02. The equipment shall be operated to determine that it is functioning properly and to energize potential sparking or high temperature components. Mechanical loads on drive assemblies and servos, mechanical and electrical loads on switches, and relays may be simulated, when necessary, if the proper precaution is taken to duplicate the normal loads with respect to torque, voltage, current, and inductive reactance. In all instances, it will be considered preferable to operate the equipment as it normally functions in the system during service use.
- 2. Test Procedure. The test chamber will be sealed and the internal pressure of 1 atmosphere or 5 psia will be maintained with 100 percent oxygen. In the case of the mission simulation-life test, the equipment will be operated in a manner which simulates operation during a mission. The test specimen will then be operated with the making and breaking of all electrical contacts. If high temperature components are present, sufficient warm-up time will be employed. The test time will be determined and specified by S&ID.



4.3.5.1 General

4.3.5 Vacuum

- 1. Pressure. Design proof 1×10^{-4} mm Hg (C/M interior) 1×10^{-6} mm Hg (S/M interior) 7.5×10^{-10} mm Hg * (external to S/C)
- 2. Time. Design proof equals 100 hours

*Hard Vacuum test applies only to small vacuum sensitive components and to materials. Larger equipment, subsystems, black boxes, etc., shall be subjected to vacuum of 1×10^{-6} mm Hg.

4.3.5.2 Detail

The equipment shall be placed in the test chamber and the pressure reduced to the selected level. This pressure will be maintained as determined by S&ID. If the equipment is to operate in service under vacuum conditions, it shall be operated in a manner simulating lunar mission performance requirements. (The allowable performance variation will be defined in the applicable procurement or process specification.) Pressure will then be raised to ambient level. The equipment will be visually inspected for deterioration and operated to determine compliance with the performance requirements of the pertinent specification.

4.3.6 Temperature (Low or High)

4.3.6.1 General

The test level and time will depend on the location of the test article in the vehicle and the mission time during which it must operate.

4.3.6.2 Detail

The equipment will be placed within the test chamber. The internal temperature of the chamber will be brought to the selected temperature. The equipment will be exposed to that temperature for the specified time. Equipment operation will simulate the in-service requirements. Performance during and/or after exposure to this test must conform to the requirements of the applicable equipment specification. The equipment will then be returned to ambient conditions and the equipment again operated and inspected visually. (If there is a specific rate of temperature change, this will be included in the individual test procedure.)



4.3.6.3 Cold Plates

For equipment that is temperature controlled by cold plates, the temperature tests are conducted as described below:

- nission, with the exception of the reentry and recovery phase will be inserted in the temperature chamber with cold plates attached and stabilized at the selected ambient air temperature with a coolant inlet temperature and a rate of coolant flow as determined by S&ID for the specific component. (Note: This will be the maximum inlet temperature anticipated.) The operation of the equipment and the outlet coolant and internal temperature will be monitored during this test. The procedure described above shall then be repeated with an ambient air temperature and a coolant inlet temperature, which will represent the minimum temperature anticipated. The flow rate shall remain constant throughout the tests.
- Recovery Essential Equipment. Equipment that must operate during reentry and recovery will be stabilized to selected ambient air and inlet coolant temperatures and coolant flow rate. The flow of coolant will be terminated and the ambient air temperature will be increased linearly to a predetermined temperature in a specified time which would simulate the ambient rise experienced during reentry. These temperatures will be maintained for a predetermined length of time. This will be followed by a decrease in temperature for a specified time commensurate with landing and recovery phases.
- 3. Off-Limit. The equipment will be stabilized to selected ambient air and inlet coolant temperatures and coolant flow rate. The equipment will then be operated and allowed to stabilize at its new temperature. The equipment will be monitored for proper operation. The coolant temperature will be increased by a predetermined amount and the equipment temperature allowed to stabilize. The ambient air temperature then will be increased by a predetermined amount and the temperature of the equipment allowed to stabilize again. The steps in this paragraph will be repeated in the same sequence with the coolant temperature, and the ambient air temperature increased in predetermined increments.







4.3.7 Vibration

4.3.7.1 General

Level and Time

Design proof (See Tables 4-5 and 4-6) Off-limit (See Table 4-7) Mission simulation-life (see Table 4-8)

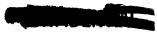
4.3.7.2 Detail

- 4.3.7.2.1 Mounting Description. The test specimen will be attached to a test fixture capable of transmitting the vibration conditions specified herein. Attachment of the test specimen to the test fixture will duplicate the space vehicle mounting or simulateit, where necessary. The test fixture will be designed such that any inherent resonances within the test frequency band will be minor. Any cables, tubing, or wires connected to the assembly under test will not affect the vibration inputs. The magnitude of the applied vibration will be monitored on the test fixture near the specimen mounting points. Vibration accelerometers will be mounted triaxially. Equipment response will be monitored in three major axes and other critical areas, as required.
- 4.3.7.2.2 Resonant Frequencies. Resonant modes of the assembly under test will be determined by varying the frequency of applied vibration slowly through the frequency range 5 to 2000 cps at a minimum amplitude (2/g or less).

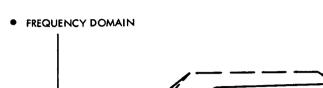
Precautions will be taken to avoid exceeding the specified vibration input at unexpected resonant frequencies. A resonant search will be made in each of the three mutually perpendicular axes. Any resonant frequency that is accompanied with a gain of 1.5 or greater will be recorded and noted in the test report.

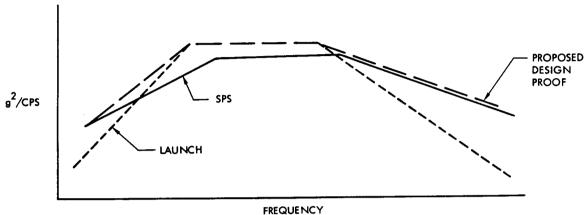
4.3.7.2.3 Combined Random and Sinusoidal Vibration. The test specimen will be subjected to a combined vibration test consisting of a sinusoidal waveform superimposed on a random waveform. The vibration will be applied successively in each of the three mutually perpendicular axes. The vibration levels and times are specified in Tables 4-5, 4-6, 4-7 and 4-8 and are graphically displayed in frequency and time domains in Figures 4-9 and 4-10. The sinusoidal sweep will be from 5 to 2000 cps and will be applied at a logarithmic rate. At the conclusion of the test, the test specimen will be inspected for any visible internal or external damage which could prevent the test item from meeting its operational reliability requirements. If a malfunction occurs during or after the environmental test, an internal inspection will be conducted to provide the required failure analysis data.

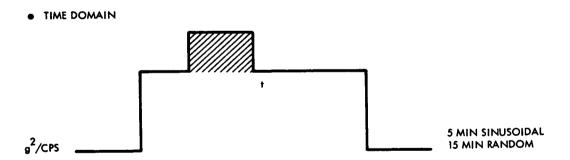








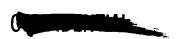


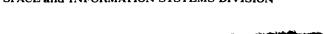


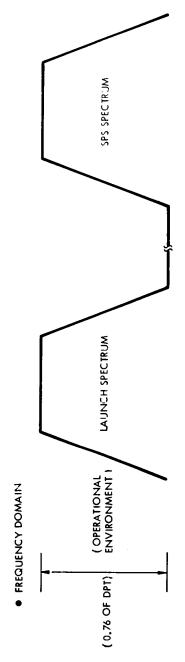
NOTE: DP TEST MARGIN = 1.33 (MAXIMUM OPERATING LEVEL)

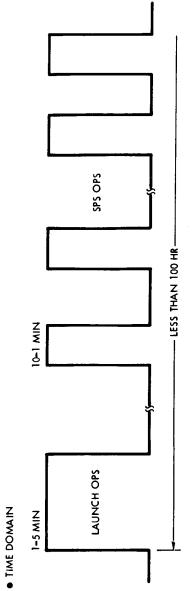
Figure 4-9. Design Proof Level











NOTE: OTHER ENVIRONMENTS MAY BE COMBINED WITH THIS TEST

Figure 4-10. Mission Simulation Life Application

4-39





Table 4-5. Vibration Test Criteria for Design Proof Tests

;

Vibration	Zone 1	Zone 2	Zone 3	Zone 4
Random (linear relates) to plot on log-log seals	5 to 50 cps linear increase from 0.007 to 0.122 $\rm g^2/cps$	5 to 50 cps, linear increase from 0.007 to 0.095 g ² /cps	5 to 50 cps, linear increase from 0.009 to 0.086 $g^2/{\rm cps}$	5 to 50 cps, linear increase from 0.004 to 0.025 $\rm g^2/cps$
	50 to 150 cps, constant at 0.122 g ² /cps	50 to 150 cps, constant at 0.095 g ² /cps	50 to 150 cps, constant at 0.086 g ² /cps	50 to 150 cps, constant at 0.025 g^2/cps
	150 to 2000 cps, linear decrease from 0.122 to to 0.035 g^2/cps	150 to 2000 cps, linear decrease from 0.095 g^2/cps to 0.015 g^2/cps	150 to 2000 cps, linear decrease from 0.086 g^2/cps to 0.058 g^2/cps	150 to 2000 cps, linear decrease from 0.025 $\rm g^2/cps$ to 0.005 $\rm g^2/cps$
Sinusoidal (g Peak) (linear relates to plot on log-log scale)	5 to 70 cps, linear increase from 0.3 g to 6 g	5 to 70 cps, linear increase from 0.3 g to 5 g	5 to 90 cps, linear increase from 0.25 g to 5 g	5 to 100 cps, linear increase from 0.22 g to 3 g
	70 cps to 2000 cps constant at 6 g	70 to 1000 cps, constant at 5 g	90 to 2000 cps, constant at 5 g	100 to 600 cps, constant at 3 g 600 to 2000 cps constant at 4 g
		1000 cps to 2000 cps constant at 4 g		
NOTE: (1) Test time 1	NOTE: (1) Test time 15 minutes/axis, random 5 minutes/axis sinusoidal.	nutes/axis sinusoidal.		

Vibration levels shown are for basic structure and for small rigidly mounted packages. For rigidly mounted packages with weights in excess of 10 pounds, correct vibration levels must be specifically established. (2)

Zone 1 - Forward and Aft C/M equipment compartments to Xa 910 on S/M Zone 2 - Crew Compartment Interior (3)

- Crew Compartment Interior - S/M and Adapter from Xa'910 to Xa 745

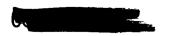
- Adapter - Aft of Xa 745 Zone 3

Iť

5 minutes in the equipment's most sensitive axis (determined during development). the most sensitive axis is not determined in the development test, vibrate the test

affect crew safety will be subjected to the vibration test described for a period of





Vibration Test Criteria for Design Proof Tests, Max q Abort Table 4-6.

Vibration	Zone 1	Zone 2
Random (linear relates to plot on log-log scale)	5 to 60 cps, linear increase from 0.006 to 0.155 g ² /cps	5 to 60 cps, linear increase from 0.006 $\rm g^2/cps$ to 0.13 $\rm g^2/cps$
	60 to 500 cps, constant at 0.155 g^2/cps	60 to 200 cps, constant at 0.13 g ² /cps
	500 to 2000 cps, linear decrease from 0.155 to 0.35 g^2/cps	200 to 2000 cps, linear decrease from 0.13 g^2/cps to 0.006 g^2/cps
Sinusoidal (g peak) (linear relates to plot	5 to 90 cps, linear increase 0.3 to 8 g	5 to 90 cps, linear increase 0.3 to 7 g
on rog-rog scare)	90 to 300 cps, constant 8 g	90 to 2000 cps, constant 7 g
	300 to 2000 cps, constant 12 g	
,		
Note: Equipment that must	Note: Equipment that must operate during or after a Max-q abort and the failure of which will	bort and the failure of which will

specimen in the axis of vehicle thrust.



Table 4-7. Vibration Test Criteria for Off-Limit Tests

22 J

Level	Criteria
Level 1	The random input spectrum of the design proof test (See Table 4-2) with (1) the random rms g level increased by 50 percent and (2) the sinusoidal input omitted
Level 2	The level shall be 175 percent of the random design proof rms g level.
Level 3	The level shall be 200 percent of the design proof level.
Level 4	The level shall be 225 percent of the design proof level.
Level 5	The level shall be 250 percent of the design proof level.
	Test time is 5 minutes per test level in the axis of vehicle thrust.







Table 4-8. Vibration Test Criteria for Mission Simulation-Life Tests

PART 1 Vibration	Zone 1	Zone 2	Zone 3
Random (linear relates to log-log plot)	5 to 50 cps linear increase from 0.008 to 0.93 $\rm g^2/cps$	5 to 50 cps linear increase from 0.007 to 0.072 g^2/cps	5 to 50 cps linear increase from 0.009 to 0.065 g ² /cps
	50 to 150 cps constant 0.093 g^2/cps	50 to 150 cps constant 0.072 g^2/cps	50 to 150 cps constant 0.065 g^2/cps
	150 to 2000 cps linear decrease from 0.093 to 0.005 g^2/cps	150 to 2000 cps linear decrease from 0.072 to 0.003 $\rm g^2/cps$	150 to 2000 cps linear decrease from 0.065 to 0.004 $\rm g^2/cps$
PART 2 Vibration	Zone 1	Zone 2	Zone 3
Random (linear relates to log-log plot)	5 to 100 cps linear increase from 0.007 $\rm g^2/cps$ to 0.04 $\rm g^2/cps$	5 to 100 cps linear increase from 0.007 $\rm g^2/cps$ to 0.031 $\rm g^2/cps$	5 to 100 cps linear increase from 0.009 $\rm g^2/cps$ to 0.053 $\rm g^2/cps$
	100 to 550 cps constant 0.04 g^2/cps	100 to 200 cps constant 0.031 g/cps	100 to 550 constant at 0.053 g ² /cps
	550 to 2000 cps linear decrease to $0.027g^2/\text{cps}$	200 to 2000 cps linear decrease to 0.011 $\rm g^2/cps$	550 to 2000 cps linear decrease to 0.038 $\rm g^2/cps$
NOTE: (1) Test time for Part I shall be	for Part I shall be 5 minutes		
(2) Test time f monitoring	(2) Test time for Part 2 shall consist of ten (10) one (1) minute bursts with adequate time between each burst for inspection and/or monitoring of test specimen.	e bursts with adequate time between	each burst for inspection and/or

(3) Test levels of packages in excess of 10 pounds must be specifically established.



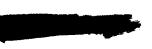


Table 4-9. Acoustic Test Criteria for Design Proof and Mission Simulation-Life Tests

*

		Locatio	Location and Levels (db)	1b)	
Frequency (cps)	Zone l External (vehicle)	Zone 3	Zone 1 (internal)	Zone 2	Zone 4
37.5 - 75	161 (+3,-0)	143 (+3, -0)	150 (+3,-0)	133 (+3, -0)	141 (+3,-0)
75 - 150	158 (+3, -0)	140 (+3,-0)	147 (+3,-0)	131 (+3, -0)	138 (+3, -0)
150 - 300	155 (+3,-0)	136 (+3, -0)	145 (+3,-0)	127 (+3,-0)	134 (+3,-0)
300 - 600	150 (+3,-0)	132 (+3, -0)	140 (+3,-0)	122 (+3,-0)	130 (+3,-0)
600 - 1,200	145 (+3,-0)	122 (+3,-0)	132 (+3, -0)	116 (+3,-0)	123 (+3,-0)
1,200 - 2,400	139 (+3,-0)	119 (+3,-0)	125 (+3, -0)	109 (+3, -0)	116 (+3,-0)
2,400 - 4,800	133 (+3, -0)	113 (+3, -0)	120 (+3,-0)	101 (+3,-0)	110 (+3,-0)
4,800 - 9,600	129 (+3, -0)	107 (+3,-0)	116 (+3, -0)	95 (+3, -0)	104 (+3,-0)
Over-all	168.5 (-3,+0)	148 (-3,+0)	158 (-3,+0)	140 (-3,+0)	147 (-3,+0)

The test may be omitted from phase B if there will be no fatigue as a result of acoustics. The levels shown will be the test levels for design proof tests A-1 and for life phase B. Note:

Time for test is 5 minutes.





Table 4-10. Acoustic Test Criteria for Abort-Essential Equipment

	I	Location and Levels (db)	
Frequencies	Zone 1	Zone 2	External
37.5 - 75	150 (+3,-0)	134 (+3, -0)	161 (+3,-0)
75 - 150	150 (+3,-0)	134 (+3,-0)	161 (+3,-0)
150 - 300	149 (+3,-0)	131 (+3, -0)	159 (+3,-0)
300 - 600	144 (+3,-0)	129 (+3,-0)	157 (+3,-0)
600 - 1,200	145 (+3,-0)	130 (+3, -0)	158 (+3,-0)
1,200 - 2,400	147 (+3,-0)	129 (+3, -0)	159 (+3,-0)
2,400 - 4,800	144 (+3, -0)	126 (+3,-0)	157 (+3,-0)
4,800 - 9,600	142 (+3,-0)	122 (+3, -0)	155 (+3,-0)
Over-all	158 (-3,+0)	142 (-3,+0)	171 (-3,+0)

This test is to be performed on equipment that must operate during or after an abort and the failure of which will affect crew safety. Note:

Test time is 1 minute.





4.3.8 Acoustics

4.3.8.1 General

The acoustic levels are delineated by zones in Tables 4-9 and 4-10.

4.3.8.2 Detail

- 4.3.8.2.1 Apparatus. The assembly will be placed within a reverberant test enclosure suitably formed and proportioned to produce, as closely as possible, a diffuse sound field, the sound energy density of which is very nearly uniform throughout the enclosure. Acute angles of adjacent walls will be avoided, whenever possible.
- 4.3.8.2.2 Mounting. The test specimen will be suspended in the test enclosure by means of a soft suspension device, such as soft springs or elastic cord. The natural frequency of all modes of suspension will be less than 25 cps. Every surface of the test specimen will be exposed to the sound field by centrally locating it in the test chamber. The test specimen volume will be no greater than 10 percent of the test chamber volume. If the test chamber is rectangular, no major surface of the test specimen will be installed parallel to a chamber wall.
- 4.3.8.2.3 Procedure. The sound pressure field will be measured with the test item mounted in the test chamber. Measurements will be made by using a microphone (or more than one as required) to measure the test specimen sound field in the proximity of each major dissimilar surface. The over-all sound pressure level will be within -3 db of the test level, and the time to conduct the survey or measurements will be less than 1/10 of the final test time. If possible, the test microphones will be moved over the test specimen surface at least 18 inches from the surface of the test article.

The over-all sound pressure level will be raised to the correct test level. The average sound pressure distribution around the test specimen will be uniform within 0 to +3 db of the desired value. The test time shall be as shown in Tables 4-9 or 4-10. If the unit under test is to operate while subjected to the acoustic environment, operating the test article will be monitored during this test. The test data will be compared to the preceding operational test at room ambient conditions. At the conclusion of the test, the test specimen will be inspected for any visible internal or external damage which could prevent the test item from meeting its operational and reliability requirements. It should be noted that an internal inspection may be impractical and may be omitted prior to operation of the unit. If a malfunction occurs during or after being subjected to the acoustic environment,







internal inspection will be performed as failure analysis requirements dictate. If the test specimen malfunctioned during the test but operated within functional requirements after removal of the acoustic environment, a single frequency sweep sound test will be performed to determine how the malfunction can be duplicated and its specific cause. In the application of the single frequency sound, the sound pressure field shall be measured as specified above. A single frequency sound at which a similar malfunction is observed shall be recorded and the results compared with the data obtained during the continuous spectrum test.

4.3.9 Humidity (Application Limited)

4.3.9.1 General

- 1. Level. 95 percent (+5, -0) percent, relative humidity
- 2. Temperature. 68 160 F
- 3. Time. 240 hours

4.3.9.2 Detail

Procedure per MIL-Std 810

4.3.10 Electromagnetic Interference

4.3.10.1 General

As in S&ID specification MC 999-0002B

4.3.10.2 Detail

As in S&ID specification MC 999-0002B

4. 3. 11 Sand and Dust (Application Limited)

4.3.11.1 General

As encountered in beach and coastal areas, particularly AMR

4.3.11.2 Detail

Procedure per MIL-Std 810



4.3.12 Salt Fog (Application Limited)

4.3.12.1 General

As encountered in beach and coastal areas, particularly AMR

4.3.12.2 Detail

Procedure per MIL-Std 810

4.4 COMBINED ENVIRONMENTAL TESTS

The combined environmental tests are those tests used to simulate actual spaceflight conditions as nearly as possible. The procedures will be applied as facilities and schedules permit. Particular attention is to be given those components where the failure mode analysis indicates a possible problem area.

4.4.1 Temperature-Vacuum

When a combined temperature, vacuum, and a dynamic test is to be performed, the test specimen will be stabilized at the required temperature, and the required pressure obtained. Then the dynamic test will be performed. If the unit is to be operated during the combined test operation, it will first be checked after the temperature has stabilized, and the required pressure has been achieved.

4.4.2 Vibration-Acceleration

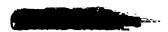
The test unit is to be mounted on a centrifuge-vibration test equipment. The test specimen is to be operated to determine compliance with its procurement specification. It will then be subjected to the acceleration environment. While undergoing this environment, it shall be operated if it will operate in service during acceleration. The vibration test will then be performed per paragraph 4.3.7. Note that equalization of the vibration equipment shall be accomplished while the equipment is subjected to the acceleration environment.

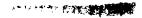
4.4.3 Temperature-Vibration

Salar 🍇

With the test unit mounted on the vibration test equipment and installed within the temperature chamber, the test specimen will be operated to determine compliance with the requirements of its procurement specification. It is then to be stabilized at the required test temperature. At this time the units operation must be checked again. After it has been determined that the temperature environment does not cause a failure, the combined temperature-vibration test will be performed, as required, for vibration alone in paragraph 4.3.7.







5.0 SUBSYSTEM QUALIFICATION TESTS

This section presents the individual sybsystem qualification test plans, and features the variant physical characteristics and unique mission requirements of each subsystem. Each test plan has been designed to verify system capability to perform within design specification requirements for a sufficient length of time to fulfill mission operational requirements. Another test plan objective is to demonstrate repeatability of functional and quality characteristics. Each test plan has been made optimum to qualify the respective equipment in ground simulation within the program constraints as defined in previous sections of this volume. Reliability assessment models, listings of system parameters for qualification testing, and qualification test schedules are defined within the limitations of information available at this issue of the Apollo General Test Plan. Schedules will be revised to reflect the current program direction and requirements.

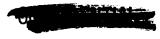
5.1 SERVICE PROPULSION SYSTEM

5.1.1 Scope

The qualification test plan for the service propulsion system will include environmental tests on components and the complete engine. It will consist of a sea level phase and a simulated altitude phase. Each test will employ an engine equipped with a thrust chamber that had been fired for a duration which did not exceed 30 seconds (accumulated during acceptance testing). Additional tests will be conducted under abnormal conditions and environments for extended periods to exhibit equipment design margin capabilities. Selection of the number of engine tests is based on the requirement to assess engine capabilities under simulated mission environments and off-limit operating conditions.

5.1.2 Reliability Assessment Model

Figure 5-1 depicts the reliability assessment model for the service propulsion system. The model will aid in establishing test requirements and in programming the collection of data for the assessment of reliability by illustrating the interfaces of system components and subassemblies.







5.1.3 Criticality and Hardware Requirements

5.1.3.1 Service Propulsion Engine

Table 5-1 designates the criticality class, as defined in subsection 2.4, for the components of the service propulsion engine. The table enumerates the hardware requirements for a minimum qualification program as established in subsection 2.5. The location of the components in the spacecraft is indicated by spacecraft zone numbers as defined in subsection 4.2.

Component	S/C Zone	Criticality	Required Hardware
Thrust chamber	3	1	24
Valves	3	1	13
Actuator	3	1	14
Mount	3	1 .	11
Lines	3	1	11
Nozzle	4	1	6
Injector	3	1	12

Table 5-1. SPS Engine Parameters for Qualification Testing

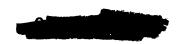
5.1.3.2 Propellant Feed

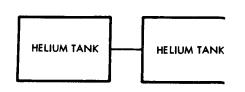
Table 5-2 designates the criticality class, as defined in subsection 2.4, for the components of the service propulsion system propellant feed. The table enumerates the hardware requirements for a minimum qualification program as established in subsection 2.5. The distribution of the hardware through the subsystem qualification test phases, as described in subsection 2.3, is shown. The location of the components in the spacecraft is indicated by spacecraft zone numbers as defined in subsection 4.2.

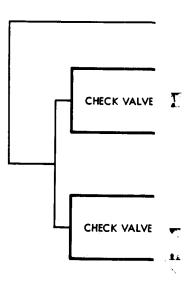
5.1.4 Qualification Test Schedule

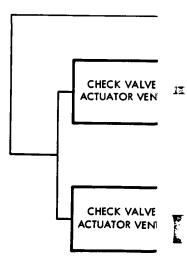
5.1.4.1 Service Propulsion Engine

Figure 5-2 displays the qualification test schedule for the service propulsion system engine and defines the test utilization of the hardware enumerated in Table 5-1. The specific test levels to be applied in

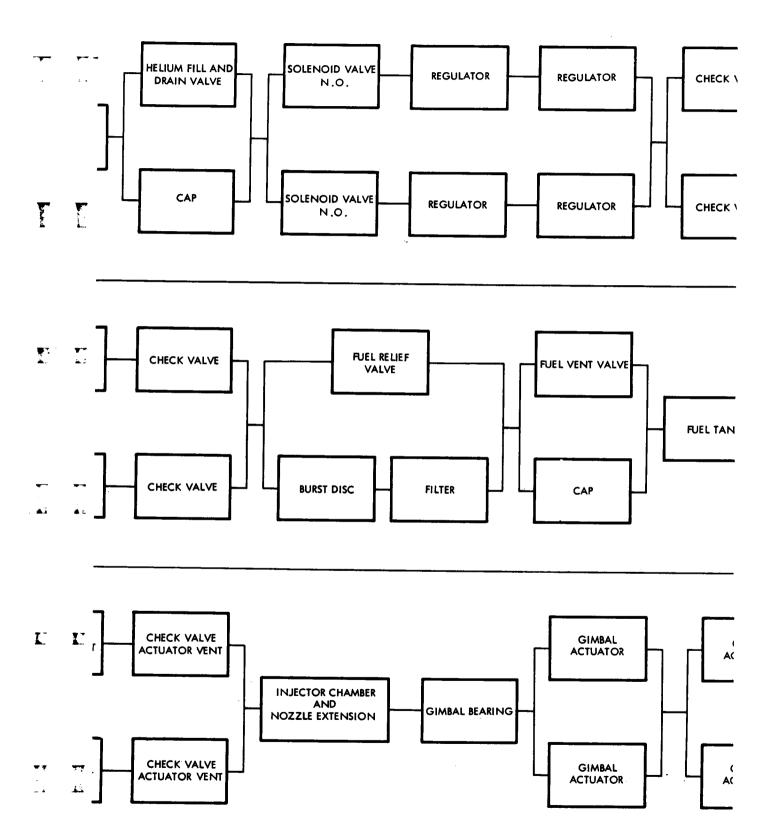


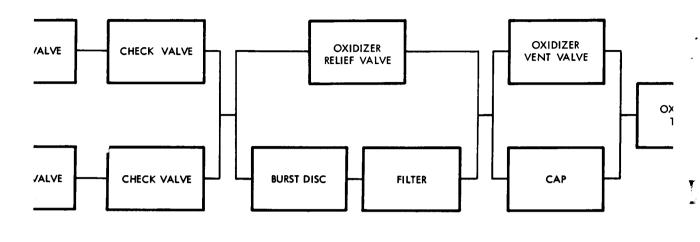


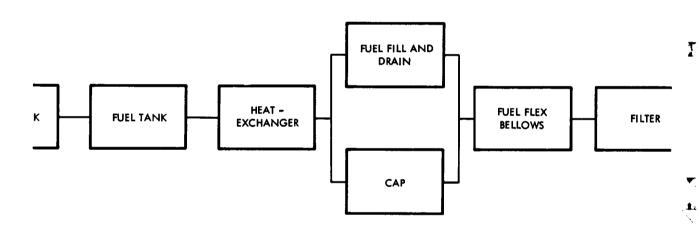


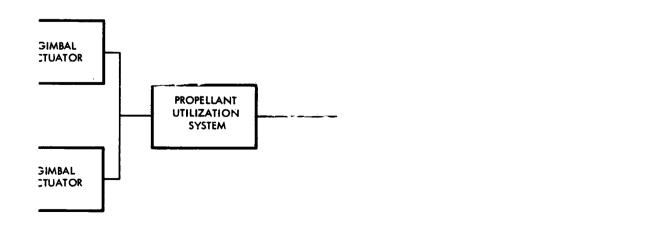


Ĺ



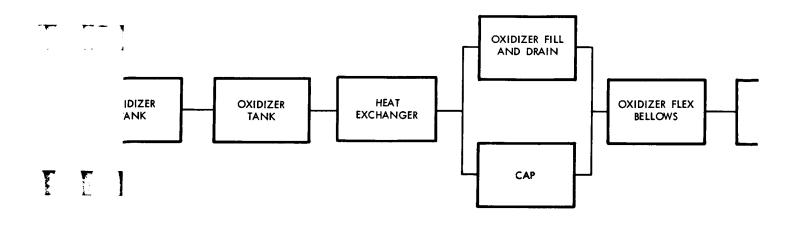


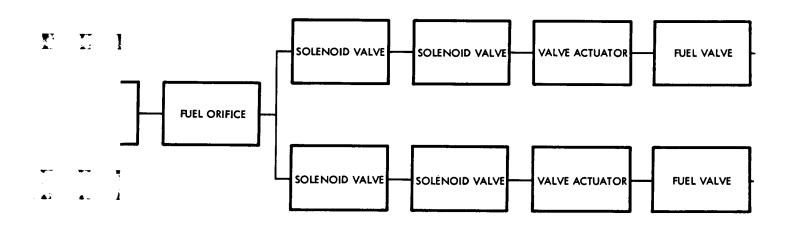




Z

I





L L I

पत्र प्रमु

E I

Ģ

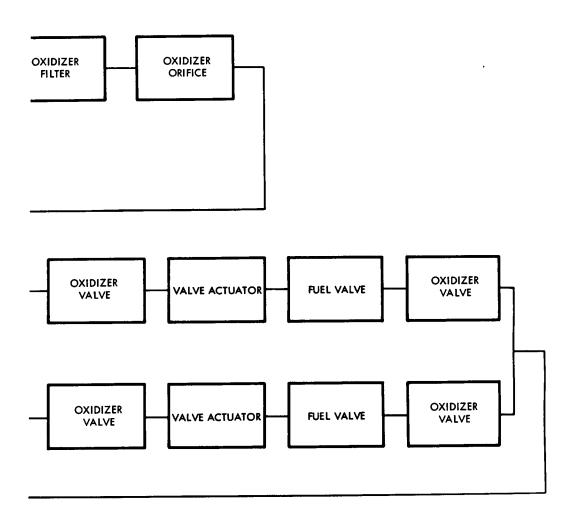


Figure 5-1. SPS Reliability Assessment Model

5-3,5-4



K

I







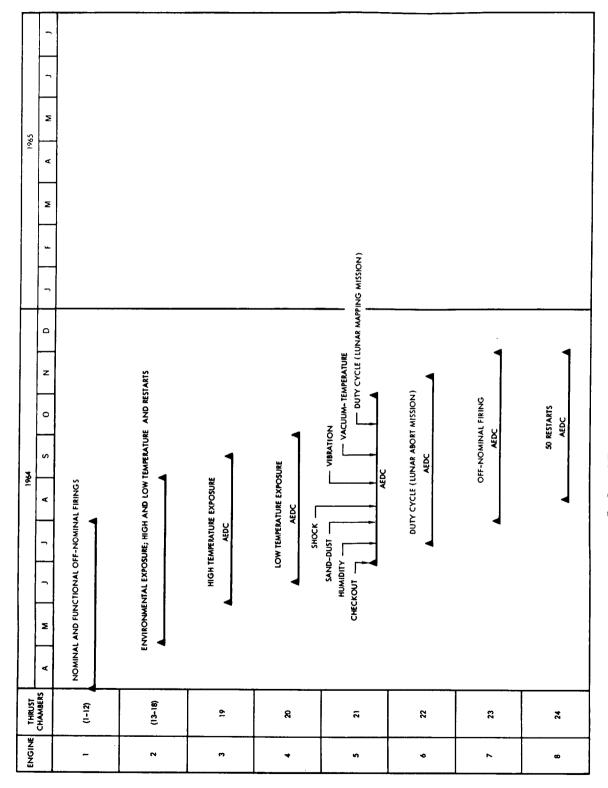
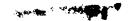


Figure 5-2. SPS Engine Test Schedule





qualification testing are found in the tables of environmental test criteria in subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. The zone number is given in Table 5-1.

Table 5-2. SPS Propellant Feed Parameters for Qualification Testing

			Required		cation Test Distribution
Component	S/C Zone	Criticality	Hardware	Qual	Off- Limit
Heat exchangers	3	1	4	4	2
Disconnects	3	3	4	4	2
Connectors	3	1	4	4	2
Valves	3	3	4	4	2
Regulators	3	3	4	4	2
Quantity Gaging and Indicator Subsystem	1	1	4	4	2
Tanks (3 types)	1	1	4	4	2

5.1.4.2 Propellant Feed

Figure 5-3 displays the qualification test schedules for the SPS propellant feed components and defines the test utilization of the hardware enumerated in Table 5-2. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. The zone number is given in Table 5-2.

5.2 REACTION CONTROL SYSTEM

5.2.1 Scope

Qualification tests on the reaction control subsystem engines conform to the general requirements of MIL-E-5151 and include the following:

- 1. Calibration tests
- 2. Environmental tests





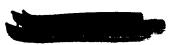


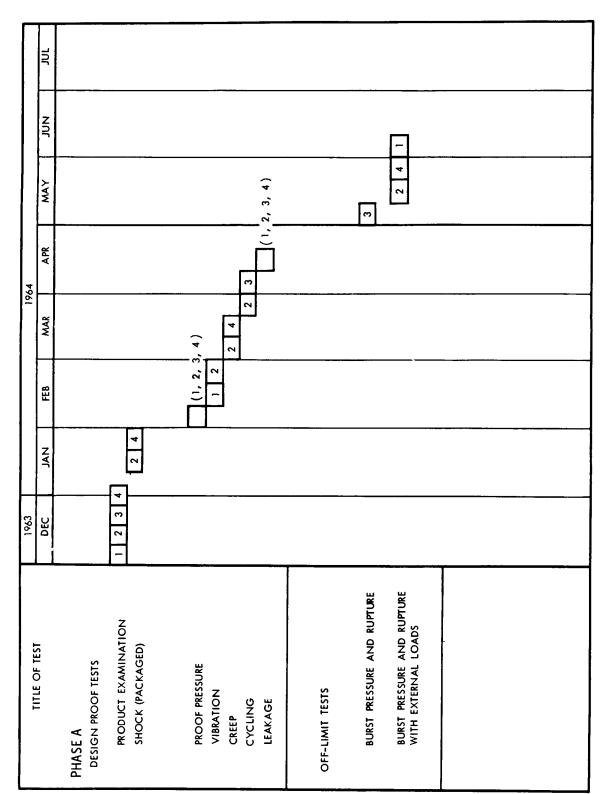


	ITEAA								WEE	K NO.										
COMPONENTS	NO.	1	2	3	4	5	6	7	8	9	10	0	11	12		13	14	15	16	17
HEAT EXCHANGER, OXIDIZER HEAT EXCHANGER, FUEL	1-4	1	2	6	8	9	17	T	12	1		11	HU ELE EXI ACI VIB TEA VAI	PLOSI CELEI BRATIC OUST MPERA MPERA CUUN	ANCE TY DMAG IVE A RATIC DN TICS ATURE A	METIC TMOSI ON , HIG	C IN'		RENCE	
VALVE, CHECK	1 2 3 4	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	18	7 1	6 1	2						13 14 15 16 17	VAC VIB VIB PERI SUR	CUUN RATIC RATIC FORM IGE PI	A, TE ON, ON, MANC RESSU	MPERA ACCEL TEMPEI E	ERAT RATU	NOIT		
VALVE, RELIEF, HELIUM	1 .2 3 4	1 2 1 2 1 6	2 6	3	5 1	0 i	6 1 7 1 2	2	16							•				
REGULATOR, PRESSURE, HELIUM	1 2 3 4	1 6 1 6 1 1:	3 1	5				2												
VALVE, SOLENOID, HELIUM	1 2 3 4	1 3 1 1:	3 4 5 8		6 .		8 9	\Rightarrow	6	12										
GROUND HALF DISCONNECT, FILL, HELIUM DISCONNECT, TEST, HELIUM DISCONNECT, FILL, OXIDIZER DISCONNECT, VEST, OXIDIZER DISCONNECT, VENT, OXIDIZER DISCONNECT, FILL, FUEL DISCONNECT, TEST, FUEL DISCONNECT, VENT, FUEL AIRBORNE HALF	1 & 2 3 & 4 1 & 2 3 & 4	1] 2	18	18		?] 1	7	16	1	5 1:	2									
CONNECTOR, FUEL CONNECTOR, OXIDIZER	1 - 4	1	18	J:	2 .	6 1	2										•			-
SPS QUANTITY GAGING AND INDICATOR SUBSYSTEM	1 - 4	1]	18] ?	2 16	5 11	7	6	5	10	Γi	2								

Figure 5-3. SPS Propellant Feed Components (Less Tanks) Qualification Test Schedule (Sheet 1 of 2)







SPS Propellant Feed Components (Less Tanks) Qualification Test Schedule (Sheet 2 of 2) Figure 5-3.





- 3. Electromagnetic interference and susceptibility tests
- 4. Mission simulation life tests

The number of test engines is predicated on the requirement to assess compliance with the procurement specification in normal and off-limit modes of operation. The number of qualification test samples for the components of the propellant feed subsystem is based on the criticality index, limited life requirements, service life considerations, and the multiple use of the same test articles.

5.2.2 Reliability Assessment Model

5.2.2.1 Command Module

Figure 5-4 depicts the reliability assessment model for the C/M RCS. The model will aid in establishing test requirements and in programming the collection of data for the assessment of reliability by illustrating the interrelationship of system components.

5.2.2.2 Service Module

Figure 5-5 depicts the reliability assessment model for the S/M RCS. The model will aid in establishing test requirements and in programming the collection of data for the assessment of reliability by illustrating the interrelationship of system components.

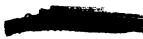
5.2.3 Criticality and Hardware Requirements

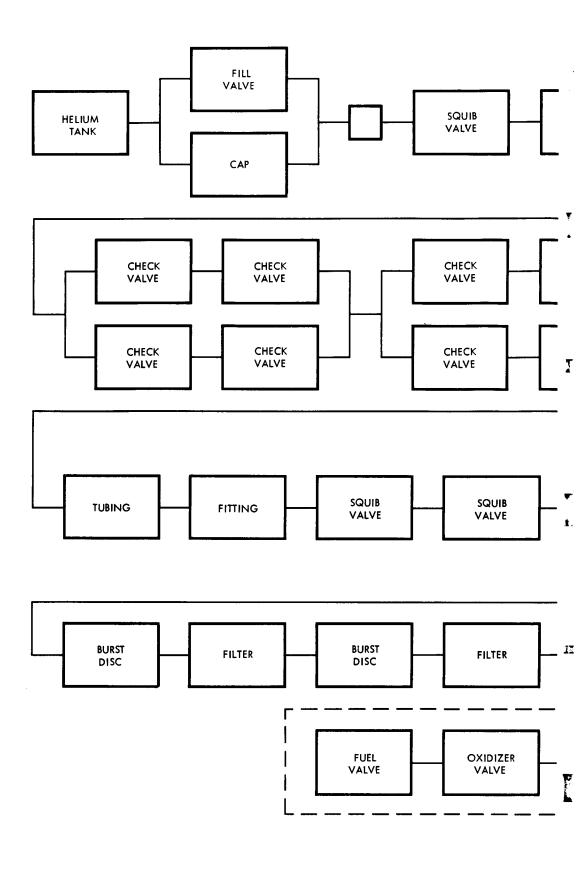
5.2.3.1 Command Module

5.2.3.1.1 Engine. Table 5-3 designates the criticality class, as defined in subsection 2.4, for the components of the C/M rocket engine. The table enumerates the hardware requirements for a minimum qualification program as established in subsection 2.5. The location of the components in the spacecraft is indicated by spacecraft zone numbers as defined in subsection 4.2.

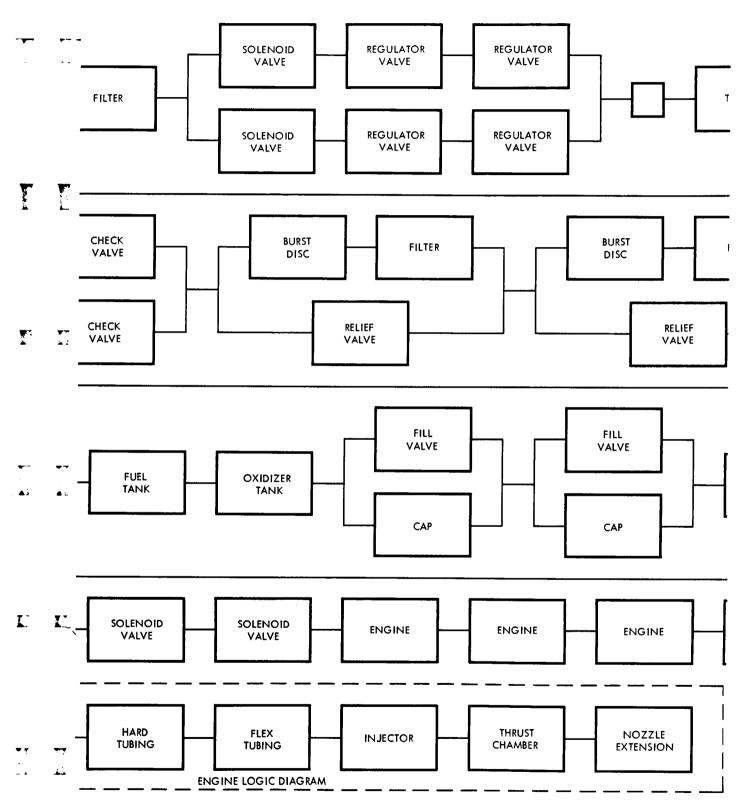
Table Jed. Clim respende farameters for challneamon lesti	Table 5-3.	C/M RCS	Engine Parameters f	or Qualification Testing
---	------------	---------	---------------------	--------------------------

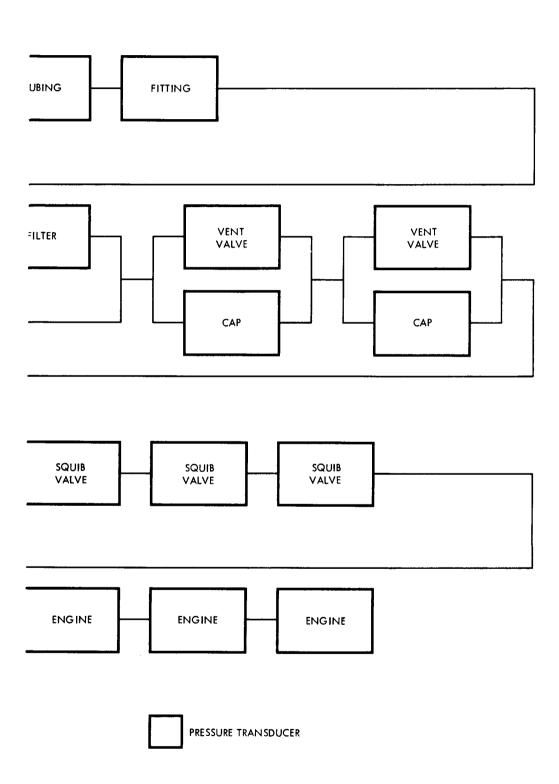
Component	S/C Zone	Criticality	Required Hardware
Thrust chamber	1	2	16
Injector	1	2	14
Fuel valve	1	2	14
Oxidizer valve	1	2	14





į





igure 5-4. C/M RCS Reliability Assessment Model

- 5-11,5-12 -

Ţ





■ 1000年 L 二次発験



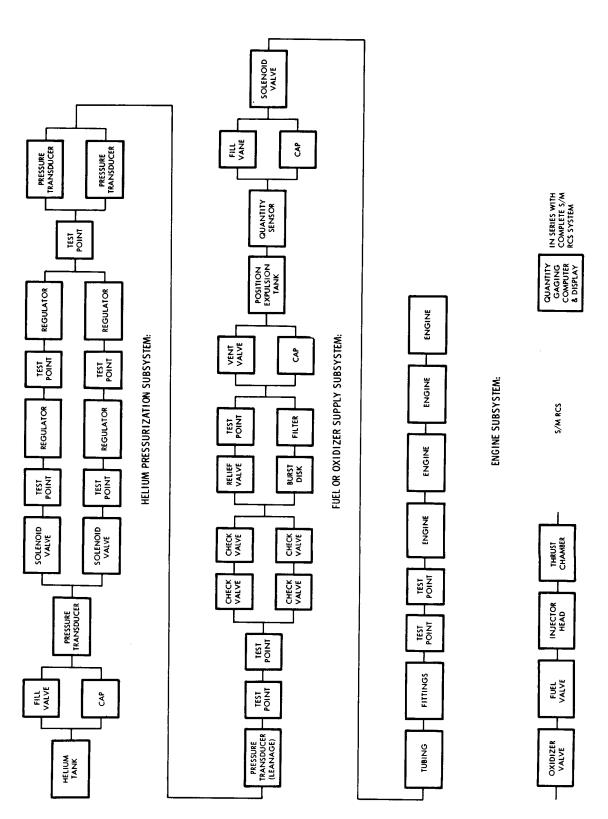
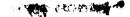


Figure 5-5. S/M RCS Module Configuration





5.2.3.1.2 Propellant Feed. Table 5-4 designates the criticality class, as defined in Section 2.4, for the components of the C/M RCS Propellant Feed. The table enumerates the hardware requirements for a minimum qualification program, as established in Section 2.5. The distribution of the hardware through the subsystem qualification test phases, as described in Section 2.3, is shown. The location of the components in the spacecraft is indicated by spacecraft zone numbers, as defined in Section 4.2.

Table 5-4. C/M RCS Propellant Feed Parameters for Qualification Testing

			Required	Qualifi Phase		1
Component	S/C Zone	Criticality	Hardware	A - 1	A-2	В
Burst Disc	1	2	4	2	1	1
Squib valve	1	2	5	2	1	2
Disconnect	1	3	6	2	1	3
Valves, solenoid check or relief	1	3	8	2	2	4
Regulator	1	3	4	1	1	2
Tanks (3 types)	1	2	6	6	6	0

5.2.3.2 Service Module

5.2.3.2.1 Engine. Table 5-5 designates the criticality class, as defined in subsection 2.4, for the components of the S/M rocket engine. The table enumerates the hardware requirements for a minimum qualification program as established in subsection 2.5. The location of the components in the spacecraft is indicated by spacecraft zone numbers as defined in subsection 4.2.

Table 5-5. S/M RCS Rocket Engine Parameters for Qualification Testing

Component	S/C Zone	Criticality	Required Hardware
Thrust chamber	1	3	13
Injector	1	3	9
Fuel valve	1	3	10
Oxidizer valve	1	3	10





5.2.3.2.2 Propellant Feed. Table 5-6 designates the criticality class, as defined in subsection 2.4, for the components of the S/M RCS propellant feed. The table enumerates the hardware requirements for a minimum qualification program as established in Section 2.5. The distribution of the hardware through the subsystem qualification test phases, as described in subsection 2.3, is shown. The location of the components in the spacecraft is indicated by spacecraft zone numbers, as defined in subsection 4.2.

Table 5-6. S/M RCS Propellant Feed Parameters for Qualification Testing

			D : 1	Qualification Test Phase Distribution		
Component	S/C Zone	Criticality	Required Hardware	A - 1	A-2	В
Disconnect	1	3	6	2	1	3
Flex hose	1	3	4	1	1	2
Regulator	1	3	6	2	1	3
Quantity gaging	1	3	3	ì	1	. 1
Valve	1	3	4	1	1	2
Tanks (3 types)	1	3	5	5	5	0

5.2.4 Qualification Test Schedule

5.2.4.1 Command Module

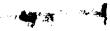
5.2.4.1.1 Engine. Figure 5-6 displays the qualification test schedule for the C/M RCS engines and defines the test utilization of the hardware enumerated in Table 5-3. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. These zone numbers are given in Table 5-3.

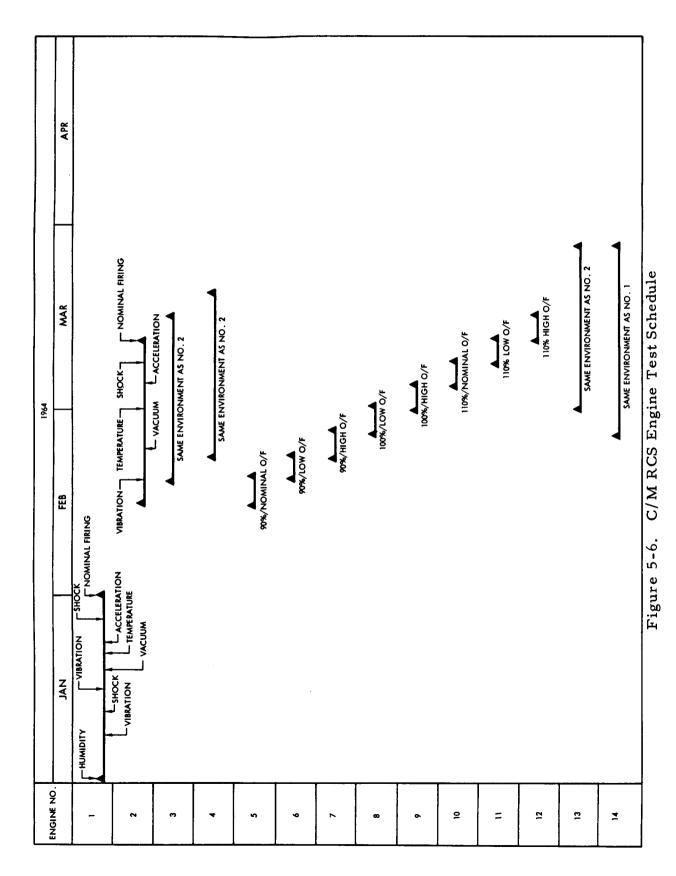
5.2.4.1.2 Propellant Feed. Figure 5-7 displays the qualification test schedule for the C/M RCS propellant feed and defines the test utilization of the hardware enumerated in Table 5-4. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. These zone numbers are given in Table 5-4.















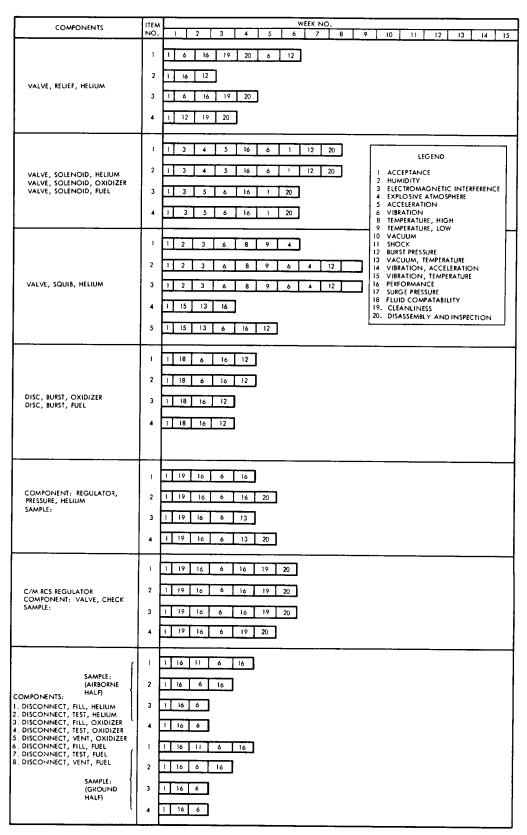
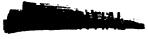


Figure 5-7. C/M RCS Propellant Feed (Less Tanks)
Qualification Test Schedule (Sheet 1 of 2)







	1963		61	1964	
TITLE OF TEST	EC	NA NA	FEB	MAR	씱
	1 2 3 4	1 2 3 4	1 2 3 4	1 2 3 4	1 2 3 4
PHASE A DESIGN PROOF TESTS CLIMATICS					
ACCEPTANCE HUMIDITY	NO. 2	NO. 1, 2, 3 & 4			
MISSION MAXIMUM PROOF PRESSURE LEAKAGE SLOSH ACCELERATION VIBRATION VACUUM FLUID COMPATIBILITY CYCLING		NO. 1 & 2 NO. 3 & 4			
OFF-LIMIT VIBRATION CYCLING BURST			NO. 1 & 2	3&4	

Figure 5-7. C/M RCS Propellant Feed (Tanks) Qualification Test Schedule (Sheet 2 of 2)





5.2.4.2 Service Module

5.2.4.2.1 Engine. Figure 5-8 displays the qualification test schedule for the S/M RCS engines and defines the test utilization of the hardware enumerated in Table 5-5. Qualification tests will use eight complete engines and four replacement thrust chambers. The thirteenth thrust chamber will be used for component testing. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. These zone numbers are given in Table 5-5.

5.2.4.2.2 Propellant Feed. Figure 5-9 displays the qualification test schedules for the S/M RCS propellant feed components and defines the test utilization of the hardware enumerated in Table 5-6. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. These zone numbers are given in Table 5-6.

5.3 LAUNCH ESCAPE SYSTEM

5.3.1 Scope

Qualification testing of launch escape, tower jettison, and pitch control motors will be accomplished on representative production samples of units and associated components to determine compliance with functional and performance specification requirements. The number of test motors is based on the requirements deemed necessary to assess compliance with the specification. The test program will subject the equipment to a series of environments as anticipated in service.

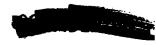
5.3.2 Reliability Assessment Model

Figure 5-10 depicts the reliability assessment model for the LES. The model will aid in establishing test requirements and in programming the collection of data for the assessment of reliability by illustrating the interrelationship of system components.

5.3.3 Criticality and Hardware Requirements

Table 5-7 designates the criticality class, as defined in subsection 2.4, for the LES rocket motors. The table enumerates the hardware requirements for an optimum qualification program as established in subsection 2.5.







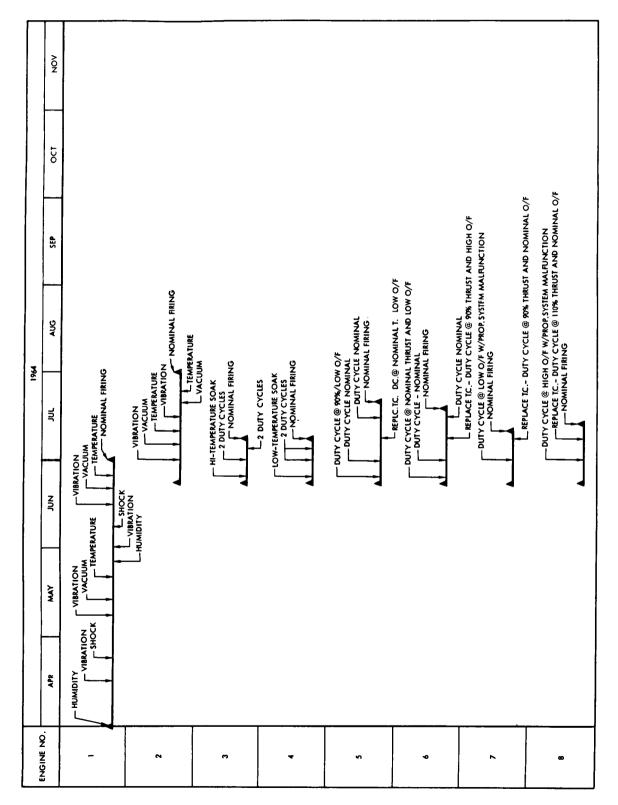


Figure 5-8. S/M RCS Engine Test Schedule

4.53mg 1.04**mg**

Ç





2. 李龙龙 · 海水学

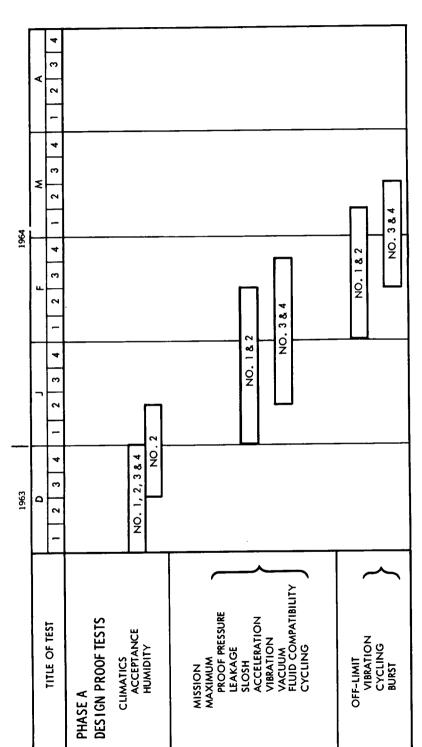
COMPONIENTE	ITEM							_	w	VEEK N	ю.									
COMPONENTS	NO.	1	2	3	4	5	6	7	8	9	10	11	1	2	13	14	1:	5	16	17
	1	iI	6	15	16	18	12										-			
FLEX HOSE	2	1	6	9	16	18	12													
	3	ij	6	15	16	17	12													
	4		6	9	16	12														
, GROUND HALF	1	1]	16	11	6	16														
	2	1	16	6	16															
DISCONNECT, FILL, HELIUM DISCONNECT, TEST, HELIUM	3 1	1	16	6																
DISCONNECT, FILL, OXIDIZER DISCONNECT, TEST, OXIDIZER DISCONNECT, VENT, OXIDIZER	4	1	16	6																
DISCONNECT, FILL, FUEL DISCONNECT, TEST, FUEL DISCONNECT, VENT, FUEL AIRBORNE	1	1	16	11	6	16														
HALF	2	1	16	6	16															
	3	ıI	16	6																
	4	1 [16	6											LEG	GEND				
	1	1	3	4	5	16	6	1 1	12 2	20		2	2 HL	CEPT	TY	E GNET	IC IN	TERFF	RENO	CE
VALVE, SOLENOID, HELIUM VALVE, SOLENOID, FUEL	2	ı]	3	4	5	16	6	1 1	2 2	20		5	EX AC		IVE A	OMTA				
VALVE, SOLENOID, OXIDIZER	3	1	3	5	6	16	1 2	<u> </u>				5	TE	MPERA	ATUF ATUF	E, HK				l
	4	1	3	5	6	16	1 2	<u>□</u>				112	SH BU	OCK RST P	RESS	URE EMPÉR	ATUR	Ē		
	1	1	19	16	6	16						14	VII	BRATI	ОN, ОN,	TEMP	LERA	TION		
S/M RCS SOLENOID VALVES REGULATOR, PRESSURE, HELIUM	2	1	9	16	6	16	20					18	FL	RGE F JID C EANL	OM	PATIBI	LITY			
	3					13	_									Y&I	NSPEC	1017	4	
	4	<u> </u>	19	16	6	13 :	20						···							
	1	1]	6	16	19	20	6 I	2												
S/M RCS REGULATOR VALVE, RELIEF, HELIUM	2			12																
	3					20														
	4	1 1	2	19	20															
·	۱	1 1	9	16	6	16 1	9 2	0												
S/M RCS RELIEF VALVE VALVE, CHECK	2			16	6	16 1	9 2	<u> </u>												
	3						9 2	0												
	4	1 1	9	16	6	19 2	<u></u>													
	1	1	3	4 6	10		5 16													
PROPELLANT QUANTITY GAUGING	2		3	4 6			<u>6</u>													
	3	1]_	3	4 6	8	11	15 16													

Figure 5-9. S/M RCS Propellant Feed (Less Tanks)
Qualification Test Schedule (Sheet 1 of 2)



and the same of th



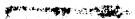


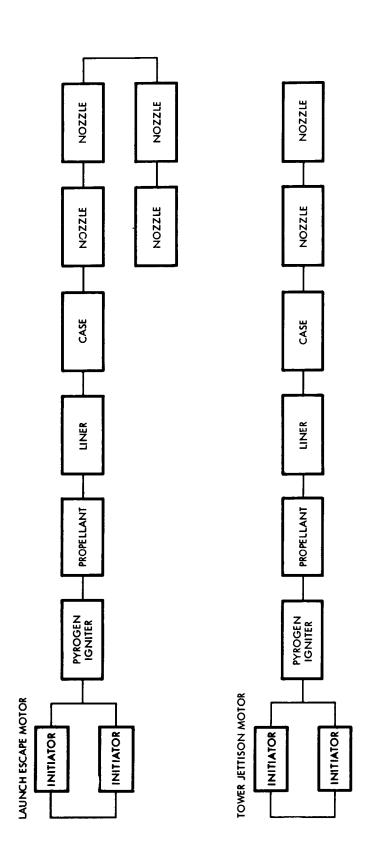
S/M RCS Propellant Feed (Tanks) Qualification Test Schedule (Sheet 2 of 2) Figure 5-9.





The same of





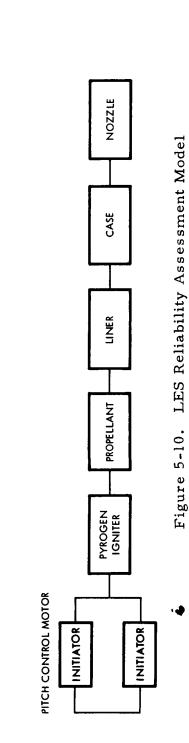










Table 5-7. LES Rocket Motor Criticality and Hardware Requirements

Criticality	Number of Units Required
2	28
2	28
3	30
1	118
	2 2

NOTE: The additional two pitch control motors are required for acceleration tests. See Table 5-9.

5.3.4 Qualification Test Schedule

5.3.4.1 Tower Jettison Motor

Figure 5-11 displays the qualification test schedule for the LES tower jettison motor. Table 5-8 programs the test articles enumerated in Table 5-7 in accordance with the test schedule. Since the test utilization of the launch escape motor hardware is similar to that of the tower jettison motor, Table 5-8 is also applicable to the launch escape motor.

5.3.4.2 Launch Escape Motor

Figure 5-12 displays the qualification test schedule for the LES launch escape motor. The schedule defines the test utilization of the hardware enumerated in Table 5-7 in accordance with the test program of Table 5-8.

5.3.4.3 Pitch Control Motor

Figure 5-13 displays the qualification test schedule for the LES pitch control motor. The schedule defines the test utilization of the hardware enumerated in Table 5-7 in accordance with the test program of Table 5-9.

5.3.4.4 Hot Wire Igniter Cartridge

Table 5-10 defines the test utilization of the hardware enumerated in Table 5-7. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in Section 4.2.



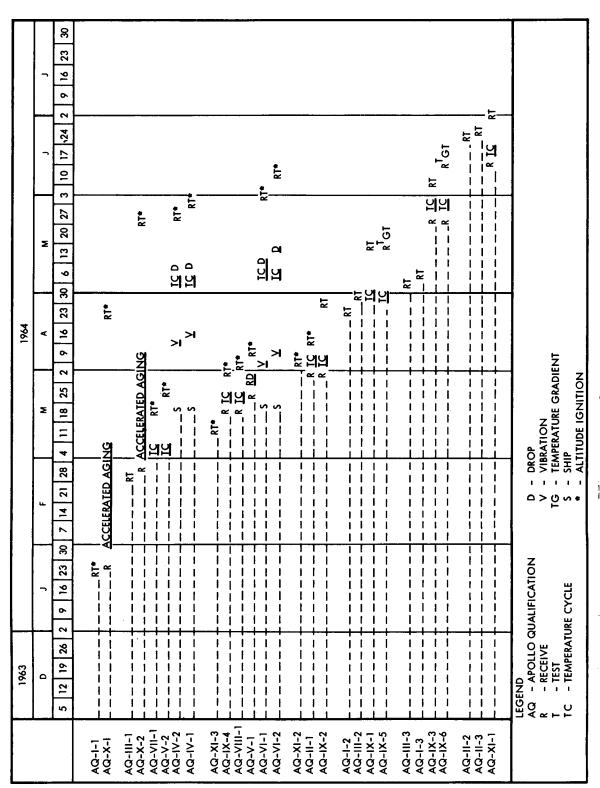


Figure 5-11. LES Tower Jettison Motor Qualification Test Schedule

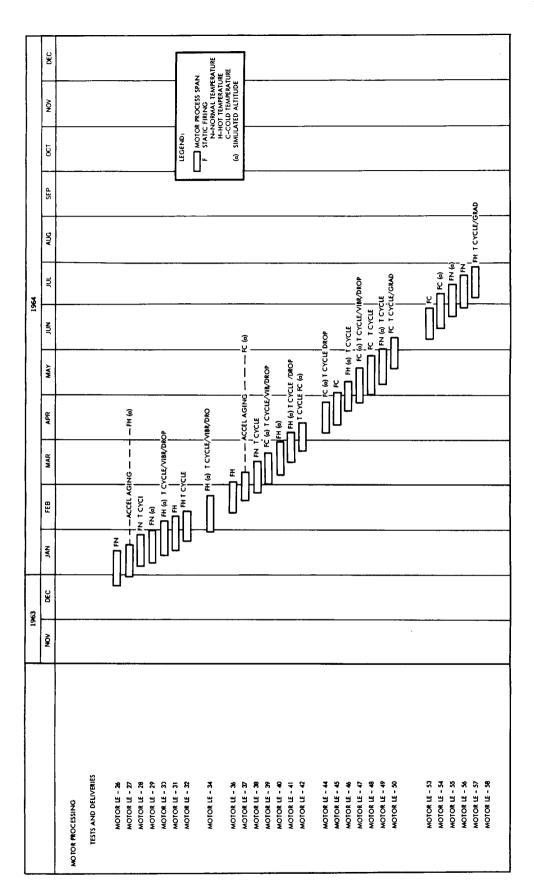


Figure 5-12. Launch Escape Motor Qualification Test Schedule

5-27, 5-28

SID 62-109-3

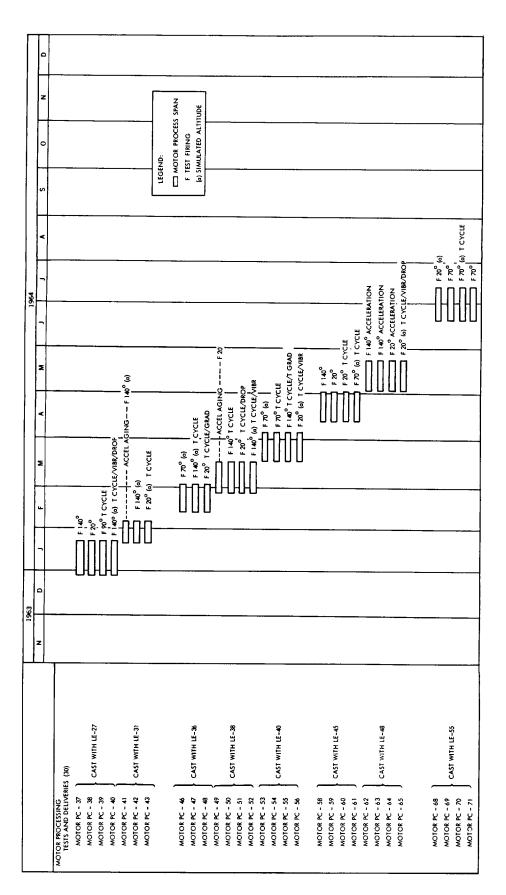


Figure 5-13. Pitch Control Motor Qualification Test Schedule







Table 5-8. Program for Test Articles, Tower Jettison and Launch Escape Motors

			Tes		up ar		mber	of Mo	tors		
	I	II	III	IV	V	VI	VII	VIII	IX	X	XI
	(3)	(3)	(3)	(2)	(2)	(2)	(1)	(1)	(6)	(2)	(3)
Statistical firing											
High temperature	2								1		
Normal temperature		2							1		1
Low temperature			2						1		
Sequential treatment											
Temperature cycle		1		2	2	2	1	1	6		1
Vibration											
High temperature				2							
Low temperature						2					
Drop											
High temperature				2							i
Normal temperature					2						
Low temperature						2					
Accelerated age										2	
Altitude firing											
High temperature	1			1	1	1		1		1	
Normal temperature		1							1		2
Low temperature			1	1	1	1	1			1	
Temperature gradient											
High to low									1		
Low to high									1		

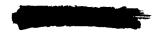


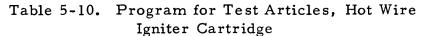




Table 5-9. Program for Test Articles, Pitch Control Motor

			Тє	est C	rou	p and	d Nun	nber	of M	otor	s	
	I	II	III	IV	V	VI	VII	VIII	IX	Х	XI	XII
	(3)	(3)	(3)	(2)	(1)	(2)	(1)	(1)	(6)	(2)	(3)	(3)
Statistical firing												
High temperature	2								1			
Normal temperature		2							1		1	
Low temperature			2						1			
Sequential temperature												
Temperature cycle		1		2	1	2	1	1	1		1	
Vibration												
High temperature				2								
Low temperature						2						
Drop												
High temperature				2								
Normal temperature					1							
Low temperature												
Acceleration												
High temperature												2
Low temperature												.1
Accelerated age										2		
Altitude firing												
High temperature	1			1	1	1		1		1		
Normal temperature		1							1		2	
Low temperature			1	1		1	1			1		
Temperature gradient												
High to low									1			
Low to high									1			





		Τe	st Se	quer	ice a	nd N	0. 0	f Uni	ts	
Test	20	20	20	10	10	20	4	4	6	4
Acceptance	1	1	1	1	1	1	1	1	1	1
No fire current	2	2	2	2	2	2	2	2	2	2
Static sensitivity	3	3	3	3	3	3	3	3	3	3
Dielectric strength	4	4	4	4	4	4	4	4	4	4
Humidity	5									
Eight-foot drop				5						
Salt spray						5				
Vibration and temperature	6	5	5						,	
High temperature		6								
Low temperature			6							
Fire - room temperature				6	6		6	6	6	6
Fire - high temperature	7	7								
Fire - low temperature			7			6				
Vibration (off limit)					5					
Jolt							5			
Jumble								5		į
Forty-foot drop									5	
High temperature tolerance										5

5.4 EARTH LANDING SYSTEM

5.4.1 Scope

The purpose of the ground qualification test program is to qualify the earth landing system by subjecting components to mission environments; i.e., humidity, high and low temperature vacuum, vibration, acceleration, and shock. These ground tests are in addition to the drop test program.

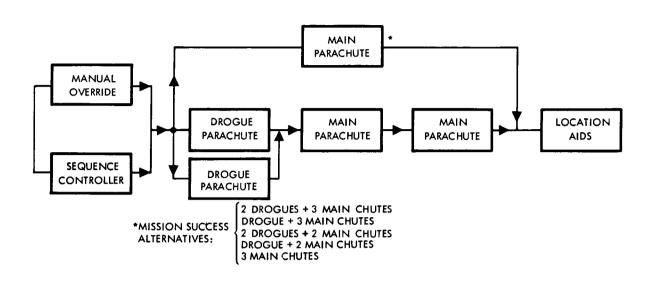


Figure 5-14. ELS Reliability Assessment Model

5.4.2 Reliability Assessment Model

Figure 5-14 depicts the reliability assessment model for the ELS. The model will aid in establishing test continuity and in programming the collection of data for the assessment of reliability by illustrating the interactions of the system components and subassemblies.

5.4.3 Criticality and Hardware Requirements

Table 5-11 designates the criticality class, as defined in subsection 2.4, for the components of the ELS. The table enumerates the hardware requirements for a minimum qualification program as established in subsection 2.5. The distribution of the hardware through the subsystem qualification test phases, as described in subsection 2.3, is shown in the respective qualification test schedule. The location of the components in the spacecraft is indicated by spacecraft zone numbers, as defined in subsection 4.2.

5.4.4 Qualification Test Schedule

5.4.4.1 Drogue and Main Parachute Disconnects

Figure 5-15 displays the qualification test schedule for the ELS parachute disconnects and defines the test utilization of the hardware enumerated in Table 5-11. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in subsection 4.2 and

STREET, STREET





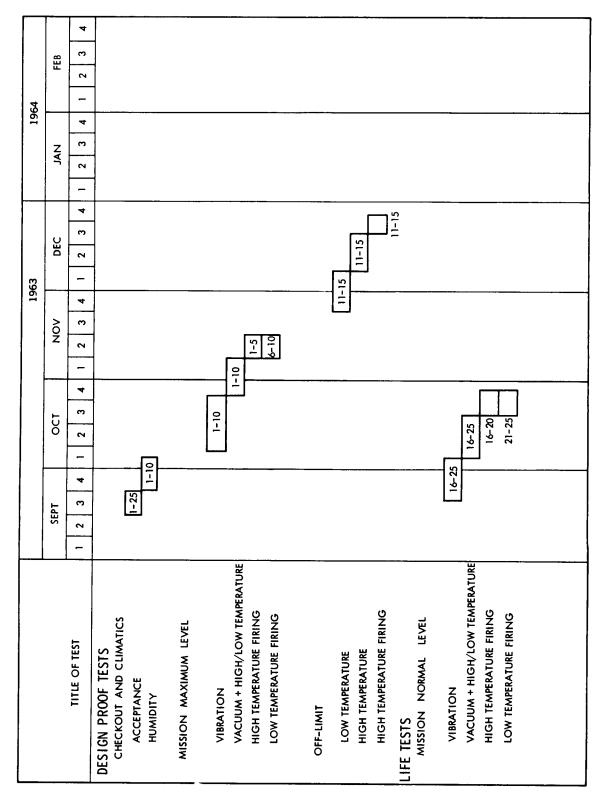


Figure 5-15. ELS Main Parachute Disconnects Qualification Test Schedule



DOMESTICAL

Table 5-11. ELS Parameters for Qualification Testing

·	S/C Zone	Criticality	Required Hardware
Main chute disconnect	1	3	25 25
Drogue chute disconnect	<u> </u>	3	45
Drogue chute mortar	1	3	4
Pilot chute mortar	1	3	4
Sequence controller	1	3	4 ·
Parachute fabric sample	1	3	25 of each
•			specimen
Main cluster harness assy	1	3	44
Reefing line cutter	1	3	50

are a function of the zone location of the equipment in the spacecraft. These zone numbers are given in Table 5-11.

5.4.4.2 Drogue and Pilot Mortars

Figure 5-16 displays the qualification test schedule for the ELS mortars and defines the test utilization of the hardware enumerated in Table 5-10. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. These zone numbers are given in Table 5-11.

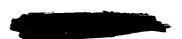
5.4.4.3 Sequence Controller

Figure 5-17 displays the qualification test schedule for the ELS sequence controller and defines the test utilization of the hardware enumerated in Table 5-11. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. These zone numbers are given in Table 5-11.

5.4.4.4 Parachute Fabric Samples

Figure 5-18, 5-19, and 5-20 display the qualification test schedule for the ESL parachute fabric samples and defines the test utilization of the hardware enumerated in Table 5-11. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in





فانتي

•

Figure 5-16. ELS Drogue and Pilot Mortars Qualification Test Schedule





		1963			1964	2	
PHASE AND TITLE OF TEST	SEPT	00.1	NON	DEC	JAN	FEB	
	1 2 3 4	1 2 3 4	1 2 3 4	1 2 3 4	1 2 3 4	1 2 3	4
DESIGN PROOF TESTS CHECKOUT AND CLIMATICS			1-3-4				
ACCEPTANCE					[2]		
HUMIDITY EXPLOSION-PROOF			<u>-</u>]				
ELECTROMAGNETIC INTERFERENCE				Ē			
MISSION SEQUENTIAL MAXIMUM LEVELS				E			
VIBRATION				£			
VACUUM + HIGH/LOW TEMPERATURE				F			
OPERATIONAL SHOCK							
OFF-LIMIT]			
VIBRATION					2		
LOW TEMPERATURE					2		
HIGH TEMPERATURE						2	
OPERATIONAL LIFE						2	
SHOCK						2	
LIFE TESTS]	
MISSION NORMAL LEVELS							
OPERATIONAL				3-4			
ACCELERATION				3-4			
VIBRATION				3-4			
VACUUM + HIGH/LOW TEMPERATURE				1.5	[-		
OPERATIONAL					3-4		
SHOCK							
					3-4		
							-

Figure 5-17. ELS Sequence Controller Qualification Test Schedule





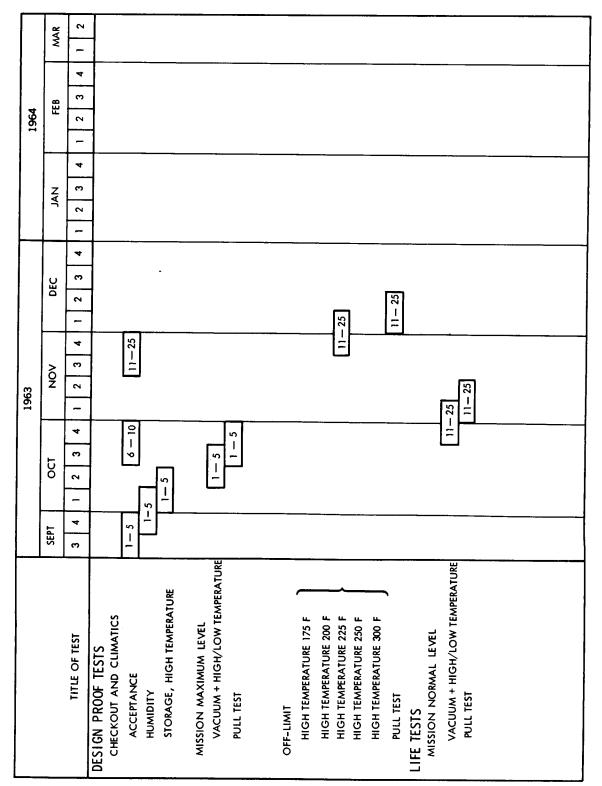


Figure 5-18. ELS Parachute Fabric Samples Qualification Test Schedule



	MAR	1 2 3 4				
1964	FEB	1 2 3 4				
	NAL	1 2 3 4				
	DEC	1 2 3 4				
1963	NON	1 2 3 4	82	1-14		
	OCT	1 2 3 4	15-28			
	PHASE AND TITLE OF TEST		DESIGN PROOF TESTS ACCEPTANCE VACUUM + HIGH/LOW TEMPERATURE DYNAMIC LOAD	OFF-LIMIT PULL TEST		

ELS Main Cluster Harness Assembly Qualification Test Schedule Figure 5-19.

3



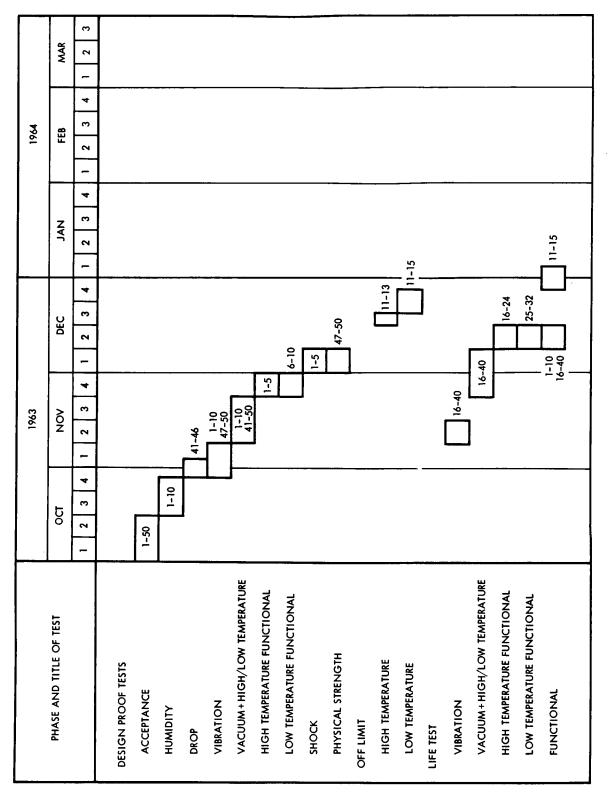


Figure 5-20. ELS Reefing Line Cutter Qualification Test Schedule

\$ 3 J

£





subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. These zone numbers are given in Table 5-11.

5.5 ENVIRONMENTAL CONTROL SYSTEM AND CRYOGENIC SUBSYSTEM

5.5.1 Scope

5.5.1.1 Environmental Control System

Complexity of the subsystem and its circuits with many components not in a common housing make qualification as a system difficult. For this reason, the subcontractor qualification program has been designed at the component and package level. The subcontractor will deliver components and packages to S&ID where they will be mounted in command module structures and tested as a system in boilerplate and airframe tests.

5.5.1.2 Cryogenic Subsystem

Laboratory qualification of the cryogenic storage system and reliability assessment from data obtained will be performed by the subcontractor.

5.5.2 Reliability Assessment Model

5.5.2.1 Environmental Control System

Figure 5-21depicts the reliability assessment model for the ECS. The model will aid in establishing test continuity and in programming the collection of data for the assessment of reliability by illustrating the interfaces of the system circuits and components.



Figure 5-21. ECS Test Oriented Reliability Logic Diagram

5.5.2.2 Cryogenic Subsystem

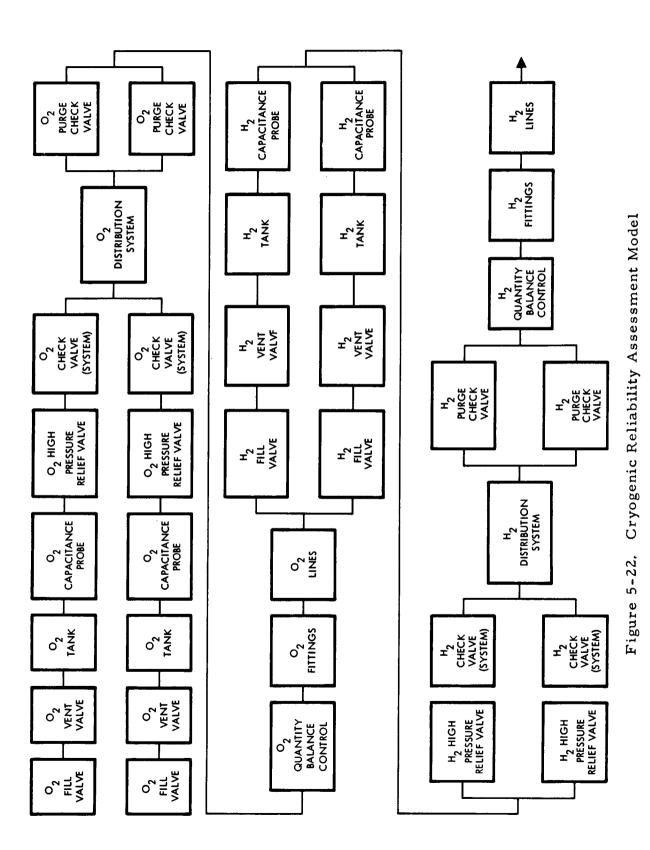
Figure 5-22 depicts the reliability assessment model for the cryogenic subsystem. The model will aid in establishing test continuity and in













programming the collection of data for the assessment of reliability by illustrating the interaction of the system components.

5.5.3 Criticality and Hardware Requirements

5.5.3.1 Environmental Control System

Table 5-12 designates the criticality class, as defined in subsection 2.4, for the components of the ECS. The table enumerates the hardware requirements for a minimum qualification program as established in subsection 2.5. The location of the components in the spacecraft is indicated by spacecraft zone numbers as defined in subsection 4.2.

Component	S/C Zone	Criticality	Required Hardware
Pressure suit	1	1	3
Water-glycol	1	1	3
C/M pressure and temperature control	1	1	3
Oxygen supply system	1	1	3
Water supply system	1	1	3
Transducers	1	1	3
Cold plates	2	1	3
Space radiators	l and 3	1	3

Table 5-12. ECS Parameters for Qualification Testing

5.5.3.2 Cryogenic Subsystem

Table 5-13 designates the criticality class, as defined in subsection 2.4, for the components of the cryogenic subsystem. The table enumerates the hardware requirements for a minimum qualification program as established in subsection 2.5. The location of the components in the spacecraft is indicated by spacecraft zone numbers as defined in subsection 4.2.

Table 5-13. Cryogenic Subsystem Parameters for Qualification Testing

Component	S/C Zone	Criticality	Required Hardware
Oxygen subsystem	l and 3	3	4 (less one tank each)
Hydrogen subsystem	l and 3	3	4 (less one tank each)







5.5.4 Qualification Test Schedule

5.5.4.1 Environmental Control System

Figure 5-23 displays the qualification test schedule for the ECS and defines the test utilization of the hardware enumerated in Table 5-12. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. These zone numbers are given in Table 5-12.

5.5.4.2 Cryogenic Subsystem

Figures 5-24 and 5-25 display the qualification test schedule for the cryogenic subsystem and define the test utilization of the hardware enumerated in Table 5-13. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. These zone numbers are given in Table 5-13.

5.6 ELECTRICAL POWER SYSTEM AND FUEL CELLS

5.6.1 Scope

5.6.1.1 Electrical Power System

The qualification program for the EPS has been designed to qualify the system for Apollo spacecraft use while determining optimum qualification test costs. The tests will verify design integrity and will provide S&ID with data to be integrated with other ground and flight test data for reliability assessment purposes. The components of the EPS are to be supplied to S&ID by different suppliers and subcontractors. Each supplier or subcontractor will perform the test, report and analyze failures, propose corrective action, and furnish S&ID with data to be used for reliability assessment. S&ID will monitor the tests and assist in failure analysis when necessary. S&ID will approve corrective actions, approve qualification results, and assess achieved reliability based on data supplied by the subcontractor or supplier. The qualification sample sizes were selected as the minimum required to accomplish engineering objectives. The number and type of tests will vary for the different components of the EPS depending on its use, operational characteristics, and location within the spacecraft.

5.6.1.2 Fuel Cells

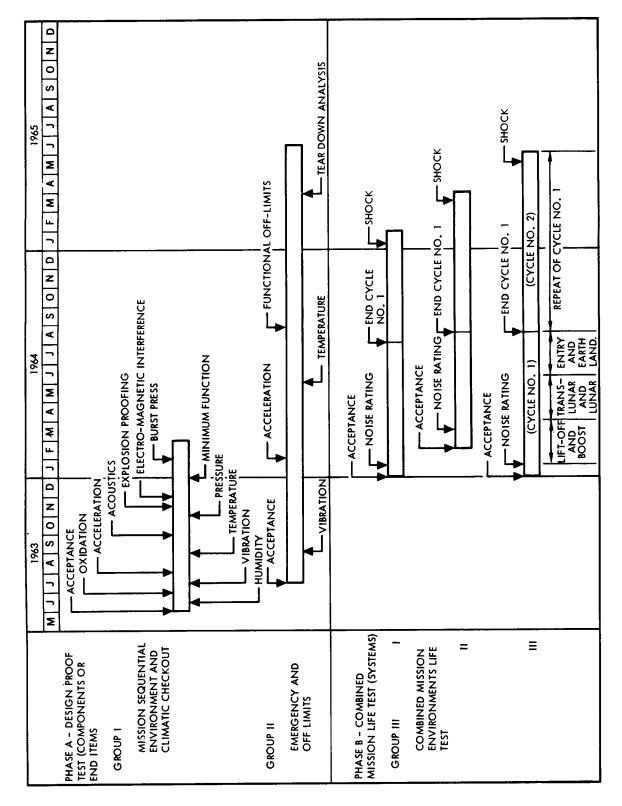
COLUMN TO SERVICE STATE OF THE PARTY OF THE

Although its basic theory of operation has been known for decades, the fuel cell is a recent addition to practical power supplies. For this reason,









ECS Qualification Test Schedule Figure 5-23.

10.7

. . .





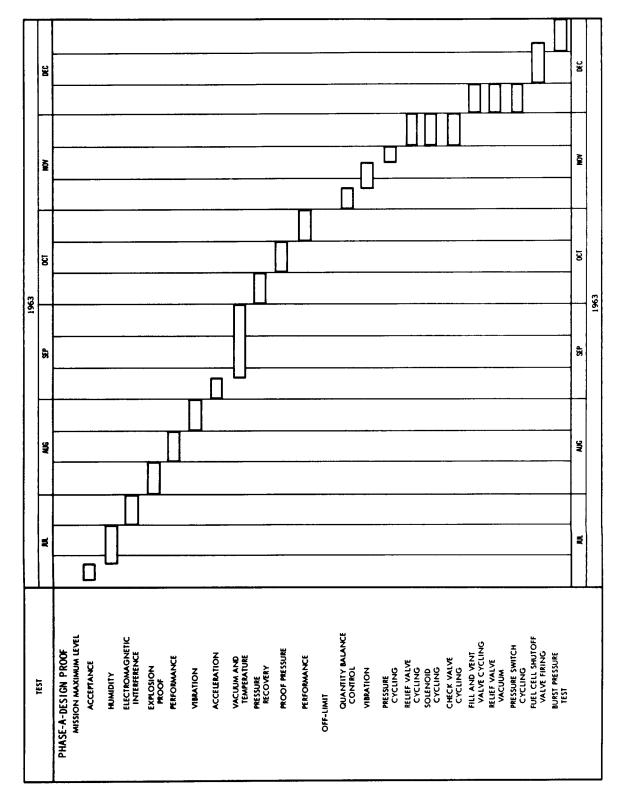
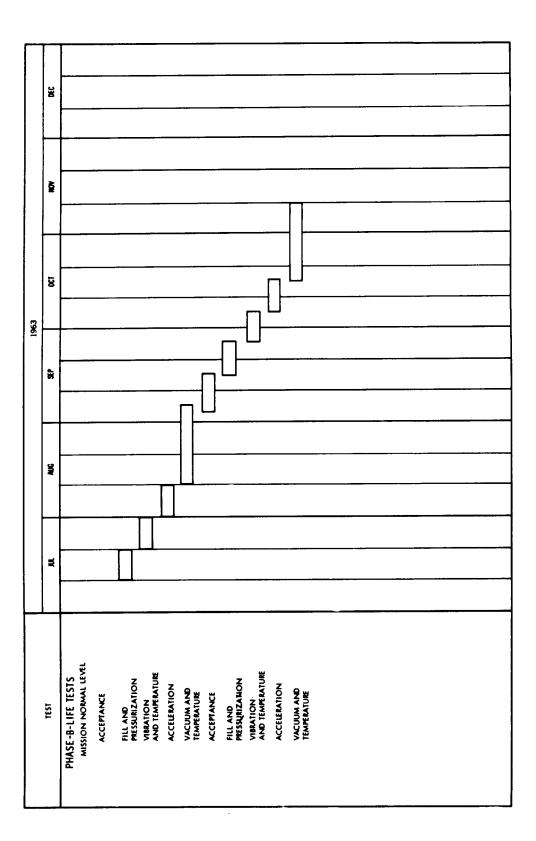


Figure 5-24. Cryogenic Subsystem Qualification Test Schedule, Phase A

e 🐈







Cryogenic Subsystem Qualification Test Schedule, Phase B Figure 5-25.

 \tilde{C}^{-}





the manufacturing "know-how" is new. The operating life (without replacement of parts) is still relatively short. The Apollo fuel cell power plant, as presently being developed, will have an operating life of 400 hours, which is 20 percent above the lunar mission time. The qualification test program has been carefully planned to verify that the fuel cell design will meet this operating life requirement. Because of the importance of the fuel cell to mission success, an active redundancy is used in the system (i.e., three fuel cells are used in parallel when any two will supply sufficient power).

Fuel cell qualification testing will be conducted by the subcontractor with surveillance by S&ID to insure conformance. Integrated system testing will be accomplished by boilerplate and airframe tests at S&ID.

5.6.2 Reliability Assessment Model

5.6.2.1 Electrical Power System

Figure 5-26 depicts the reliability assessment model for the EPS. The model will aid in establishing test continuity and in programming the collection of data for the assessment of reliability by illustrating the functional and reliability interrelationships of the system components.

5.6.2.2 Fuel Cells

Figure 5-27 illustrates the reliability interrelationship of the fuel cells.

5.6.3 Criticality and Hardware Requirements

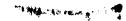
5.6.3.1 Electrical Power System

Table 5-14 designates the criticality class, as defined in subsection 2.4, for the components of the EPS less the fuel cells. The table enumerates the hardware requirements for a minimum qualification program as established in subsection 2.5. The distribution of the hardware through the subsystem qualification test phases, as described in subsection 2.3, is shown in the qualification test schedule (Figure 5-28). The location of the components in the spacecraft is indicated in the table by spacecraft zone numbers as defined in subsection 4.2.









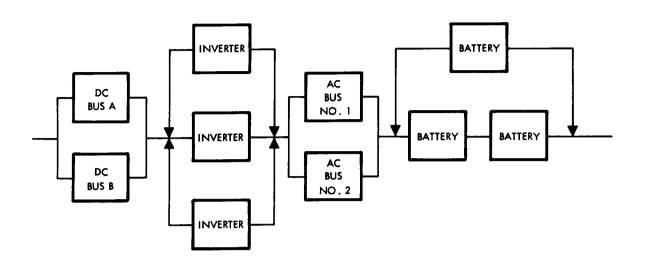


Figure 5-26. EPS Reliability Assessment Model (Less Fuel Cell)

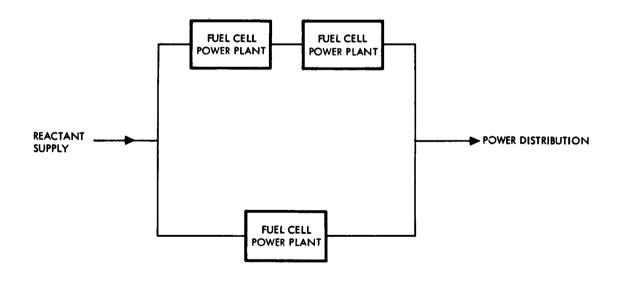
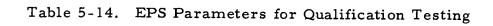


Figure 5-27. Fuel Cell Reliability Assessment Model

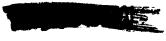




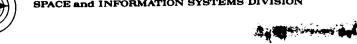




		1	
	S/C Zone	Criticality	Required Hardware
Static inverter	2	3	4
Battery	2	3	10
Battery charger	2	3	4
Circuit breakers	1 and 2	3	6 of each type 3 types
Relay general purpose	1 and 2	3	36
Connector, umbilical C/M to LES	1 external	3	4
Connector, general purpose electrical system	1, 2, 3	3	3 class F (each size) 3 class H (each size) with 3 class E plugs
Electrical feed through bulkhead C/M	2	3	2 of each type 2 types
Power transfer switch	2	3	6 of each type 3 types
Motor operated power switch and overcurrent relay	3	3	5
Floodlight fixtures	2	3	14 total 3 types
Ribbon cables C/M to S/M	1 external	3	6
Cable, electrical flat, 600 volts	1 external	3	6
Sequencer	2	3	
Relay - A			2
Relay - B		į	2
Solid state - C			2
Solid state - D			4
RCS transfer switch	1	3	4 of each class
Motor-operated DPST			
Transfer switch			4
Electrical connector set	1 internal	3	6
Aft and forward bulkhead connector	1 external	3	5
Rectangular electrical connectors	1 external	3	3







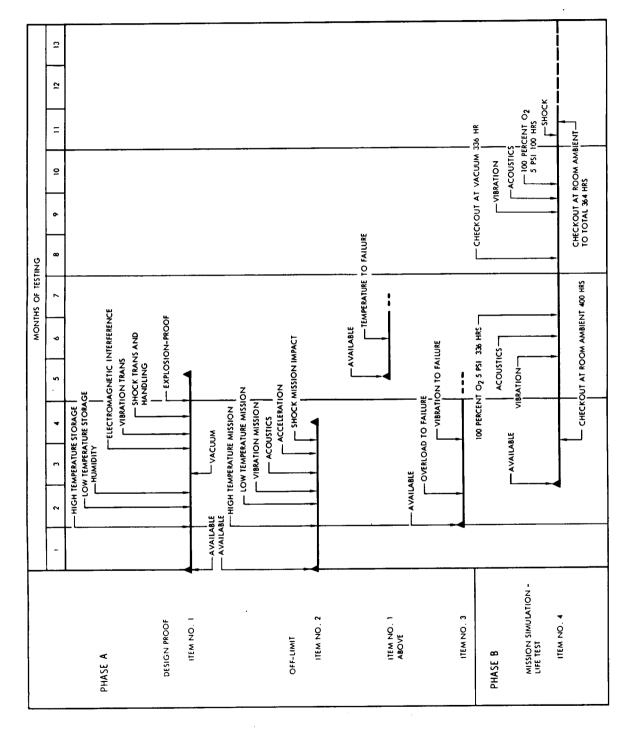


Figure 5-28. EPS Typical Qualification Test Schedule







5.6.3.2 Fuel Cells

Table 5-15 designates the criticality class, as defined in subsection 2.4, for the components of the fuel cells. The table enumerates the hardware requirements for a minimum qualification program, as established in subsection 2.5. The distribution of the hardware through the subsystem qualification test phases, as described in subsection 2.3, is shown in the qualification test schedule (Figure 5-29). The location of the components in the spacecraft is indicated in the table by spacecraft zone numbers, as defined in subsection 4.2.

Table 5-15. Fuel Cell Parameters for Qualification Testing

Component	S/C Zone	Criticality	Required Hardware	
Fuel Cell	3	3	4*	

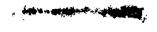
5.6.4 Qualification Test Schedule

5.6.4.1 Electrical Power System

Figure 5-28 displays the qualification test schedule for the EPS and defines the test utilization of the hardware enumerated in Table 5-14. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. These zone numbers are given in Table 5-14.

5.6.4.2 Fuel Cells

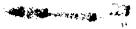
Figure 5-29 displays the qualification test schedule for the fuel cells and defines the test utilization of the hardware enumerated in Table 5-15. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. These zone numbers are given in Table 5-15.











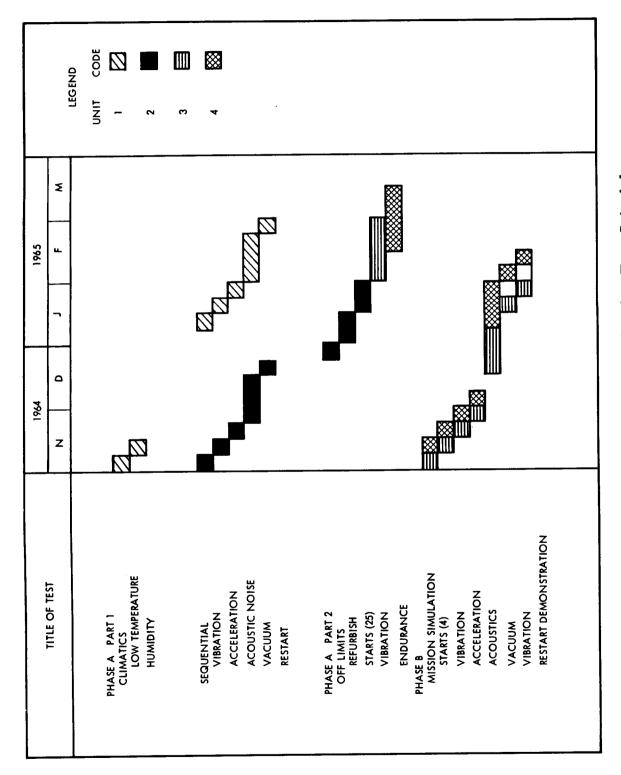


Figure 5-29. EPS Fuel Cells Qualification Test Schedule





5.7 GUIDANCE AND NAVIGATION SYSTEM

5.7.1 Scope

Efforts concerning the qualification testing of the guidance and navigation components, subsystems, and systems are specifically divided between the associate contractor and S&ID. The test programs conducted by the associate contractor and S&ID will be integrated to avoid duplication of effort and to provide maximum engineering confidence in the success of the Apollo mission.

5.7.2 Reliability Assessment Model

Figure 5-30 depicts the reliability assessment model for the G&NS. The model illustrates the reliability and functional interrelationships among the system components.

5.7.3 Criticality and Hardware Requirements

Table 5-16 designates the criticality class, as defined in subsection 2.4, for the components of the G&NS. The location of the components in the spacecraft is indicated by spacecraft zone numbers as defined in subsection 4.2.

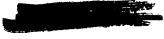
Components	S/C Zone	Criticality	Required* Hardware
IMU	2	2	
PSA	2	2	
CDU	2	2	
D&C	2	2	
AGC	2	2	
OPTICS	2	2	
MDV	2	2	
NAV BASE	2	2	

Table 5-16. G&NS Parameters for Qualification Testing

5.7.4 Qualification Test Schedule

The second of the

Figure 5-31 displays the qualification test schedule for the G&NS. The qualification test program is negotiated between MIT and NASA.





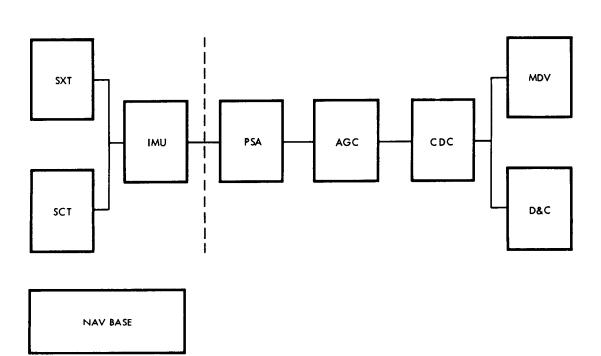


Figure 5-30. Guidance and Navigation Reliability Assessment Model

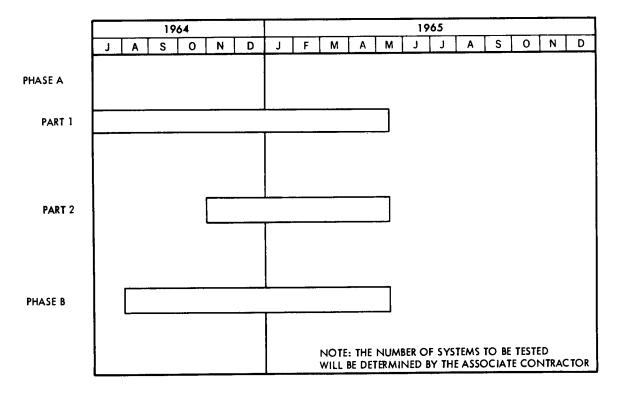
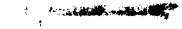


Figure 5-31. Guidance and Navigation Qualification Test Schedule







5.8 STABILIZATION AND CONTROL SYSTEM

5.8.1 Scope

The SCS qualification program has been designed to qualify the stabilization and control subsystem for Apollo use while optimizing qualification test costs. The tests will accomplish all engineering objectives and will provide S&ID with data to be integrated with all other ground and flight test data for reliability assessment purposes. The tests will be performed by the SCS subcontractor, Minneapolis-Honeywell Regulator Company, at their Aeronautical Division in Minneapolis, Minnesota. Honeywell will perform the tests, report and analyze failures, propose corrective action, and furnish S&ID with data to be used for reliability assessment. S&ID will monitor the tests, assist in failure analysis when necessary, approve corrective actions, approve qualification results and assess achieved reliability based on subcontractor-furnished data. The qualification sample sizes were selected as the minimum required to accomplish program objectives and represent the optimum hardware usage. Time and schedule constraints have necessitated the use of additional packages to bring the total sample size to six complete systems in cases where all systems are undergoing concurrent testing.

In effect, the six stabilization and control systems and the two equivalent systems, which are refurbished from the six, serve as eight systems available to accelerate the qualification program. Despite this stratagem, qualification of the SCS will not be completed before the first manned flight, reference paragraph 3.3.8 and Figure 3-9.

5.8.2 Reliability Assessment Model

Figure 5-32 depicts the reliability assessment model for the S&C system. The model will aid in establishing test continuity and in programming the collection of data for the assessment of reliability by illustrating the reliability and functional interrelationships of the system components.

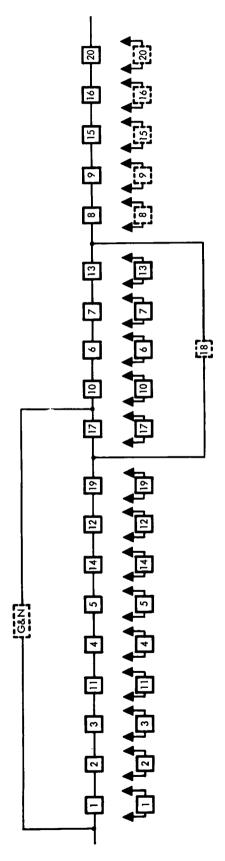
5.8.3 Criticality and Hardware Requirements

Table 5-17 designates the criticality class, as defined in subsection 2.4, for the components of the SCS. The table enumerates the hardware requirements for a minimum qualification program as established in subsection 2.5. The distribution of the hardware through the subsystem qualification test phases as described in subsection 2.3, is shown. The location of the components in the spacecraft is indicated by spacecraft zone numbers as defined in subsection 4.2.









4

FUNCTIONAL BACK-UP PROVIDED BY OTHER SPACECRAFT SYSTEMS AND EMERGENCY MANUAL CONTROLS.

EQUIPMENT KEY

- ATTITUDE GYROS (BMAG)
- ATTITUDE GYRO ELECTRONICS (ECA-D) 7
- ATTITUDE GYRO COUPLING UNIT (ECA-X) က်
- ACCELEROMETER AND ELECTRONICS (BMAG) 4.
- INTEGRATOR (ECA-D) ς.

RATE GYROS - (RGP)

è.

- RATE GYRO ELECTRONICS (RGP) ۲.
- THRUST VECTOR CONTROL CIRCUITS (ECA-P, Y) œ
- ENGINE THRUST CIRCUITS (ECA-X)
- ATTITUDE CONTROL AND REACTION JET CIRCUITS (ECA-P, Y, R) ..

- ATTITUDE INDICATOR AND DEA (FDAI, ECA-D) Ξ:
- ATTITUDE ERROR INDICATOR AND DEA (FDA1, ECA-D) 12.
- ANGULAR VELOCITY INDICATOR AND DEA (FDAI, ECA-D) 3.
- AV INDICATOR AND DEA (VI, ECA-D) 7.
- GIMBAL POSITION INDICATOR AND DEA (GPI, ECA-D) 15.
- DEA POWER SUPPLY (ECA-D) 9.
- MANUAL ROTATIONAL CONTROLS, NORMAL 7.
- MANUAL ROTATIONAL CONTROLS, EMERGENCY 18.
- MANUAL TRANSLATIONAL THRUST CONTROLS, NORMAL <u>.</u>
- SCS CONTROL PANEL (SCS-CP) ģ

SCS Reliability Assessment Model Figure 5-32.









Table 5-17. System Parameters for Qualification Testing

					Qualification	
Component	S/C Zone	Criticality	Required Hardware	Test	Phase A-2	Dist B
Rate gyro package	2	1	7	3	* 2	4
Attitude gyro and accelero- meter package	2	2	5	3	2	2
Electronics control assembly						
ECA - Pitch	2	1	6	3	2	3
ECA - Roll	2	1	6	3	2	3
ECA - Yaw	2	1	6	3	2	3
ECA - Auxiliary	2	1	6	3	2	3
ECA - Display	2	2	6	3	2	3
Gimbal position indicator	2	2	6	3	2	3
Three-axis- rotational control	2	2	6	3	2	3
Translation control	2	2	6	3	2	3
V display	2	2	6	3	2	3
Flight director attitude indicator	2	2	6	3	2	3
SCS control panel	2	1	5	3	2	2

*Samples for off limit tests are refurbished units from design proof test (A-1)









5.8.4 Qualification Test Schedule

Figure 5-33 displays the qualification test schedule for SCS and defines the test utilization of the hardware enumerated in Table 5-17. specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. These zone numbers are given in Table 5-17.

5.9 COMMUNICATIONS AND INSTRUMENTATION SYSTEMS

5.9.1 Scope

5.9.1.1 Television Equipment and Central Timing Unit

Qualification tests on the television equipment and CTU conform to the general requirements of MIL-E-5272 and include the following:

- 1. Calibration tests
- 2. Environmental tests
- 3. Electromagnetic interference
- 4. Susceptibility tests
- 5. Mission simulation-life tests

The number of test systems is predicated on the requirement to assess compliance with the procurement specification both in the normal and offlimit modes of operation. The number of qualification test samples of the television equipment and the CTU is based on the criticality index, limited life requirements, service life considerations, and multiple use of test articles.

5.9.1.2 Communications and Data Subsystem

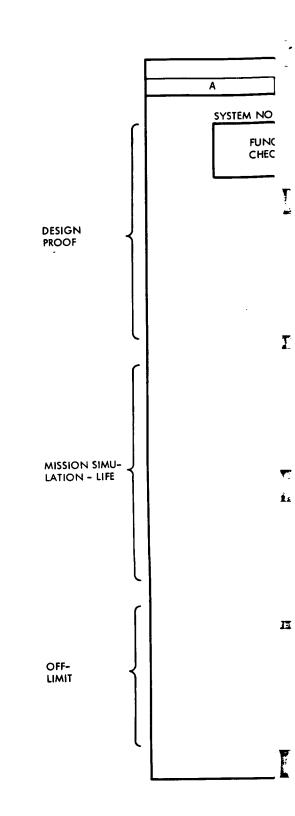
Same as for 5.9.1.1.

5.9.1.3 Antenna Systems

The antenna ground qualification test plan has been designed to accomplish three objectives. First, to test to the maximum levels of the mission environments; second, to test beyond design limits to determine the design margins in critical mission environments; and third, to conduct environmental testing in accordance with the mission sequence. If the antenna







•

I

19€ J J Α S М VACI TION VIBRATION HIGH-LOW-VIBRATION (GROUND) **TEMPERATURE TEMPERATURE KOUT** (10 SYSTEM NO. 4 **FUNCTION** CHECKOUT SYSTEM NO. 2 **FUNCTION ELECTROMAGNETIC** HUMI CHECKOUT INTERFERENCE SYSTEM NO. 3 VIBRATION SHOCK GROUND VIBRATION **FUNCTION** (GROUND) (GROUND) **CHECKOUT** CHECKOUT **ACOUSTIC** SYSTEM NO. 5 **FUNCTION** VIBRATION GROUND CHECKOUT (GROUND) CHECKOUT SYSTEM NO. 6 FUNCTION VIBRATION GROUND (GROUND) CHECKOUT CHECKOUT TE I. I

Ų,

_ _												34		
	F			J			D		N)			
					sноск	S	ERATION	ACCE		COUSTIC NOISE	A	JUM -4)		
_		CELERATION	ACC		ACOUST NOISE									
			SHOO (LANDI		VIBRATI (GROUN	ON	OXIDATI	OW RATURE		IGH ERATURE		DITY		
AC' (5P		VIBRATION TEMPERATURE		NCE	ECALIBRAT MAINTENA AND REPA		ATION ERATURE			VACU (5PS	ATION	ACCELER		
1A	RECALIBRA MAINTEN AND RE		VACL (5P:		LERATION	ACCE	BRATION COUSTIC			VIBRATI TEMPERA		SHOCK (GROUNI		
TI Ah	RECALIBRA MAINTENA AND RE		VIBRAT ACOU		VACUUM (5PSI)		SHOCK (GROUND)			ACCELERATION		ACCELERA		/IBRATION MPERATURE
N(UR	IO . 7 (OLD	SYSTEM N												
	IO . 8 (OLD	SYSTEM 1												
_														

Ţ

	M		Α		М	I	J		19
	IBRATION		SHOCK (30G)	ті	HIGH- EMPERATURE	LOW- TEMPERATU	V,	 ACUUM (10 ⁻⁴)	VIBRATIO (GROUNI
JUM SI)	ACCELERATIC	N	VIBRATIO ACOUST	DN CIC	GROU CHECK	ND OUT	SHOCK (GROUND)		ATION DUND)
ON → ICE IR			/IBRATION MPERATURE	(0	SHOCK (GROUND)		ACCELERATION		BRATION COUSTIC
ON ICE IR	GROUND CHECKOUT		ACCELERATION	7	VIBRATION VIBRATION ACOUSTIC TEMPERATURE			SHOCK (GROUND)	
). 1) BISHMEN	т		VOLTAGE VARIATION						
). 2) BISHMEN	т				VIBRAT TEMPER	'ION ATURE]		

E E

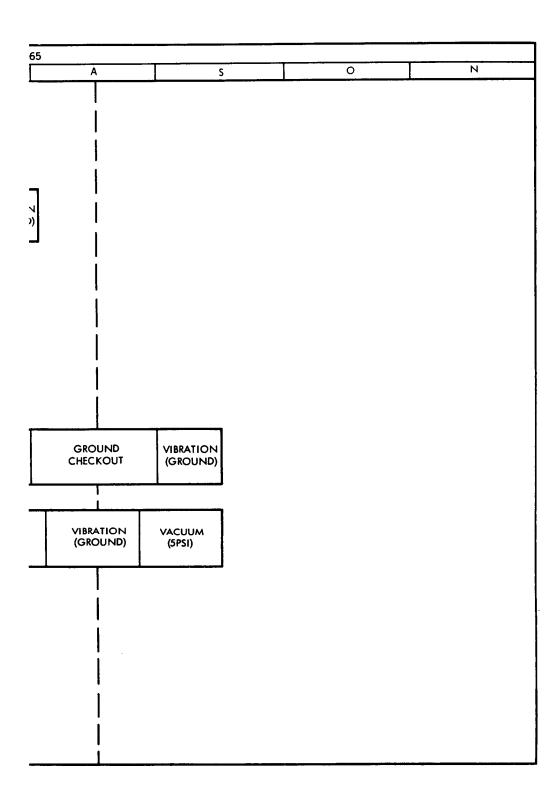


Figure 5-33. SCS Qualification Test Schedule



CONFIDENTIAL

The second

systems perform successfully after the subjection to the mission profile, first and third objectives, they are then considered qualified for use in flight qualification tests.

5.9.2 Reliability Assessment Model

5.9.2.1 Television Equipment and Central Timing Unit

The reliability assessment model for the television equipment will be submitted with the next quarterly revision of the Apollo General Test Plan. Figure 5-34 depicts the reliability assessment model for the CTU. The models will aid in establishing test continuity and in programming the collection of data for the assessment of reliability of this equipment by illustrating the reliability and functional interrelationships of the system components.

5.9.2.2 Communications and Data Subsystem

Figure 5-35 depicts the reliability assessment model for the telemetry of the communications and data subsystem. Figure 5-36 depicts the reliability assessment model for the C&D subsystem during the near-earth phase of the mission. Figure 5-37 depicts the reliability assessment model for the C&D subsystem during the deep-space phase of the mission. Figure 5-38 depicts the reliability assessment model for the C&D subsystem during recovery. Each subsystem is a series of the reliability function.

5.9.2.3 Antenna Systems

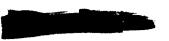
• •

Figure 5-39 depicts the reliability assessment model for the recovery antenna system. Figure 5-40 depicts the reliability assessment model for the high-gain antenna system. The models will aid in establishing test continuity and in programming the collection of data for the assessment of reliability of the antenna systems by illustrating the reliability and functional interrelationships of each system's components.

5.9.3 Criticality and Hardware Requirements

The tables under this paragraph designate the criticality class, as defined in subsection 2.4, for the components of the subsystems listed. The table enumerates the hardware requirements for a minimum qualification program as established in subsection 2.5. The distribution of the hardware through the subsystem qualification test phases, as described in subsection 2.3, is shown. The location of the components in the spacecraft is indicated by spacecraft zone numbers as defined in subsection 4.2.





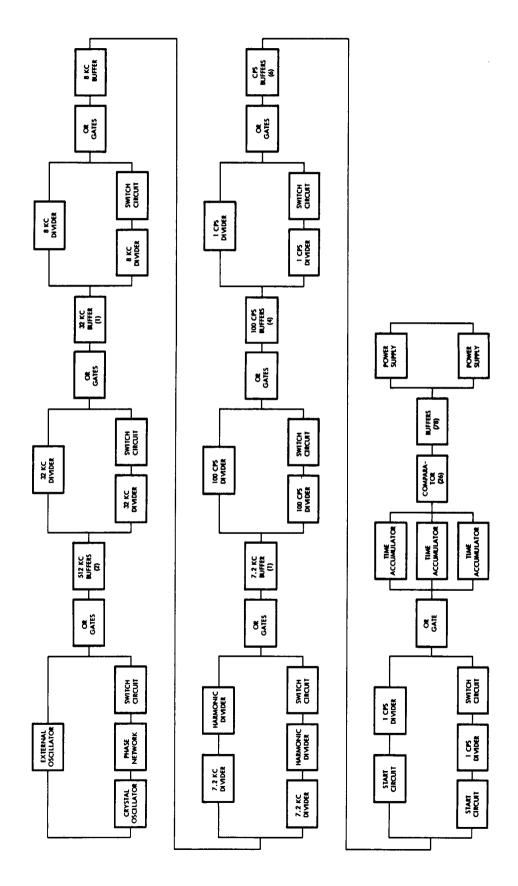


Figure 5-34. CTU Reliability Assessment Model



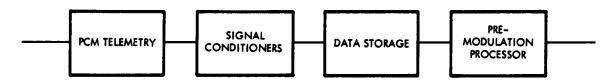


Figure 5-35. Telemetry Assessment Model

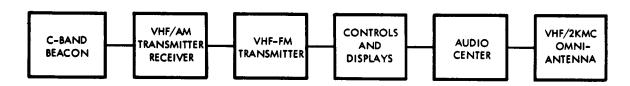


Figure 5-36. Near-Earth Assessment Model

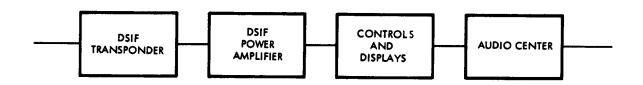


Figure 5-37. Deep-Space Assessment Model

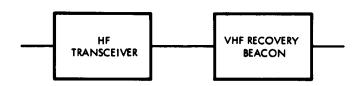


Figure 5-38. Recovery Assessment Model

₩.







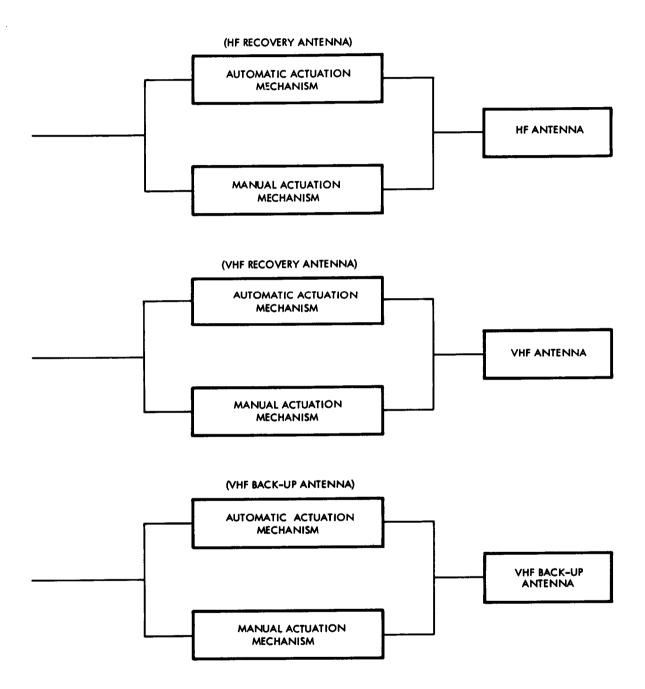


Figure 5-39. Recovery Antenna Assessment Model

1009,2000







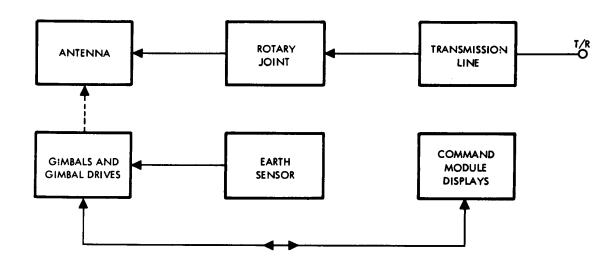


Figure 5-40. High-Gain Antenna Assessment Model

5. 9. 3. 1 Television Equipment and Central Timing Unit

Table 5-18 exhibits the system parameters for qualification testing for the television equipment and CTU.

					ication Test Distribution	
Component	S/C Zone	Criticality	Required Hardware	A-1	A-2	В
TV equip.	2	3	4	2	2	1
CTU	2	2	6	2	2	3

Table 5-18. System Parameters for Qualification Testing

5. 9. 3. 2 Communications and Data Subsystem

Table 5-19 exhibits the system parameters for qualification testing of the communications and data subsystem.



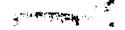
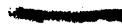


Table 5-19. CDS Parameters for Qualification Testing

				Qualification Te Phase Distributi		
Component	S/C Zone	Criticality	Required Hardware	A-1	A-2	В
Audio center equipment	2	2	4	2	2	1
VHF/FM transmitter	2	3	6	3	2	2
VHF/AM transmitter- receiver	2	2	7	3	2	3
C-Band transponder	2	2	5	2	2	2
DSIF transponder	2	2	7	3	2	3
DSIF P. A.	2	2	7	3	2	3
VHF recovery beacon	2	3	5	3	2	1
HF transceiver	2	3	5	3	2	1
Pre-Mod. processor	2	2	7	3	2	3
Signal conditioners	2	3	5	2	2	2
Data storage	2	3	5	2	2	2
Comm. control panel	2	3	6	3	2	2
Audio control panel	2	3	6	3	2	2
PCM telemetry	2	3	5	3	2	1
					:	





5.9.3.3 Antenna Systems

Table 5-20 exhibits the system parameters for qualification testing of the antenna systems.

Table 5-20. Antenna Systems Parameters for Qualification Testing

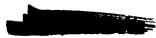
			,	1	fication Test Distribution	
Component	S/C Zone	Criticality	Required Hardware	A - 1	A-2	В
HF recovery antenna	1	1	3	2	1	
VHF recovery antenna	1	3	3	2	1	·
VHF backup recovery antenna	1	3	3	2	1	
High-gain antenna	3	2	6	2	1	3
C-Band antenna	1	2	3	2	1	

5.9.4 Qualification Test Schedule

The figures described in this paragraph display the qualification test schedules for the subsystems of the communications and instrumentation systems and define the test utilization of the hardware enumerated in the tables of subsection 5.9.3. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in subsection 4.2 and are a function of the zone location of the equipment in the spacecraft. The zone numbers of the C&I subsystems and components are given in the tables associated with the test schedules described.

5.9.4.1 Television Equipment and Central Timing Unit

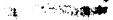
Figure 5-41 displays the qualification test schedule for the television equipment. Figure 5-42 displays the qualification test schedule for the central timing unit. Table 5-18 lists the associated system parameters.

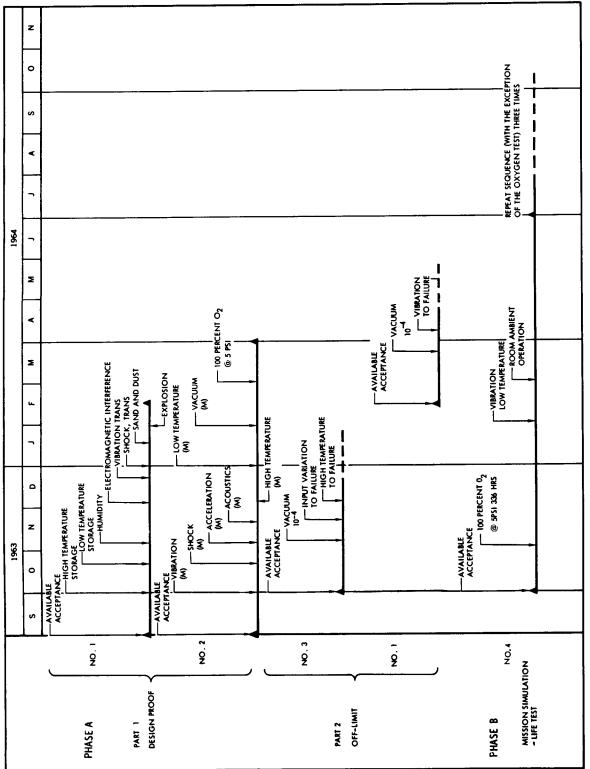












TV Equipment Qualification Test Schedule Figure 5-41

•ي• لائش

1 44





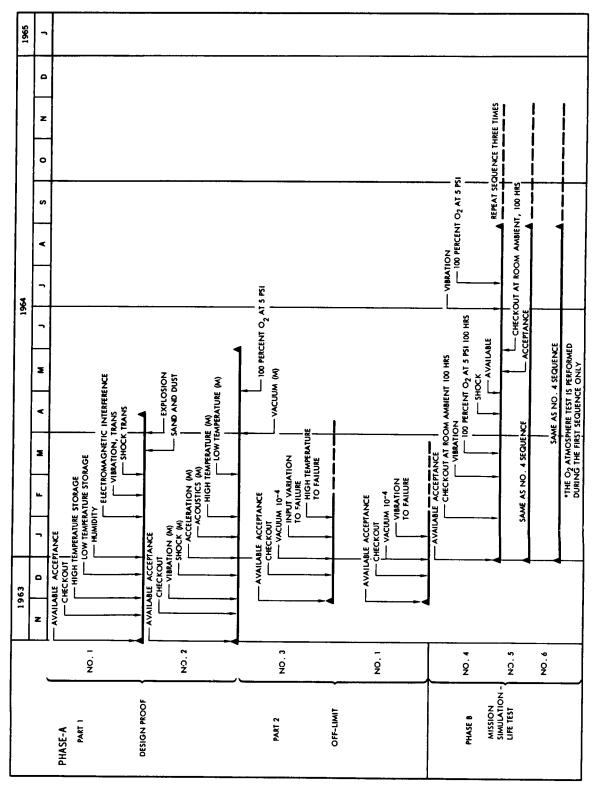


Figure 5-42. CTE Qualification Test Schedule



5.9.4.2 Communications and Data Subsystem

Figure 5-43 displays the qualification test schedule for the CDS components of criticality category 2.

Figure 5-44 displays the qualification test schedule for the CDS components of criticality category 3.

Table 5-19 lists the associated system parameters for these test schedules.

5.9.4.3 Antenna Systems

Figure 5-45 displays the qualification test schedule for the HF recovery antenna.

Figure 5-46 displays the qualification test schedule for the VHF recovery antenna.

Figure 5-47 displays the qualification test schedule for the VHF recovery (back-up) antennas.

Figure 5-48 displays the qualification test schedule for the 2KMC high-gain antenna.

Figure 5-49 displays the qualification test schedule for the C-band beacon antenna and incorporates the antenna window qualification.

Table 5-20 lists the associated system parameters for these test schedules.

5.10 LIFE SYSTEMS

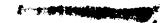
5.10.1 Scope

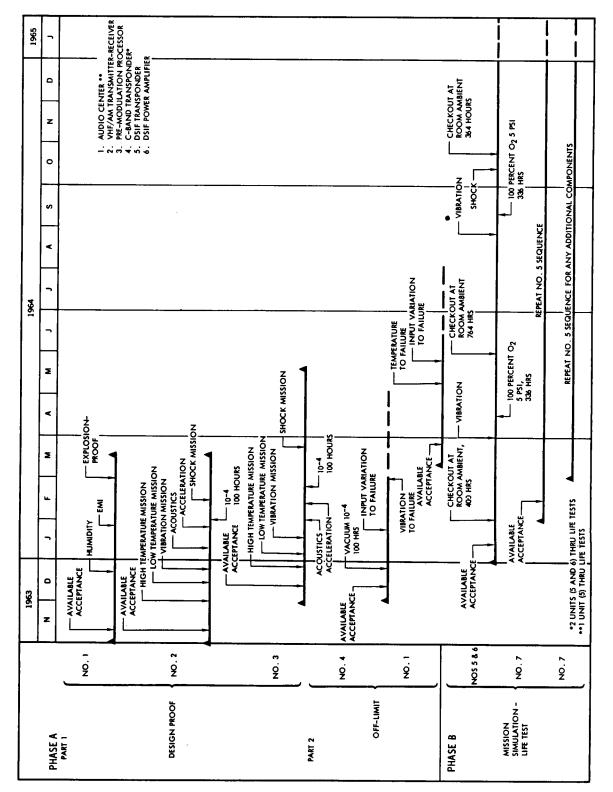
Since many components will be qualified and furnished by NASA, life system tests will be conducted to verify compatibility of crew equipment and related GSE systems machine interfaces. Qualification testing will be conducted with AFRM vehicle mock-ups and production equipment.









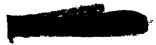


CDS Qualification Test Schedule (Criticality 2) Figure 5-43.



-





•

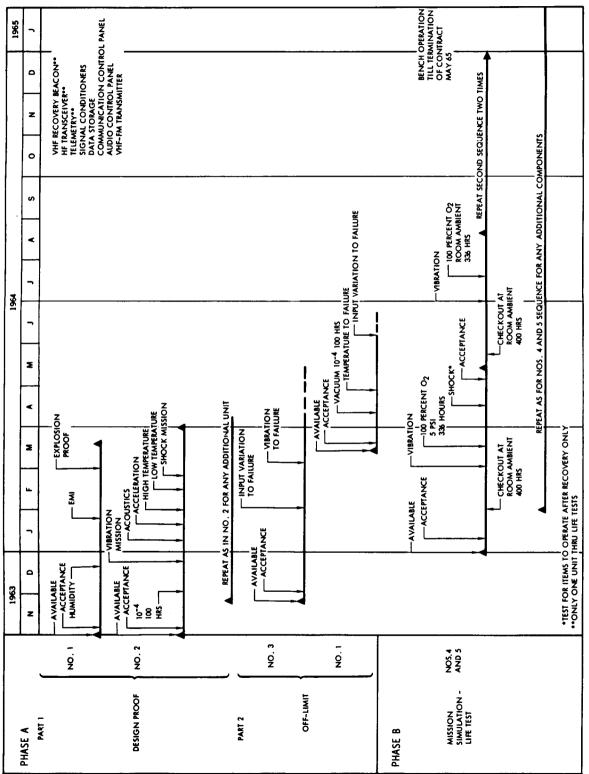


Figure 5-44. CDS Qualification Test Schedule (Criticality 3)

. .





三級



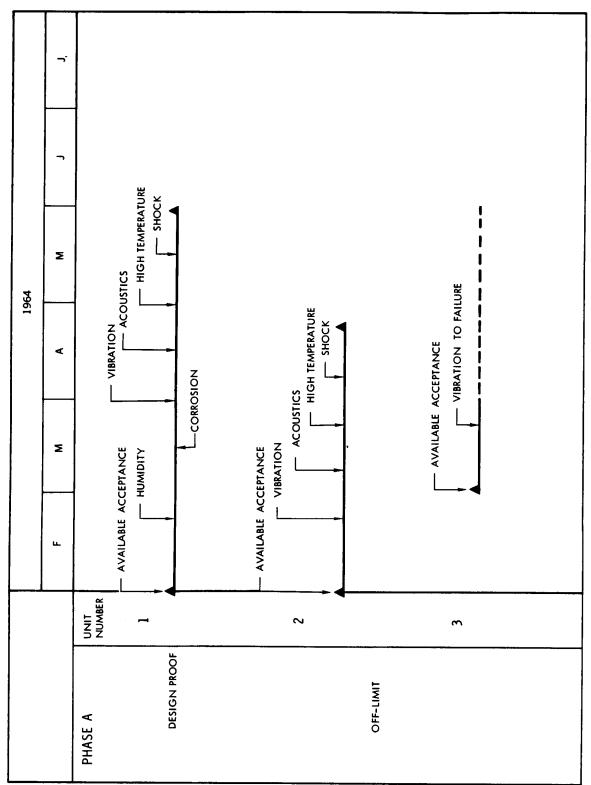
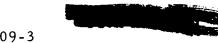


Figure 5-45. HF Recovery Qualification Test Schedule







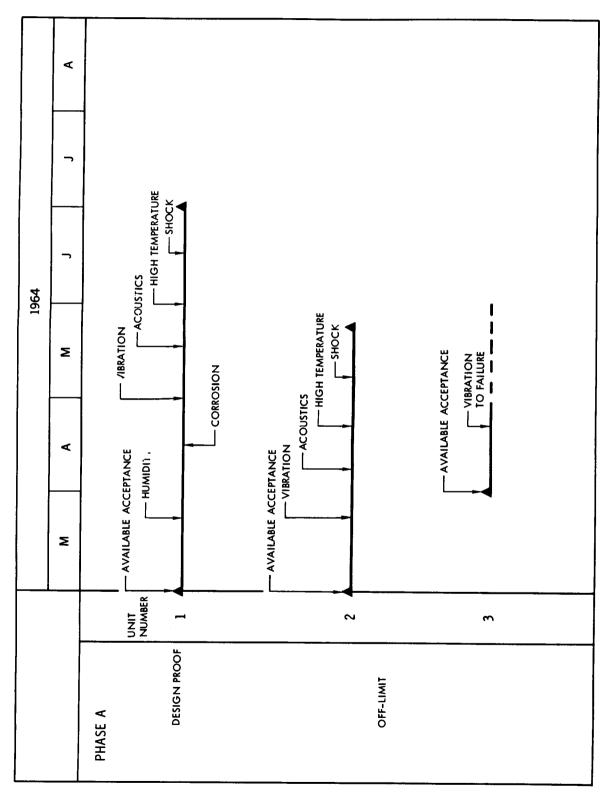


Figure 5-46. VHF Recovery Qualification Test Schedule

-





-,5

•

1



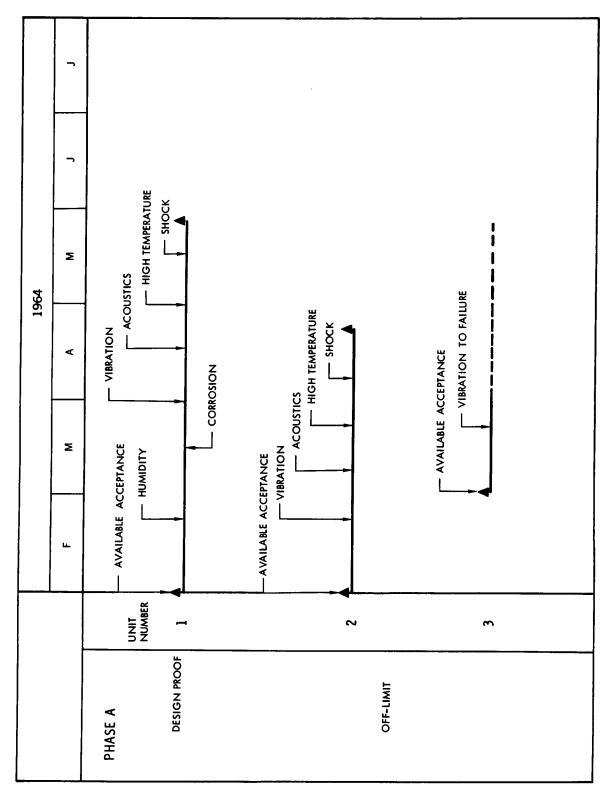


Figure 5-47. VHF Recovery (Back-up) Qualification Test Schedule

- 4

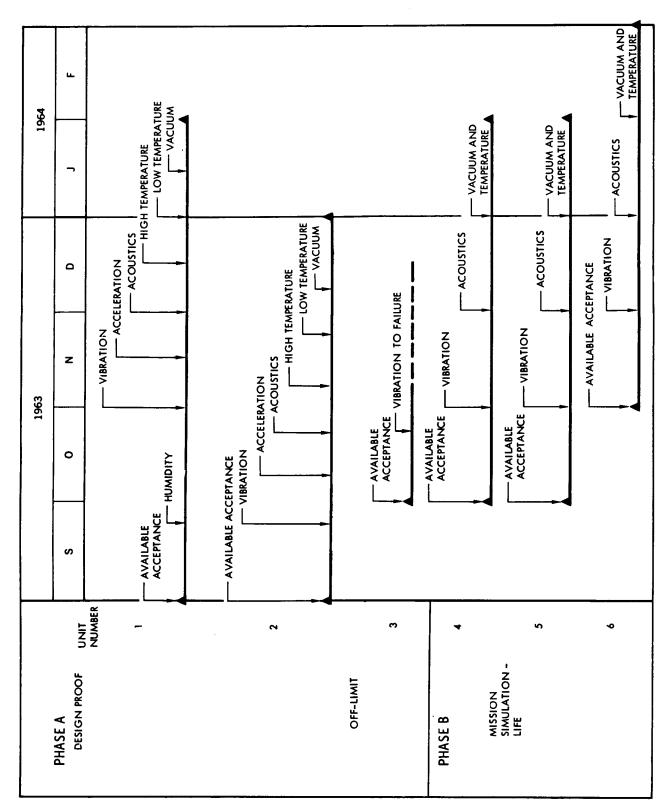
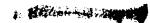


Figure 5-48. Two-kmc High-Gain Qualification Test Schedule







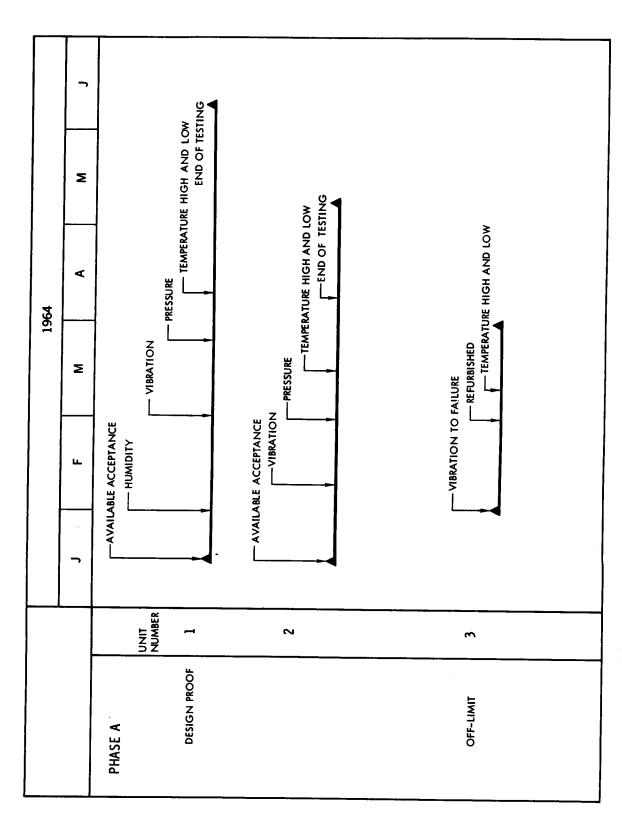


Figure 5-49. C-Band Beacon Qualification Test Schedule

- INCHES







5.10.2 Reliability Assessment Model

Due to the number of components and the varied nature of the qualification testing, a reliability assessment model is not considered applicable for the life systems.

5.10.3 Criticality and Hardware Requirements

Table 5-21 designates the criticality class, as defined in Section 2.4, for the components of the life systems. The table enumerates the hardware requirements for a minimum qualification program, as established in Section 2.5. The location of the components in the spacecraft is indicated by spacecraft zone numbers, as defined in Section 4.2.

5.10.4 Qualification Test Schedule

Figure 5-50 displays the qualification test schedule for the components of the life systems. Because the particular tests to be applied are not defined at this time, the schedule displays the time phasing of the test categories, only.

5.11 THERMAL PROTECTION SYSTEM

5.11.1 Scope

The ground qualification test plan for the thermal protection system (TPS) consists of environmental qualification and mission simulation-life test of heat shield panels fabricated with the same ablative and bonding materials and surface control coating and in the same configuration as that which will be used for the C/M heat shield. The data obtained will be used for backup to the C/M heat shield flight qualification testing and for assessment of TPS reliability.

5.11.2 Reliability Assessment Model

Figure 5-51 illustrates the functional relationship and the series reliability configuration of the heat shield materials.

5.11.3 Criticality and Hardware Requirements

Table 5-22 designates the criticality class, as defined in Section 2.4; the number of panels required for an optimized ground qualification test plan, as described in Section 2.5; and the zone locations of the heat shield in the spacecraft, as defined in Section 4.2. The distribution of the panels through the qualifications test phases, as described in Section 2.3, is shown.









Table 5-21. Life Systems Parameters for Qualification Testing

Component	S/C Zone	Criticality*	Required Hardware
Tool set in-flight	2		4
Pad assembly couch	2		6
Harness assembly couch	2		4
Restraint assembly rest station	2		4
Portable light assembly	2		8
Constant wear garment	2		4
Hose umbilical	2		8
Disconnect assembly cabin half	2		6
Food and food package	2		8
Canister assembly - fecal	2		4
Bag (set) fecal	2		4
Receptacle assembly crewmen relief	2		4
Receptacle, liner set	2		3
Head set and microphone	2	:	6
Transceiver	2		6
Cleansing pad	2		3
Ingestible dentifrice	2		3
Shaver	2		3
Deodorizer pad	2		3
Emergency medical supplies and equipment	2		3

[&]quot;To be determined





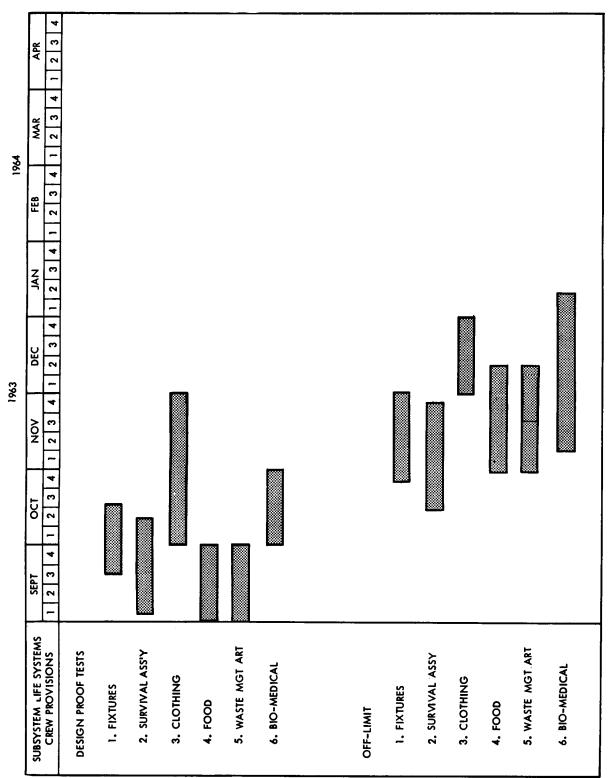


Figure 5-50. Life Systems Qualification Test Schedule

4

ş . **





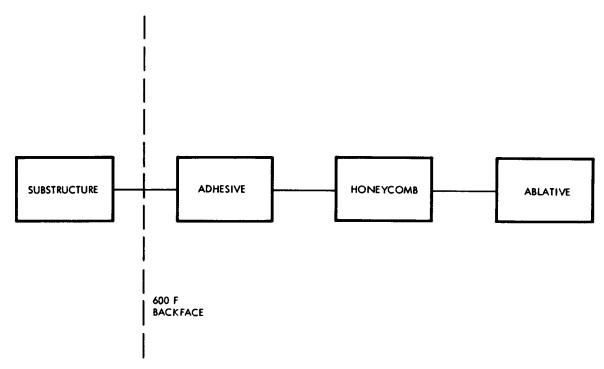


Figure 5-51. TPS Reliability Assessment Model

Table 5-22. TPS Parameters for Qualification Testing

		Qualification T Phase Distribu				
Component	S/C Zone	Criticality	Required Hardware	A-1	A-2	В
Heat shield panel	1	1	16	6	4	6

5.11.4 Qualification Test Schedule

Figure 5-52 displays the qualification test schedule for the TPS and defines the test utilization of the panels enumerated in Table 5-22. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in Section 4. 2 and are a function of the zone location of the heat shield in the spacecraft. The zone number is given in Table 5-22.





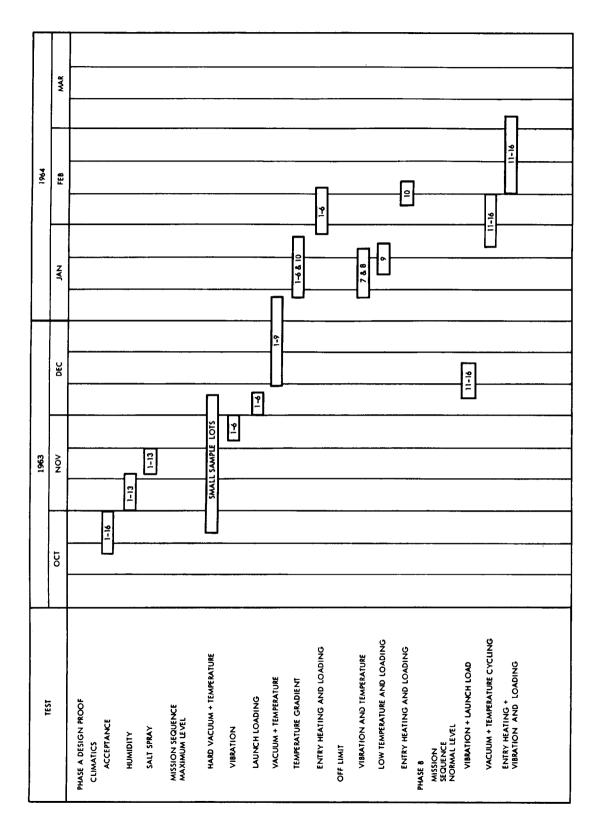
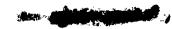


Figure 5-52. TPS Qualification Test Schedule







5.12 STRUCTURAL SYSTEM

5.12.1 Scope

The qualification test program includes testing of structural components and complete structures of command module, service module, spacecraft adapter, launch escape tower, and combined structures. Subassembly testing of structural members including joints, truss sections, welds, tankage, windows, and motor supports, will be conducted by applying limit loads for major critical design conditions and then by applying ultimate design loads. The test specimen will be loaded to failure for a selected condition for each test to determine the maximum load capability.

5.12.2 Reliability Assessment Model

Problems in the reliability analysis of structural components and complete structural assemblies including the development of reliability assessment models are being studied. When presentation techniques have been developed, a reliability assessment model will be included in the structures qualification test plan.

5.12.3 Criticality and Hardware Requirements

The criticality and hardware requirements of the structural system are being determined and will be included in a later revision of this volume.

5.12.4 Qualification Test Schedule

The structures system qualification test schedule will be defined to the extent of information available and will be submitted in later revisions.

5.13 MECHANICAL SYSTEMS

5.13.1 Scope

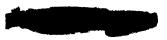
The qualification test program includes component and systems testing of the four separation systems and the crew hatch and astro sextant door actuating systems, and component testing of the crew couch attenuation struts.

5.13.1.1 Forward Heat Shield Separation System

The separation of the forward heat shield from the command module, prior to operation of the earth landing system, will be accomplished by firing two pressure cartridges. The gas pressure operates four thrusters that will each break one tie bolt. The qualification test program for the









separation system will be included in a later revision. The qualification test program for the pressure cartridge will subject 118 specimens to mission environments and firing tests.

5.13.1.2 Launch Escape Tower Separation System

The separation of the launch escape tower from the command module will be accomplished by firing four explosive bolts. Each bolt has two independent cutting modes, either of which will separate the bolt. The qualification test program for the separation system will be included in a later revision. The qualification test program for the bolts will subject 133 specimens to mission environments, loads, and firing tests.

5.13.1.3 Command Module to Service Module Separation System

The command module will be separated from the service module by firing detonators and linear-shaped charges in three tie rod assemblies. Each tie rod assembly has two detonators and two linear-shaped charges in redundant pairs. The qualification test program for the separation system will be included in a later revision. The qualification test program for the detonator will subject 118 specimens to mission environments and firing tests.

5.13.1.4 Adapter Separation System

The service module will be separated from the launch vehicle upper stage by firing detonators and linear-shaped charges. The cylindrical adapter for the S-I vehicle and the tapered adapter for the S-V vehicle will have basically similar systems. The explosive separation system consists of 40 lengths of flexible linear-shaped charge, 8 interface junction blocks, and 2 umbilical cable cutters, each with 2 lengths of linear-shaped charge and 4 lengths of mild detonating fuse. The system is initiated by two detonators, one of which is redundant. The qualification test program for the separation system will be included in a later revision. The qualification test program for the linear-shaped charge will subject 100 specimens to mission environments and penetration tests; the detonator test program is referred to in 5.13.1.3.

5.13.1.5 Crew Hatch Actuating System

The crew hatch will be operated manually from inside the crew compartment. A hermetically sealed, manually operated actuator will operate latches on the outside of the inner crew hatch of the command module. The qualification test program for the complete actuating system will be included in a later revision. The qualification test program for the manually operated actuator will subject four specimens to mission environments, loading, and life tests.





5.13.1.6 Astro Sextant Door Actuating System

The doors covering the astro sextant window will be operated manually from inside the crew compartment. A hermetically sealed, manually driven gear box will apply torque to three rotary flexible shafts. Two of the shafts will operate the door mechanism and the third will actuate the latch mechanical linkage by means of a screwjack. The qualification test program for the complete actuating system will be included in a later revision. The qualification test programs for the gear box, rotary flexible shaft, and screwjack will subject four specimens of each to mission environments, loading, and life tests.

5.13.1.7 Crew Couch Shock Attenuation System

The shock loads induced in the crew couches by earth landing will be attenuated by a total of eight shock struts of four different types. The qualification test program for the complete attenuation system will be included in a later revision. The qualification test program for the shock struts will subject seven specimens of each type of strut to mission environments, and normal and emergency impact loading. Each strut will be subjected to twenty impacts to compress the replaceable crushable honeycomb core.

5.13.2 Reliability Assessment Model

5.13.2.1 Forward Heat Shield Separation System

Figure 5-53 depicts the reliability assessment model for the forward heat shield separation system pressure cartridges.

5.13.2.2 Launch Escape Tower Separation System

Figure 5-54 depicts the reliability assessment model for the LET separation system explosive bolts.

5.13.2.3 Command Module to Service Module Separation System

Figure 5-55 depicts the reliability assessment model for the $\mbox{C/M}$ to $\mbox{S/M}$ separation system.

5.13.3. Criticality and Hardware Requirements

Table 5-23 designates the criticality class, as defined in Section 2.4, for the components of the mechanical devices. The table enumerates the hardware requirements for a minimum qualification program, as established in Section 2.5. The distribution of the hardware through the subsystem



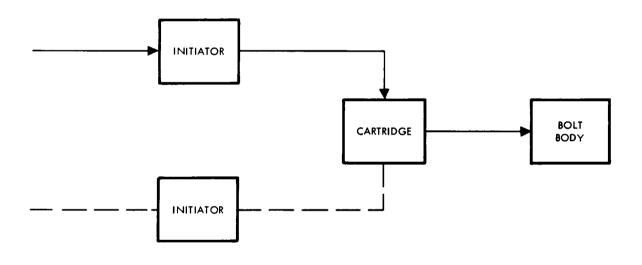
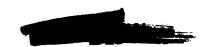
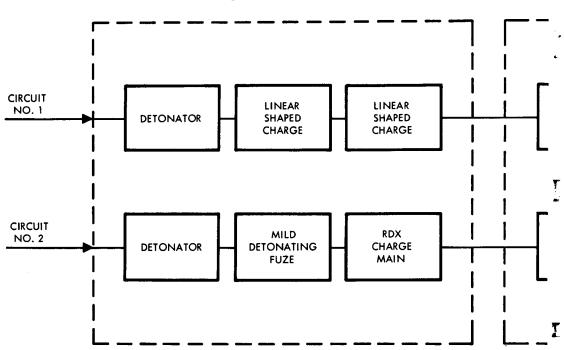
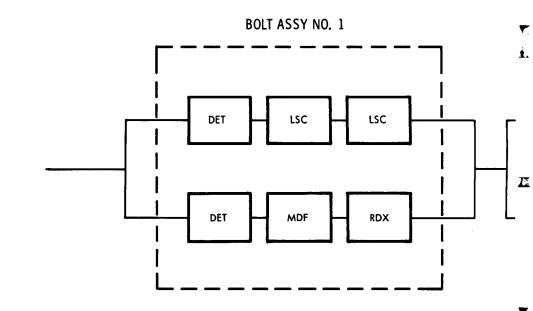


Figure 5-53. Pressure Cartridge Reliability Assessment Model

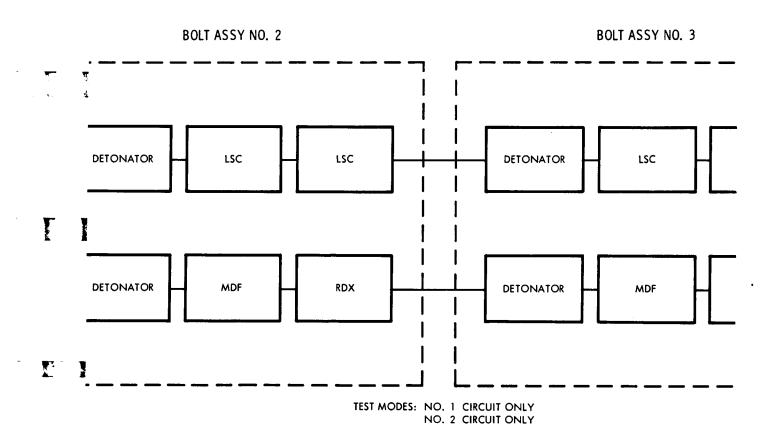


BOLT ASSY NO. 1





Ī



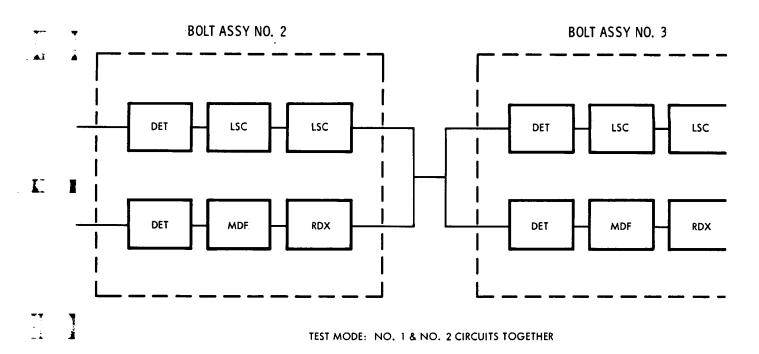
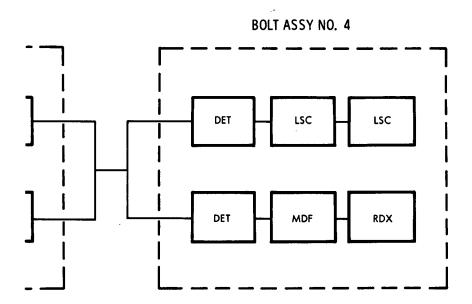


Figure 5





-54. Reliability Assessment Models Launch Escape Tower Separation System

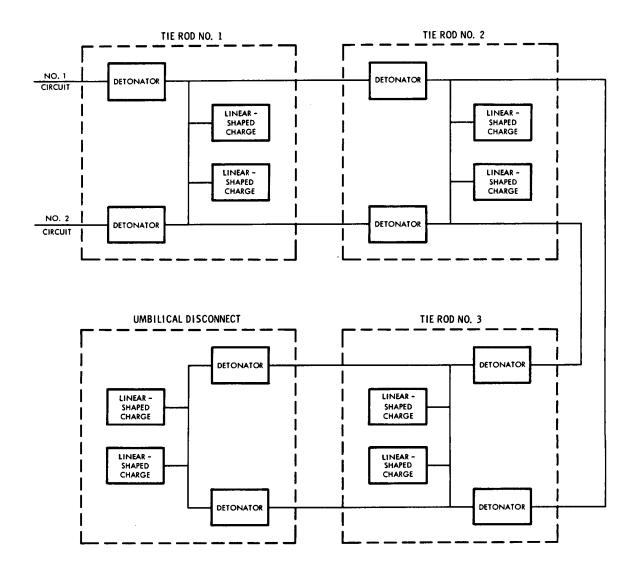






State of the last





TEST MODES: NO. 1 CIRCUIT ONLY
NO. 2 CIRCUIT ONLY
NO. 1 & NO. 2 CIRCUITS TOGETHER

Figure 5-55. Reliability Assessment Model C/M to S/M Separation System



qualification test phases, as described in Section 2.3, is shown. The location of the components in the spacecraft is indicated by spacecraft zone numbers, as defined in Section 4.2.

Table 5-23. System Parameters for Qualification Testing

Component	S/C Zone	Criticality	Required Hardware
Cartridge, forward compartment heat shield separation	1	1	118
Explosive bolt, launch escape tower separation	1	1	133
Detonator cartridge	1	1	118
Crew hatch actuator	1 & 2	3	4
Astro sextant door gear box	1 & 2	1	4
Astro sextant door rotary flexible shaft	1 & 2	1	4
Astro sextant door screwjack	1	1	4
Crew couch shock struts	2	1	7 of four types
Linear shaped charge	1,3,4	1	100 of each type
Crew hatch actuating system	1 & 2	3	2
Astro sextant door actuating system	1 & 2	1	2

5.13.4 Qualification Test Schedule

TOTAL

5.13.4.1 Forward Heat Shield Separation System

Figure 5-56 displays the qualification test schedule for the cartridges enumerated in Table 5-23. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in Section 4.2 and are a function of the zone location of the equipment in the spacecraft. The zone number is given in Table 5-23.



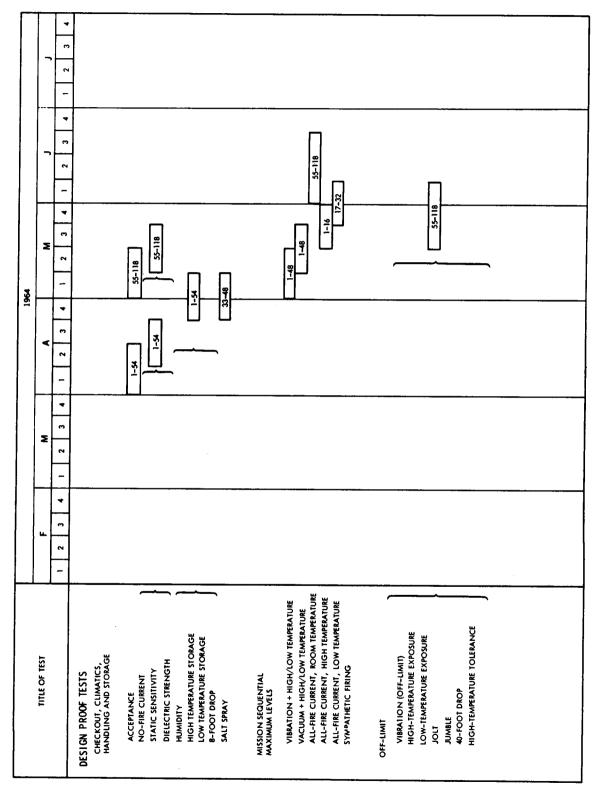


Figure 5-56. Pressure Cartridge Qualification Test Schedule

The Control of the Co

i or**ysi**a,





5.13.4.2 Launch Escape Tower Separation System

Figure 5-57 displays the qualification test schedule for the LET explosive bolts enumerated in Table 5-23. The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in Section 4.2 and are a function of the zone location of the equipment in the spacecraft. The zone number is given in Table 5-23.

5.14 ELECTRONIC SYSTEMS

5.14.1 Scope

The electronic systems (ES) consist of the display and controls system (D&C) and the in-flight test system (IFTS). The D&C system will be tested at three levels of assembly: part, subpanel assembly, and the control console

The parts qualification program will consist of a complete environmental and stress testing program. Those parts which are commonly used several subpanel usage applications will be defined as criticality one parts, in order to achieve maximum test data from a smaller total sample size of each common usage part. This philosophy applies to parts such as meters, switches, wire, and connectors used in D&C subpanels of varying criticalities. Remaining parts will be qualified according to their particular criticality requirements.

At the subpanel level, the qualification program will include acceptance type tests, operational and wiring checkouts, some off-limit tests, and a modified Phase B or Mission Simulation-Life level test program.

A complete control console will be assembled and tested through the dynamic and operational test phases. A combined vacuum-temperature operating test and temperature-vibration test also will be run on the control console. At the conclusion of all other testing, an off-limit shock test will be performed.

The supplier will qualify parts; S&ID will qualify the subpanels assembled in house and the control console.

The IFTS will be qualified by the subcontractor.

5.14.2 Reliability Assessment Model

THE PERSON NAMED IN

The multiplicity and separate purpose of the subpanel assemblies of the control console do not lend themselves to the drawing of a comprehensive reliability assessment model. Therefore, Figure 5-58 depicts the reliability assessment model for the IFTS only. The individual system subpanels are







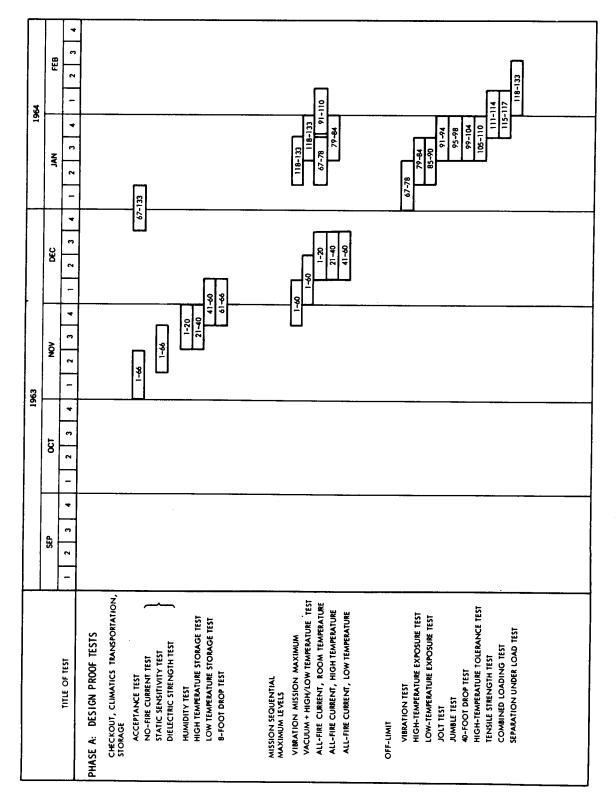


Figure 5-57. Explosive Bolt Qualification Test Schedule



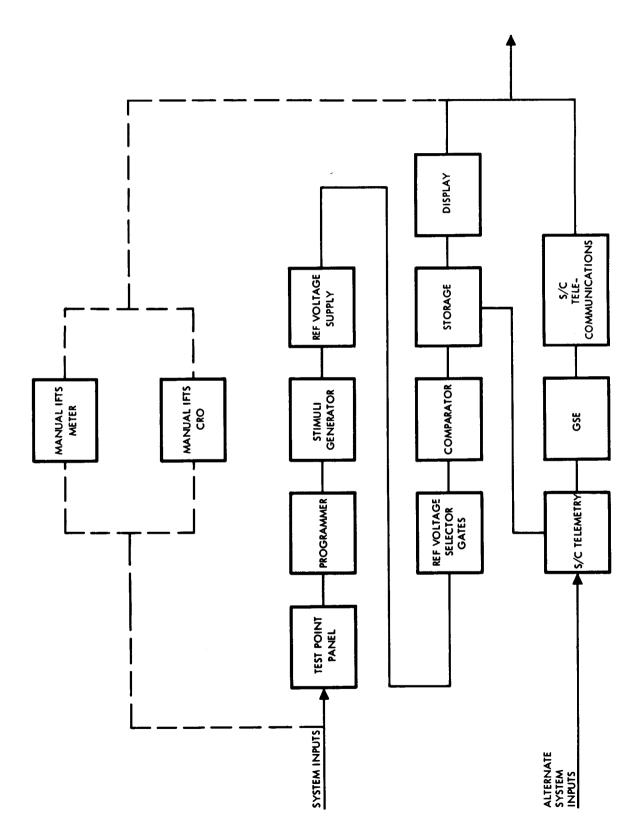
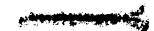


Figure 5-58. IFTS Reliability Assessment Model

3 .







a part of that system model and are used as such. The IFTS model will aid in establishing test continuity and in programming the collection of data for the assessment of reliability by illustrating the functional and reliability interrelationships of the system components.

5.14.3 Criticality and Hardware Requirements

Table 5-24 designates the criticality class, as defined in Section 2.4, for the components of the ES. The table enumerates the hardware requirements for a minimum qualification program, as established in Section 2.5. The distribution of the hardware through the subsystem qualification test phases, as described in Section 2.3, is shown. The location of the components in the spacecraft is indicated by spacecraft zone numbers, as defined in Section 4.2. This table will be completed as information becomes available.

5.14.4 Qualification Test Schedule

Figure 5-59 displays the qualification test schedule for the D&C subpanel assemblies and control console, and defines the test utilization of the hardware enumerated in Table 5-24. Subpanel assemblies numbered 2, 4, 6, 7, 9, and 14 will be qualified at the subpanel level by the vendor or subcontractor at his own facility. S&ID will qualify the console at the system level.

Figure 5-60 displays the qualification test schedule for the IFTS and defines the test utilization of the hardware enumerated in Table 5-24.

The specific test levels to be applied in qualification testing are found in the tables of environmental test criteria in Section 4.2 and are a function of the zone location of the equipment in the spacecraft. The zone number is given in Table 5-24.







one makes

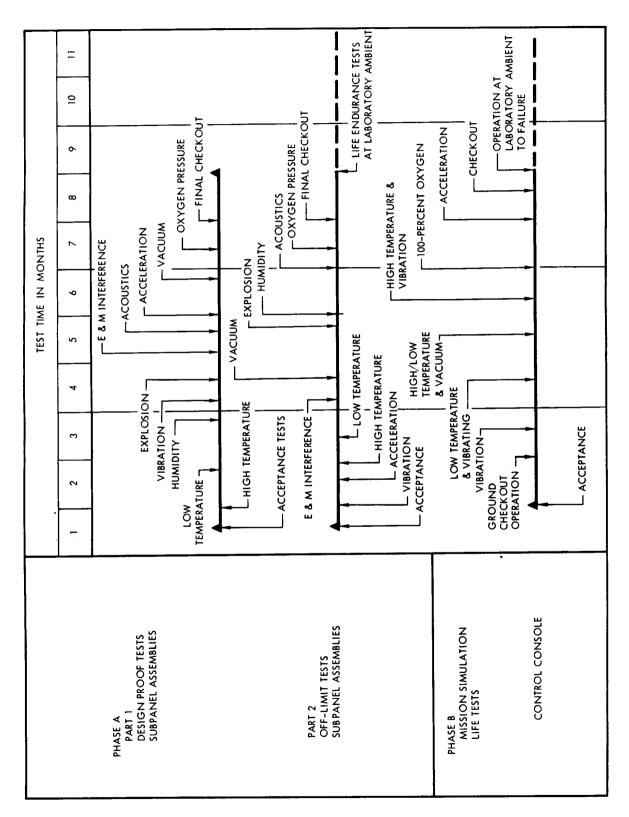
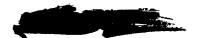


Figure 5-59. D & C Qualification Test Schedule





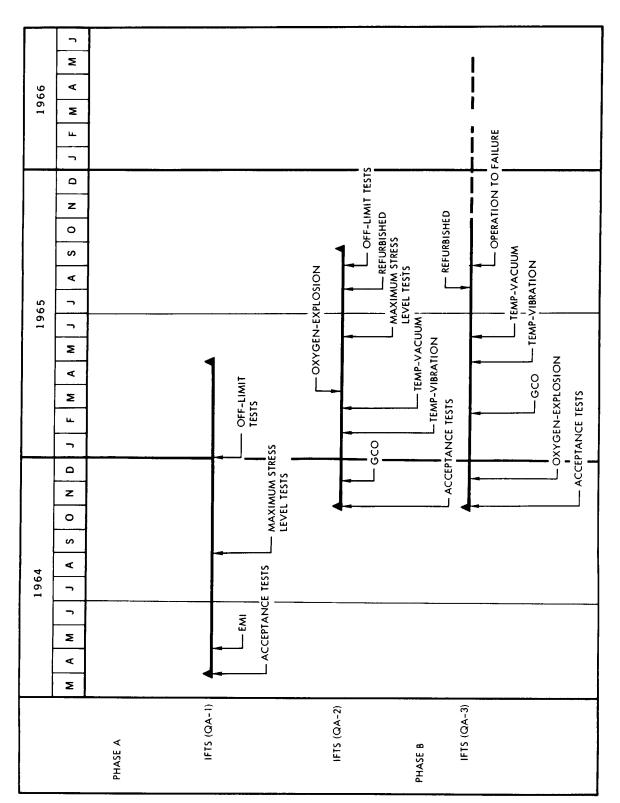


Figure 5-60. In-Flight Test System Qualification Test Schedule





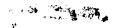
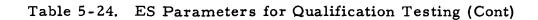


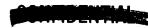
Table 5-24. ES Parameters for Qualification Testing

				Test Ph	ase Distr	ibution
Subpanel Assemblies and Component Parts	S/C Zone		Required Hardware	A-1	A-2	В
1. Barometric indicator	2	3	5	5	2	2
2. Entry monitor display* 2. 1 Switch, toggle 2. 2 Indicator light	2	2	5	4	2	2
 Emergency detection system and gimbal drive control 1 Switch, toggle (4 each) 2 Annunciator light (3 each) Meter, electrical 	2	2	5	4	2	2
4. FDAI (SCS)*						
 5. Emergency detection system and sequencer display 5. 1 Switch, push-type (3 each) 5. 2 Annunciator light (29 each) 5. 3 Timer, event, digital countout 	2	1	7	5	2	1
 6. Attitude set and GPD* 6. 1 Switch, toggle 6. 2 Potentiometer (5 each) 6. 3 Attitude indicator (3 each—roll, pitch and yaw) 6. 4 Indicator, gimbal position (yaw and pitch) 						





	646	Cuiti	Deminal	Test Pha	ase Disti	ibution
Subpanel Assemblies and Component Parts		cality	Required Hardware	1	A-2	В
 7. \(\Delta \text{V display*} \) 7. l Indicator, \(\Delta \text{V} \) remaining 7. 2 Switch toggle 7. 3 Indicator \(\Delta \text{V} \), set 7. 4 Indicator tail-off 						
8. Spare panel						
 9. SCS control and mode select* 9. 1 Switch, toggle (9 each) 9. 2 Switch, pushbutton (8 each) 						
10. Master caution (left- hand) 10.1 Annunciator (19 each)	2	3	3	2	2	1
11. Master caution (right-hand) 11.1 Annunciator (21 each)	2	3	3	2	2	1
12. RCS, GMT, static port valve 12. 1 Meter, electrical 12. 2 Annunciator 12. 3 Meter (2 each) 12. 4 Digital counter 12. 5 Switch, rotary 12. 6 GMT, display 12. 7 Switch, toggle	2	2	5	3	2	1





ATION, INC.

Table 5-24. ES Parameters for Qualification Testing (Cont)

	616	G		Test Pha	se Distri	bution
Sub-Panel Assemblies and Component Parts	S/C Zone	ı	Required Hardware	A-1	A-2	В
13. Radiation, audio, cryogenic and ECS system 13.1 Switch, toggle (13 each) 13.2 Potentiometer (4 each) 13.3 Meter, electrical (7 each)	2	2	5	3	2	1
14. G&N computer control* 14. 1 Annunciator (11 each) 14. 2 Potentiometer (2 each) 14. 3 Switch, pushbutton						
15. Reaction control system 15. 1 Switch, toggle (18 each) 15. 2 Light, indicating (16 each)	2	2	5	3	2	1
16. Crew safety control panel 16. 1 Switch, toggle (12 each)						
17. Oxygen warning 17. l Annunciator		:				
18. Fuel cells and electrical power system 18.1 Switch, toggle (28 each)						





i k

Table 5-24. ES Parameters for Qualification Testing (Cont)

	- / -			Test Phase Distri		ibution
Sub-Panel Assemblies and Component Parts	S/C Zone	Criti- cality	-	A-1	A-2	В
18. 2 Meter, electrical (4 each) 18. 3 Switch, rotary (4 each) 18. 4 Light, indicating (14 each) 19. Antenna control system 19. 1 Switch, toggle (5 each) 19. 2 Switch, rotary 19. 3 Indicator, position, roll and yaw 19. 4 Indicator, tune to				·		
max 19.5 Annunciator (2 each) 20. Command data-link and service propul- sion system 20.1 Switch, toggle (30 each) 20.2 Potentiometer 20.3 Switch, rotary 20.4 Meter, electrical (3 each) 20.5 Switch, rotary (4 each) 20.6 Indicator 20.7 Display, digital counter 20.8 Annunciator (4 each)	2	2	5	3	2	1

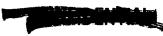








Table 5-24. ES Parameters for Qualification Testing (Cont)

				Test Pha	ase Distr	ibution
Sub-Panel Assemblies and Component Parts	S/C Zone		Required Hardware	A-1	A-2	В
21. Right-hand side console, bus, switch- ing 21.1 Switch, rotary (9 each) 21.2 Switch, toggle						
22. Right-hand side console circuit breaker and bus switching 22. 1 Circuit breaker switch (83 each) 22. 2 Switch, toggle (7 each) 22. 3 Switch, rotary (6 each)	2	3	3	2	1	1
23. Right-hand side console audio and lighting control 23. 1 Potentiometer (3 each) 23. 2 Switch, toggle (7 each) 23. 3 Rheostat	2	2	5	3	2	1
24. Left-hand side console, mission sequence controls 24. 1 Switch, toggle (8 each)	2	2	5	3	2	1
25. Left-hand side console, circuit breaker and SCS power 25. 1 Circuit breaker switch (50 each)	2	2	5	3	2	1



Table 5-24. ES Parameters for Qualification Testing (Cont.)

Sub-Panel Assemblies	s/C	C:4:	Dominod	Test Phase Distribution				
and Component Parts	•	1	Required Hardware	A - 1	A-2	В		
25. 2 Switch, rotary (4 each) 25. 3 Switch, toggle								
26. Left-hand side console, audio and lighting control 26. 1 Rheostat 26. 2 Switch, toggle (7 each) 26. 3 Potentiometer (3 each)	2	3	3	2	1	1		
	SYST	EM LE	VEL		····			
Control console in-flight test system	2	2	3	3	2.	1		
Qualified by Vendor, Subcontractor or Associate Contractor								





6.0 GROUND SUPPORT EQUIPMENT

6.1 SCOPE

This section is devoted to detailed descriptions of the qualification test program as applied to the various types and classes of ground support equipment required to support the Apollo Project and that will be the responsibility of S&ID. The program has many constraints which govern and limit the scope of the qualification program. The test planning has, therefore, been designed to work within these bounds.

The sample size has been limited, in most cases, to one item. In some cases, that item is also the end item to be delivered. Additional items will be required for certain mission essential classes where the contribution of the component to the mission is comparable with spacecraft systems requiring many more components for qualification.

There are many categories and classes of GSE required in support of Apollo and varying degrees of essentiality within these categories; each must have a program specifically tailored to the class and item. This document will cover only the basic categories.

In many cases, the time available for qualification testing is severely limited, allowing time for only a bare minimum of qualification; in some instances, qualification tests approach acceptance tests in scope. This is particularly true for items that are required for support of the early boiler-plate programs.

Other constraints, such as facilities scheduling and varied environments at the points of application, have complicated the program planning. In spite of this, the program, presented herein, is considered a reasonable compromise.

6.2 GSE QUALIFICATION TEST LOGIC

The over-all concept of the GSE test program is similar to that used for the spacecraft equipment; however, the sample sizes are more severely limited. The sample sizes and the scope of the test program are a function of the particular contribution to the mission and the criticality class of the test item.

Qualification tests of appropriate parts, components, subassemblies, and higher levels of assembly will demonstrate that the design is inherently capable of meeting the performance and environmental requirements specified for the application. The tests will be performed at the most practical





A A STATE OF THE S

level of assembly. Qualification tests are divided into two phases: phase A, design proof, and phase B, life tests.

The tests are also categorized by the equipment groups. The groups being defined on the basis of ramifications in mission success and crew survival. See Figure 6-1 for the distribution by category and function. The test applications to those categories are covered in paragraph 6.5. The maximum qualification program, as applied to mission essential equipment (MEE, defined in paragraph 6.4.2), is composed of the following:

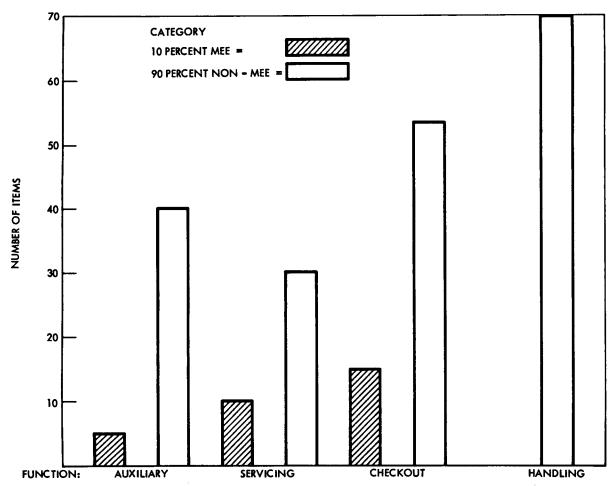


Figure 6-1. Distribution of Essential and Nonessential Ground Support Equipment

6.2.1 Phase A, Design Proof

Design proof testing includes:

- 1. Transportation and handling per MIL-E-4970A
- 2. Electromagnetic interference (EMI) per S&ID Specification MC 999-0002B
- 3. Off-limit tests, functional and nondestructive.









6.2.2 Phase B, Life Tests

Life testing will be applied to mission essential units and certain other components requiring a long life because of their intended use. The tests will consist of exposure to natural environments as delineated herein. Each unit assigned to life tests will be required to complete a given number of simulated use-operation cycles without any failures. The number of cycles required for qualification will be limited to one, except for mission essential components that are determined as a function of criticality. The use of spares during the qualification cycle will not be permitted. Upon completion of the prescribed number of cycles for qualification, limited life items may be replaced, as required, and the equipment will then be subjected to additional cycles in order to make at least four cycles before the life test has been completed.

The number of cycles imposed on a piece of mission essential GSE to qualify it has been made a function of its contribution to the mission. This is defined by criticality class. The criticality classes for GSE were derived in much the same manner as those for the spacecraft, except that the definitions are based on the ramification of a GSE induced failure or a failure that was not detected. The remaining series of cycles are required to establish repeatability of the required characteristics, to demonstrate the life objective, and to provide maintainability assurance.

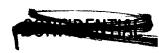
6.3 OPERATIONAL READINESS

6.3.1 Reliability Assessment

The reliability assessment program will be planned in accordance with apportioned program objectives. No additional hardware will be employed exclusively to assess reliability. The program includes specific ground rules for choice and application of data from all areas of testing. The actual assessment of reliability will be accomplished by an analytical treatment of data from tests designed to determine performance margins and life characteristics. Qualification testing will be monitored and controlled to assure maximum usefulness of the derived data for reliability assessment purposes.

6.3.2 Availability

It should be noted that reliability is not the best assessment figure of merit for GSE. Availability is a more applicable term and will be applied in the assessment program for Apollo GSE. Availability, as herein used, is analogous to operational readiness and is equal to the total operational inservice time divided by the sum of operational inservice time plus active repair time. Active repair time excludes logistic considerations. The





measure of this active repair time is termed mean-time-to-repair (MTTR). A goal of 30 minutes has been set as the allowable active repair time.

6.4 GSE CATEGORIES

6.4.1 Concept

The GSE must be divided into basic categories in order to properly establish the scope of the qualification program. It, therefore, has been divided as a function of the contribution to mission success or crew survival, as follows:

- 1. Mission essential equipment (MEE)
 - a. Checkout
 - b. Auxiliary
 - c. Servicing
- 2. Mission nonessential equipment (MNEE)
 - a. Checkout
 - b. Auxiliary
 - c. Servicing
 - d. Bench maintenance
 - e. Handling

6.4.2 Definition of Mission Essential (MEE)

A piece of GSE is classified as mission essential if it is in a closed loop with the spacecraft just prior to or during countdown, so that it:

- 1. May fail to detect a malfunction
- 2. May introduce a malfunction into spacecraft equipment
- 3. May cause a complete countdown recycle

6.5 GSE ENVIRONMENTS

The GSE is to be subjected to two classes of environments as a function of equipment use and location. The environments to be applied are presented by equipment category in Table 6-1. The detailed values applied are given in the specific test plans in subsequent paragraphs. It should be noted that salt fog, sand and dust, and rain are only applied to mission essential equipment employed in unsheltered areas. As in spacecraft tests, it has been assumed, with NASA concurrence, that the GSE will receive special handling.







Table 6-1. GSE Qualification Test Environments and Sequence

	Mission	-Essential	Mission-Nonessential			
Test Environments	Sheltered Equipment	Unsheltered Equipment	Sheltered Equipment	Unsheltered Equipment		
Function Checkout	1	1	1	1		
High Temperature	4	4	4	4		
Low Temperature	3	3	3	3		
Low Pressure	2	2	2	2		
Humidity	7*	7	7*	7*		
Vibration	6	6	6	6		
Shock	5	5	5	5		
Salt Fog		8*	1			
Sand and Dust		9*	İ			
Rain		10*				
Operating Temperature		11		8		
Tilted Position	8*	12*	8*	9*		
Electromagnetic Interference	9	13	9	10		
Noise	10*	14*	10*	11*		
Lifting	11*	15*	11*	12*		
Dielectric	12	16	12*	13*		
Insulation	13	17	13*	14*		
Continuity	14	18	14*	15*		
Life	15	19	15	16		

*Where applicable

Note: The numbers indicate the suggested sequence or application









6.6 QUALIFICATION FOR MISSION ESSENTIAL EQUIPMENT (MEE)

6.6.1 Design Proof Tests

Design proof tests are generally conducted in accordance with MIL-E-4970A. They consist of three different steps: environmental, EMI, and functional off-limit tests.

6.6.1.1 Environmental Tests

General test conditions, tolerances, etc., will be in accordance with requirements of Section 3 of MIL-E-4970A, as follows:

- 6.6.1.1.1 <u>Temperature</u>. Temperature tests will be conducted to determine the effects of high and low temperatures on equipment during transportation, storage, and operation.
- 6.6.1.1.1.1 High Temperature (Nonoperating). Nonoperating high temperature tests will be performed according to Paragraph 4.1.2 of MIL-E-4970A, except that the test temperature will be reduced to +140 F because of the modified environments applied to Apollo.
- 6.6.1.1.1.2 Low Temperature (Nonoperating). The nonoperating low temperature test will be performed according to Paragraph 4.3.3 of MIL-E-4970A with the following modifications:
 - 1. The chamber temperature will be reduced to minus 20 F because of the modified environments applied to Apollo GSE.
 - 2. The operational check will be accomplished when the temperature of the item returns to the prevailing room temperature.
- 6.6.1.1.1.3 Operating Temperature Tests. The equipment will be placed within the test chamber and the internal temperature of the chamber will be raised to +120 F. The equipment will be operated while exposed to this temperature for a period of 42 hours. The chamber temperature will then be lowered to +30 F for another 42 hours of operation. While in the temperature chamber, the equipment operation will simulate the in-service requirements, and the performance during this test will conform to the requirements of the governing document.
- 6.6.1.1.2 Low Pressure. Low pressure tests will be conducted to determine the ability of the equipment to operate satisfactorily under reduced pressure conditions where higher altitude operation is deemed a potential problem and also to determine the ability of the equipment to withstand air transportation in a nonoperating condition.





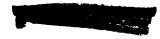


- 6.6.1.1.2.1 Procedure. The low pressure tests will be performed according to Paragraph 4.4.1.1 of MIL-E-4970A, except that the internal absolute pressure will be reduced to 7.04 inches of mercury (corresponding to an altitude of 35,000 feet above sea level) instead of 3.42 inches of mercury. This is applied only as a nonoperating environment where air transit is involved.
- 6.6.1.1.3 <u>Humidity Tests</u>. Humidity tests are conducted to determine the resistance of equipment to the effects of exposure to a warm, highly humid atmosphere, such as is found in the beach areas at AMR.
- 6.6.1.1.3.1 Procedure. Humidity tests will be performed in accordance with Paragraph 4.3.1 of MIL-E-4970A as modified below:
 - 1. The temperature for the first portion of each cycle will be 122 F.
 - 2. Total test time for the humidity test will be 48 hours (2 cycles).
- 6.6.1.1.4 <u>Vibration Tests</u>. Vibration tests are conducted on equipment to determine the effects of vibrations encountered during transportation and handling.
- 6.6.1.1.4.1 Procedure. The vibration test procedure will be in accordance with Procedure VI of MIL-E-4970A, Paragraph 4.6.8. For items of less than 1000 pounds, Table III of Paragraph 4.6.8 will be used. For items over 1000 pounds, the Table 6-2 will apply:

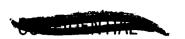
Required Range CPS	Vibratory Double Amplitude or Peak Acceleration	Type of Test
2-20	± 1.04g	Resonance search only
20-52	0.029 inch	Cycling and at resonance
52-500	± 3.33g	Cycling and at resonance

Table 6-2. Vibration Tests for Items Over 1000 Pounds

- 6.6.1.1.5 Shock Tests. Shock tests will be conducted on equipment to determine the effects of shocks to be encountered during transportation and servicing.
- 6.6.1.1.5.1 Procedure. The shock tests will be conducted in accordance with Paragraph 4.12.2 and 4.12.6 of Specification MIL-E-4970A for







items of equipment weighing less than 1000 pounds. For items weighing over 1000 pounds, the tests will be the same, except an 18-g shock will be applied instead of the 20-g shock because of anticipated dampening effects.

- 6.6.1.1.6 Sand and Dust Tests. Sand and dust tests will be performed only on equipment that is sensitive to sand and dust and is expected to have an end use in an unsheltered area.
- 6.6.1.1.6.1 Procedure. The sand and dust test procedure will be in accordance with Procedure I of Paragraph 4.10.1 of MIL-E-4970A.
- 6.6.1.1.7 Salt Fog. Salt fog tests will be conducted only on equipment that may be sensitive to a salt atmosphere as encountered in ocean coastal areas and has an end use in an unsheltered area.
- 6.6.1.1.7.1 Procedure. Salt fog tests will be conducted in accordance with Paragraph 4.5.1 of MIL-E-4970A.

6.6.1.2 Electromagnetic Interference Test

Electromagnetic interference tests will be applied to relevant GSE components as delineated in S&ID Specification MC 999-0002B without modification.

6.6.1.3 Off-Limit Test

Off-Limit tests, as applied to Apollo GSE, are functional tests designed to verify that the design is resistant to critical failure modes. The specific application of this test will be determined by failure mode and effect analyses currently in process. Specific data will be contained in later revisions of this document. The tests will be applied only to mission essential equipment in GSE criticality Classes I and II, as defined in Paragraph 6.6.2.2. They will be designed to be nondestructive in nature.

6.6.2 Life Test

6.6.2.1 Concept

Life tests, as applied to mission essential equipment, are a series of tests designed to verify tolerance to critical parameter variations and total equipment performance as a function of accrued operating time. The tests are to be performed, using limited combined environments, when and if a failure mode analysis indicates potential critical failure modes in these environments, within the definition of Paragraph 6.4.2.







The second second

Life tests provide a second and equally necessary function, that of determining the availability (A) of the equipment and its average downtime or mean-time-to-repair (MTTR). This is necessary in order to establish that the equipment can, in case of a malfunction, still meet the mission objectives. It is anticipated that a reasonable level of reliability and maintainability data will be derived as a result of these tests.

Life tests, as herein described, are applied predominantly to mission essential equipment. A modified version, however, is applied to dynamic equipment in other GSE categories when usage demands. These are employed only to demonstrate a life requirement, compatible with value consideration and an operational readiness stature.

6.6.2.2 Criticality as applied to GSE

The time of exposure to the test cycle has been derived on a compatible basis with that of the spacecraft mission life tests (MLT) and is a function of service life and criticality. Since the spacecraft MLT time was based on the contribution of the equipment to mission success or crew survival, criticality for GSE is similarly defined. However, instead of a rigorous calculation of a specific criticality number, three criticality categories were established by qualitative definition.

The following is a list of criticality classes and the definitions of each:

Class I = May prejudice crew survival

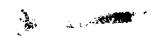
Class II = May cause a pad or in-flight abort

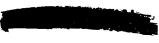
Class III = May cause a countdown recycle (including limited holds)

(Within the definition of mission essential of Paragraph 6.4.2)

6.6.2.3 Application

6.6.2.3.1 Test Design. The life test is designed to accommodate all classes of criticality. However, qualification is determined on the basis of the specific class. Reference is made to Figure 6-2, where a time line diagram is given for the life test. Each component subjected to the life test is required to complete four cycles of operation consisting of a simulated preparation (prior-to-launch) phase and a mission (pad operations) phase. These tests may be terminated at the life requirement if it is less than the time equivalence of four full cycles. Some refurbishment will be allowed and, in fact, is anticipated because of the small sample sizes. Qualification of the component is contingent on passing Cycle 1 for Class III criticality.







Cycle 2 for Class II criticality, and Cycle 3 for Class I criticality. Stipulated failure rates, maintenance time constraints, and availability must not be exceeded. These are not based on statistical confidence but merely upon a simple calculation employing formulae which yield no statistical confi-

dence but do provide some indication of equipment capability.

Mean time between failure = $\frac{\text{Total test time}}{\text{Number of failures}}$ = $\frac{500 \text{ hours MEE}}{300 \text{ hours MNEE}}$ Maintenance time constraint = $\frac{\text{Downtime (active)}}{\text{Number of failures}}$ = $\frac{30 \text{ minutes}}{\text{Number of failures}}$ Availability (A) = $\frac{\text{MTBF}}{\text{MTBF + MTTR}}$ = 0.999 (for MEE)

	ONE SIMULATED USE - OPERATION CYCLE						
PREPARATION	1 PHASE	MISSION PHASE					
FACTORY CHECKO	DUT						
S&ID IN- HO	DUSE	PAD (OPERATIONS				
S&ID AND N	IASA, OFF - SITE						
300 HOL	irs	100 HOURS					
	TIME LINE	FOR LIFE TEST					
		LASS II CLASS I					
CYCLE 1	CYCLE 2	CYCLE 3	CYCLE 4				

Figure 6-2. Life Test Application







6.6.2.3.2 <u>Use — Operation Cycle Time</u>. The time imposed for one-cycle use operation is derived from the following calculation. This is based on past experience, extrapolated from what is defined and anticipated for Apollo. These are average times and are not considered rigorous at this time.

	<u></u>
Factory checkout and acceptance	65 hours
S&ID Downey use	110 hours
On-site (prior to launch operations)	125 hours
Pad use (includes three countdown recycles)*	100 hours
	Total 400 hours
*Applied only to MEE	

6.7 QUALIFICATION TESTS FOR MISSION NONESSENTIAL EQUIPMENT (Exclusive of Handling Equipment)

6.7.1 Design Proof Tests (MNEE)

The design proof tests, as applied to the mission nonessential equipment, exclusive of handling equipment, will be based also on MIL-E-4970A, except that the EMI tests will be as delineated in S&ID Specification MC 999-0002B. The specific series of environments to apply to a given category of nonessential GSE is delineated in Table 6-1.

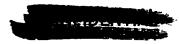
6.7.2 Life Tests (MNEE)

1

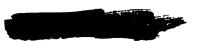
Life tests, as applied to the mission nonessential GSE, are a modified version of those specified for the MEE, as delineated in Paragraph 6.6.2. The basic differences are that they will always be conducted under local ambient conditions and that qualification will be based on the specified life of the equipment. The test will not be applied to all equipments in this category but will be limited to those dynamic type equipments deemed to be critical enough to require life demonstration.

6.8 QUALIFICATION TESTS FOR HANDLING-TYPE EQUIPMENT

The qualification tests planned for this type of equipment are limited to an expanded acceptance-type test since no items are set apart exclusively for qualification. All components in this category will be subjected to non-detrimental tests, as delineated in Paragraph 6.8.1. The specific application of these tests varies considerably between components and will be covered in the subsequent revision of this volume.









6.8.1 Test Types

- 1. Detailed examination of product
- 2. Special Nondestructive analysis, such as infrared, magnaflux, and X-ray
- 3. Proof load tests

Specific information on the nature and application of these tests is given in Volume IV, Acceptance Test Plan, of this series.



7.0 INTEGRATED SYSTEMS QUALIFICATION

7.1 SCOPE

This section will be confined to qualification and reliability program requirements and objectives to be accomplished prior to and in support of any and all phases of integrated systems testing. In the logical evolution of a fully qualified Apollo spacecraft, test objectives must be established that assure component and subsystem qualification or flight worthiness for each boilerplate or airframe test. These test objectives are best realized by preflight analysis of vehicle readiness and establishment of success criteria termed "interim qualification requirements" based on the mission objectives, which in turn form the control measures to be satisfied before a given flight should be attempted.

7.1.1 Purpose

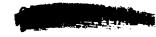
A twofold purpose exists for the qualification requirements of the integrated systems tests. In chronological order, these are to assess the flight readiness of the test vehicle and its components and to predict the probability of success of the mission relative to its objectives. The assessment of flight readiness and the prediction relevant to test success serve to optimize the extent and interaction of each test objective in relation to the over-all qualification program.

7.1.2 Method

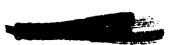
A flight/qualification flow chart has been developed to show the philosophy and implementation of integrated systems testing. Interim qualification requirements are delineated in tabular form for each flight vehicle in ascending order of severity as the mission objectives become increasingly more complex and extensive. The intent is to always ensure a reasonable probability of accomplishing the mission objectives.

7.2 FLIGHT/QUALIFICATION FLOW CHART

The flight/qualification flow chart presents a composite picture of the integrated systems test program. The boilerplate test program (Figure 7-1),









with its corresponding on-board systems, is separated from the airframe program (Figure 7-2). This should not, however, detract from the continuity of flow which exists between the two.

7.2.1 Flight Test Vehicles

The flight articles are blocks arranged horizontally to correspond to the test site with their flight dates represented by the right border. The block length has no scheduling significance.

7.2.2 Nonflyable Vehicles

Nonflyable articles are the cross-hatched areas drawn to correspond to their respective test schedules. These articles include the house spacecrafts, B-14, AFRM 006, the propulsion test spacecraft, AFRM 001, and the environmental proof airframe, AFRM 008, from which the test data will be utilized to support qualification of flight articles for all phases of the test program.

7.2.3 Flow Chart Utilization

Figure 7-1 depicts the integrated system test planning flow and the logical evolution of the ground qualification program as they parallel and augment the flight test program. The intent is to ensure a well-balanced test program, accomplishing first those tests that can be performed under simulated conditions on the ground and then augmenting and verifying results by actual flights. The qualification flow is shown by lines accompanied by a statement as to anticipated qualification status at key points. Some of these are between the particular flight articles; and between the articles and the integrated systems tests, such as propulsion tests and environmental tests conducted at other facilities. Individual systems qualification and development test status is shown relative to the launch dates. In the next revision, the explicit installation dates for the system in each test article will be shown as vertical arrows on the system test bar at the appropriate date. This will not only indicate in which article each system is to be installed, but will also mark the stage of development or qualification testing each system has undergone prior to its installation.

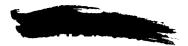
7.2.4 Sample Application

بري 📑

To illustrate the utilization of the flight/qualification flow charts, Figures 7-1 and 7-2, B-12 is chosen as an example. The mission assignment for B-12 is the Max-q LES verification. From the flow of the boilerplate test program (Figure 7-1), it may be seen that B-6, whose mission assignment is pad abort, precedes B-12. Also, the LES tower and motors, the parachutes, and the solid-state abort sequencer are not qualified









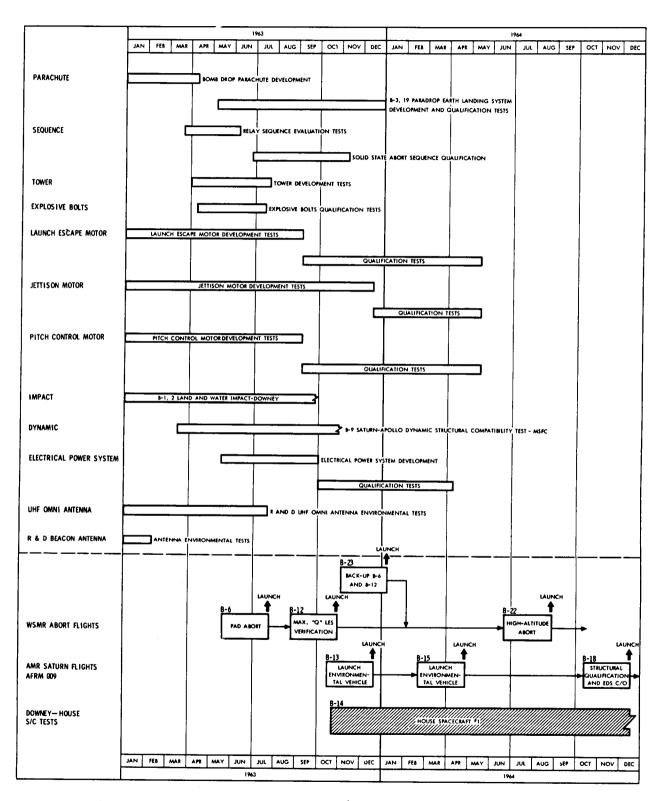
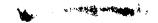
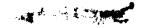


Figure 7-1. Boilerplate Flight/Qualification Flow Chart





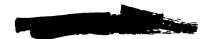




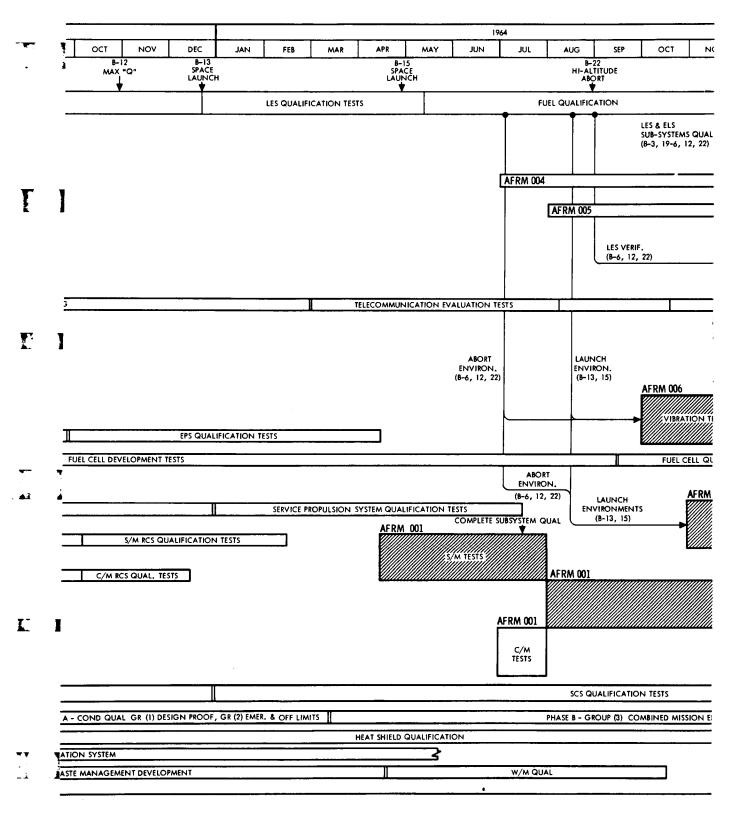
at the time of installation on board B-12. The explosive bolts, however, are qualified. The qualification requirements for B-12, therefore, will consist of two groups. The first group will be components and systems that are ground-qualified prior to flight and may include partial flight qualification, such as explosive bolts on B-6. The second group will be those components and systems that are not ground-qualified at the time of installation on the specific test vehicle. Special qualification requirements, to be known as "interim qualification requirements," are generated to encompass the latest status of development for the latter group.

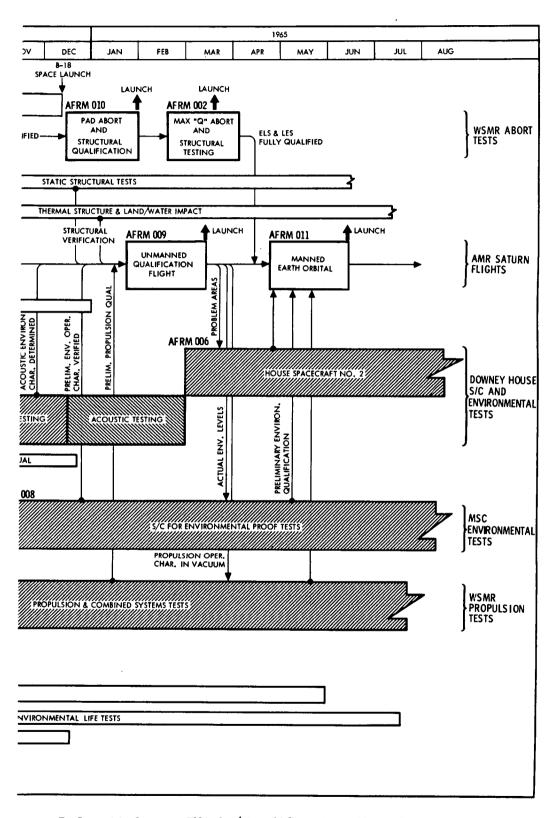
These special tests are usually extracted from the applicable procurement specifications or Apollo test requirements, each of which has specified the test required to qualify the systems. A representative selection is made based upon the types of environments the flight will encounter. The sequence of testing duplicates the events as scheduled for the limited mission.

1



· · · · · · · · · · · · · · · · · · ·									
	NAL	FEB	MAR	APR	MAY	JUN	963 JUL	AUG	SEP
	3/11			1			B-6 PAD AB	<u></u>	
									<u>.</u>
LAUNCH ESCAPE SYSTEM						LES DEVELO	DPMENT TEST		
TELECOMANNIALICATIONIC						TELECOM	MUNICATION	DEVEL OPMEN	IT TESTINI
TELECOMMUNICATIONS						TELECOM	MUNICATION	DEVELOPMEN	41 1631114
						_			
ELECTRICAL POWER SYSTEM							ELEC, POWE	R SYST DEVE	L TESTS
FUEL CELL									
SERVICE PROPULSION SYSTEM				SERV	ICE PROPULSI	ON SYSTEM	DEVELOPMEN	T TESTS	
							·		
S/M REACTION CONTROL SYSTEM			S/M REACTION	CONTROL	SYSTEM DEVE	LOPMENT TE	STS		
C/M REACTION CONTROL SYSTEM		C/M REACTI	ON CONTROL	. SYSTEM DE	/ELOPMENT		I		
•									
STABILIZATION CONTROL SYSTEM				STAB	ILIZATION C	ONTROL SYS	STEM DEVELOP	MENT TESTS	
ENVIRONMENTAL CONTROL SYSTEM		Eh	NVIRONMENTA	AL CONTROL	SYSTEM DEV	ELOPMENT T	ESTS		PHASE
HEAT SHIELD			HEA	T SHIELD DE	VELOPMENT	TEST			
GUIDANCE AND NAVIGATION SYSTEM				·				GUIDANCE	& NAVIG
WASTE MANAGEMENT									W





gure 7-2. Airframe Flight/Qualification Flow Chart





NOMENCLATURE

A listing of the special nomenclature and abbreviations used in this report is presented. These listings may appear interchangeably with their full definitions in the text. Accepted abbreviations for units of physical measurement such as volts, ohms, etc. are not included.

Abbreviation

Definition

AEDC

Arnold Engineering Development Center

AFMTC

Air Force Missile Test Center

AFRM

Airframe

AGAP

Attitude gyro and accelerometer package

AGC

Aerojet-General Corporation

AGC

Automatic gain control

AGC

Apollo guidance computer

AGREE

Advisory group on reliability of electronic equipment

AMR

Atlantic Missile Range

ATO

Apollo Test and Operations

BAL

Balance

BCD

Binary coded decimal

B-#

Boilerplate - # (with specific number)

в/м

Bench maintenance

BMAG

Body-mounted attitude gyros

BOD

Beneficial occupancy date

B/P

Boilerplate

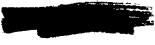








Abb	r	evi	ati	on
-----	---	-----	-----	----

Definition

Cape Canaveral Missile Test Annex CCMTA

Controls and displays C&D

Communications and data subsystems CDS

CDU Coupling display unit

Center of gravity CG

Communications and instrumentation system C&IS

Command module C/M

C/O Checkout

C-0 Crew operated

Control panel CP

Central timing unit CTU

Change verification record CVR

Display electronic assemblies DEA

Direction finding \mathbf{DF}

Department of Defense DOD

Degrees of freedom DOF

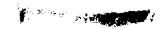
Design proof DP

Design proof test DPT

Deep Space Instrumentation Facility DSIF







Abbreviation

Definition

DVD

Differential velocity display

EBW

Exploding bridge wire

ECA

Electronic control assembly

ECS

Environmental control system

EDL

Engineering Development Laboratory (S&ID Dny)

ELS

Earth landing system

EMI

Electromagnetic interference

EPS

Electrical power system

ΕT

Escape tower

FDAI

Flight director attitude indicator

FM

Frequency modulation

FAX

Facsimile transmission

G, g

Acceleration of gravity

G&NS

Guidance and navigation system

GOSS

Ground operational support system

GP

General purpose

GPI

Gimbal position indicator

GSE

Ground support equipment

HAA

High-altitude abort

HBW

Hot bridge wire

H/A

Hazardous area











Abbreviation

Definition

IFT&M

In-flight Test and Maintenance

IMCC

Integrated Mission Control Center

IMU

Inertial measurements unit

INT

Interior

INST REF

Instrument reference

IRIG

Inter-range instrumentation group

L-

Time before launch (days)

LAD

Los Angeles Division (or NAA)

L/D

Length-diameter ratio

LEM

Lunar excursion module

LEV

Launch escape vehicle

LES

Launch escape system

LJII

Little Joe II

LOR

Lunar orbit rendezvous

LSS

Life support system

L/V

Launch vehicle

MDSS

Mission data support system

M -#

Mockup - # (with specific number)

Max q

Maximum dynamic pressure

MEE

Mission essential equipment







to only the second

Abbreviation

Definition

MIT

Massachusetts Institute of Technology

MLT

Mission life test

MNEE

Mission non-essential equipment

MSC

Manned Spacecraft Center (NASA, Houston, Texas)

MTBF

Mean time before failure

MTTR

Mean time to repair

NAA

North American Aviation

NASA

National Aeronautics and Space Administration

O/F

Oxidizer-to-fuel ratio

OPS

Operations

OTP

Operational test procedure

 $\mathbf{P}\mathbf{A}$

Power amplifier

PACE-S/C

Prelaunch automatic checkout equipment - spacecraft

PAM

Pulse amplitude modulation

PCM

Pulse coded modulation

PCM

Pulse code modulator

PDM

Pulse duration modulation

 P_{f}

Probability of failure

 $P_{f_{D}}$

Probability of performance failure

 P_{f_S}

Probability of stress failure

PFRT

Preliminary Flight Rating Test

POD

Prelaunch Operations Division (NASA)



Abbreviation

Definition

 P_s

Probability of success

PSA

Power and servo assembly

PTT

Push to talk

PUCS

Propellant utilization control system

P&WA

Pratt & Whitney Aircraft

R/B

Radar beacon

R/C

Radio command

RCC

Range control center

RCS

Reaction control system

R&D

Research and development

REG

Regulator

RF

Radio frequency

RFI

Radio frequency interference

RFWAR

Requirements for work and resources

RGP

Rate gyro package

R&Z

Range and zero

SA

Saturn Apollo

SCAT

Space communications and tracking

SCD

Specification control drawing

SCIP

Self-contained instrumentation package

SCO

Subcarrier oscillator

SCR

Silicon-controlled rectifier





THE PARTY OF

Abbreviation		Definition
SCT	Scanning telescope	
S/C	Spacecraft	

S/C _a	Spacecraft adapter

SCS	Stabilization and	control	system

SEP	Space	electronic	package
-----	-------	------------	---------

S/M	Service	module
-----	---------	--------

SPS	Service	propulsion	system
-----	---------	------------	--------

T -	Time	hafara	10ah
1 -	lime	before	launch

T-O	Time	of 1	aunch

T+	Time	2 ft 2 m	launch
1 1	1 me	aner	launch

T/M Telemeter

TP Test point

TPA Test preparation area

TPS Thermal protection system

T/R Transmitter receiver (combination in two packages)

TWT Traveling wave tube

TWX Teletype wire transmission

UDMH Unsymmetrical dimethyl hydrazine



4 🕹

Abbreviation

Definition

VCO

Voltage controlled oscillator

VLF

Vertical launch facility

VSWR

Voltage standing wave ratio

WSMR

White Sands Missile Range

XCVR

Transceiver (transmitter receiver in one package)



DEFINITION OF TERMS

ABLATE To carry away; to remove by cutting or

erosion, melting or evaporation. To undergo ablation; to become melted or vaporized and

removed at a very high temperature.

ABORT An uncompleted missile flight or an uncom-

pleted hold-down test resulting from a failure of equipment or of a system other than the one undergoing test. In a tactical operation

(simulated or real) a missile failure either on the ground or in flight; a missile that fails to

complete a programmed flight.

ADAPTER Flange or extension of a vehicle stage or

section providing a means of fitting another

stage or section to it.

AEROBALLISTICS Term derived from aerodynamics and ballis-

tics, dealing primarily with the motion of bodies whose flight path is determined by applying the principle of both sciences to

different portions of the path.

AEROTHERMODYNAMIC

BORDER

Area above an altitude of about 100 miles where the atmosphere becomes so rarefied that there is no longer any significant heat-

generating air friction on the skin of vehicles.

AIRFRAME Assembled structural and aerodynamic

components of an aircraft or missile.

ALBEDO The ratio of light reflecting from an unpolished

surface to the light falling upon it. Term is used in reference to light reflected from the

moon or planets.

AMBIENT CONDITIONS Environmental conditions such as pressure or

temperature; naturally existing conditions.

ANTHROPOMORPHIC Human-like; related to or designed for the

human body.



APOLLO

NASA designation for follow-up manned spaceflight program to Project Mercury manned orbital mission. Apollo spacecraft is to be suitable for manned earth-orbiting laboratory, manned circumlunar flight, manned lunar landing, and return.

ATLANTIC MISSILE RANGE (AMR)

A 5000- to 6000-mile instrumented range for testing ballistic and guided missiles located between Cape Canaveral, Florida, and a point beyond Ascension Auxiliary AFB, near the middle of the South Atlantic.

ATTITUDE

Orientation of an air vehicle as determined by the inclination of its axis to a frame of reference, usually the earth.

ATTITUDE JETS

Sometimes called steering jets, attitudecontrol jets or roll, pitch, and yaw jets; fixed or movable gas nozzles on a rocket, missile, or satellite operated continuously or intermittently to change attitude or position.

AXIS, AXES

Reference axes in the Apollo spacecraft are as follows:

X-axis

The X-axis is parallel to the nominal launch axis and is positive in the direction of initial flight.

Y-axis

The Y-axis is normal to the X-axis and is positive to the right of a crewman when the crewman is in his seat facing toward positive

Z-axis

The Z-axis is normal to both the X- and Y-axes and is positive in the direction of the crewman's feet when he is in his seat.

BACKUP

Designed to immediately follow an earlier space system or a project to complement the latter or take advantage of new techniques and processes; a system that can replace a failed system.





BENCH MAINTENANCE

EQUIPMENT

Equipment supporting component and subsystem testing; facilities capable of isolating, defining, and providing remedial action to malfunctions.

BIOMEDICINE

Combined discipline of biology and medicine for analysis of human tolerances to and protection against environmental variances.

BOILERPLATE

Simulated module for predevelopmental and developmental tests leading to the design of the spacecraft module.

BOOSTER ENGINE

An engine, especially a booster rocket, that adds thrust to the thrust of the sustainer engine, or provides propulsion for a special phase of flight.

BREADBOARD MODEL

An assembly of preliminary circuits and parts to prove the feasibility of a device. circuits, equipment, system or principle in rough or breadboard form without regard to the eventual over-all design or form of parts.

BRIDGE WIRE

The ignition resistor filament. The bridge wire heats the primary explosive to initiate the explosion.

CELESTIAL GUIDANCE

Mechanically or electrically recorded navigational tables, computers, and other instruments and devices that sight stars, calculate position, direct, and control the spacecraft.

CENTRIFUGE

A large motor-driven apparatus with a long rotating arm at the end of which human and animal subjects or equipment can be revolved at various speeds to simulate accelerations encountered in high-performance vehicles.

CHECKOUT

v vad≱ self

A sequence of operational and calibrational tests needed to determine the condition and status of a required operation or function.



COASTING FLIGHT

The flight of a rocket or other vehicle between burnout or thrust cutoff of one stage and ignition of another, or between final burnout and summit altitude or maximum range. Also the unpowered portion of an interplanetary flight.

COMMAND MODULE

Personnel and control vehicle in the Apollo spacecraft configuration containing command and communication facilities and crew provisions.

COMPATIBILITY

The quality that permits an item to function in harmony with other equipment and fulfill all design objectives.

CONFIGURATION

The physical nature of an item; the physical arrangement of components which comprise a spacecraft and its dimensions.

CONSOLE

Master instrument panel from which rocket and missile launchings and test are controlled; a group of controls, indicators, and similar electrical or mechanical equipment that is used to monitor readiness of and/or control specific functions such as missile checkout, countdown and launch operations.

COUNTDOWN

Series of numbered events and checks that take place from the start of rocket-launching operations until the rocket lifts off the launch stand.

CRYOGENIC FUEL

A rocket fuel that either in itself is kept at very low temperatures or combines with an oxidizer kept at very low temperatures.

CUTOFF

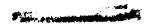
The shutting off of a liquid or solid-propellant combustion process of a rocket engine, causing a rapid drop toward zero thrust (intentional command action).

DEEP SPACE INSTRU-MENTATION FACILITY (DSIF) Communication equipment capable of contacting and tracking spacecraft beyond normal ranges. DSIF facilities are located at Woomera, Australia; Johannesburg, South Africa; and Goldstone, California









DEMONSTRATE

Denotes the occurrence of an action or an event during a test. The accomplishment of this type of objective requires a qualitative answer. The answer will be derived through the relation of this action or event to some other known information or occurrence. This category of objectives implies a minimum of system instrumentation and/or that information be obtained external to the test vehicle.

DESIGN VERIFICATION TEST

Basic development test used to determine the adequacy of the design over the anticipated operating conditions. A design verification test is always conducted by Engineering and on a breadboard level.

DETERMINE

Denotes the measuring of performance of any unit or system. This category implies the quantitative investigation of over-all operation, which includes, generally, instrumentation for measuring basic inputs and outputs of the unit or system. The information obtained should indicate to what extent the system is operating as designed. The instrumentation should allow performance deficiencies to be isolated to either the system or the system inputs.

DRAG

The resistance of a body to motion in a medium such as air.

DRY WEIGHT

Weight of a rocket vehicle without its fuel and usually without payload.

EARTH LANDING SUBSYSTEM (ELS)

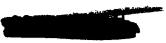
Acceleration-decreasing equipment for return to the earth's surface after atmospheric reentry; may consist of a parachute system, a flexible aerodynamic glider configuration, or both.

ENGINEERING DEVELOP-MENT PART A part or unit to be employed in a breadboard design.

ENVIRONMENTAL CONTROL SUBSYSTEM (ECS)

The components controlling crew conditions in the spacecraft; governing factors of atmosphere, pressure, and temperature; and providing support for spacesuit conditions in event of cabin decompression or extra vehicular operations.





ESTABLISH

Denotes gathering information for the development of ground procedures and operating techniques. Objectives in this category are not necessarily dependent on analytic studies.

EVALUATE

Denotes the measuring of performance of any unit or system, as well as the performance and/or interaction of its sections or subsystems that are under investigation. The accomplishment of objectives of this type requires quantitative data on the performance of both the unit or system, and its sections or subsystems will be analyzed for their contribution toward performance of the unit or system. This category will provide the most detailed information of any of these categories.

FALLAWAY SECTION

Any section of a rocket vehicle that is cast off and falls away from the vehicle during flight, especially such a section that falls back to earth.

FIRST MOTION

First indication of motion of the missile or test vehicle from its launcher. Synonymous with "takeoff" for vertically launched missiles.

FLIGHT READINESS FIRINGS (FRF)

A missile system test consisting of the complete firing of the liquid-propellant engines of a rocket missile while it is restrained in its launching stand to verify the readiness of the missile for a flight test or mission.

FREE-FLIGHT TRAJECTORY (Free Fall Ellipse) That part of a ballistic missile's trajectory that begins with thrust cutoff and ends at reentry.

FUEL CELL

A source of electrical power analogous to a common electrical cell with the reactants continually replenished from an external supply.

GAMMA RADIATION

Electromagnetic radiation having a high degree of penetration similar to X-rays originating from the nucleus.





GEMINI

NASA follow-up program to Mercury; a twoman spacecraft to demonstrate rendezvous and docking techniques, longer orbital flights (to 14 days), controlled reentry, and landing.

GIMBALED MOTOR

A rocket motor mounted on a gimbal, i. e., on a contrivance having two mutually perpendicular axes of rotation so as to correct pitching and yawing.

GODDARD SPACE FLIGHT CENTER (GSFC)

NASA research center at Greenbelt, Maryland, named for Robert H. Goddard, American rocket pioneer.

GOLDSTONE TRACKING FACILITY

A deep space instrumentation facility located at Army's Camp Irvin, Barstow, California, using a radiotelescope and operated for NASA by Jet Propulsion Laboratory (JPL).

GO NO-GO

A missile launch controlled at the end of the countdown as to permit an instantaneous change in decision on whether or not to launch.

GROUND OPERATIONAL SUPPORT SYSTEM (GOSS)

Network of tracking stations, fixed and mobile, air, ground, and seaborne to communicate with, track, and telemeter spacecraft and satellites.

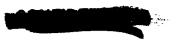
GROUND SUPPORT EQUIPMENT (GSE)

All ground equipment that is part of the complete spacecraft system and that must be furnished to ensure its support. All implements or devices required to maintain the functional operational status of the spacecraft are included. In the Apollo program, bench maintenance equipment, combined system test unit, and prelaunch automatic checkout equipment comprise the GSE.

GUIDANCE

(1) The process of intelligent gathering and maneuvering required by a missile, probe, or space ship to reach a specified destination.
(2) General term includes entire scheme: sensing devices, computers, and servo systems.





14 W 13

HEAT SHIELD

An ablative protective covering to ensure spacecraft and crew survival through the hypertemperatures of atmospheric reentry.

HEAT SINK

A device that absorbs heat energy.

HOT TEST

Propulsion system test conducted by actually firing the propellants. A hot test may be live, static, or conducted in a confined place.

INERTIAL GUIDANCE

An onboard guidance system for space and satellite vehicles where gyros, accelerometers, and possibly a gyro-stabilized platform satisfy guidance requirements without use of any ground-located components. The system is entirely automatic, following predetermined trajectory.

INFRARED LIGHT

Light in which the rays lie just below the red

end of the visible spectrum.

INITIATOR

A primary explosive mixture used as a primer, detonator for caps which initiates the explosion of blasting propellant, bursting explosives at

the desired moment.

INTERIM QUALIFIED

A term used to describe the status of a component or system scheduled for use in early flights wherein the basically essential qualification tests have been successfully completed as related to the specific flight objectives.

INVERTER

A converter to a-c power from a d-c source.

JET STEERING

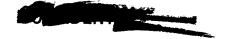
The use of fixed or movable gas jets on a space weapon, ballistic missile, or sounding rocket for thrust vector control to steer it along a desired trajectory, during both propelled flight and after thrust cutoff.

KELVIN SCALE (K)

A temperature scale that used Centigrade degrees as gradients and absolute zero for zero. Zero Kelvin equals -460 F or -273 C.

9-8





LANGLEY RESEARCH CENTER NASA installation in Hampton, Virginia, responsible for technical research in development and improvement in both atmospheric and space flight.

LAUNCH WINDOW

The allowable limits of launch time that will allow a spacecraft to achieve successful injection into programmed flight path.

LAUNCH ESCAPE SUBSYSTEM (LES)

The components for command module recovery in case of mission abort after launch and prior to orbit. The system consists of the launch escape motor, the launch escape tower, and the tower jettison motor.

LIQUID HYDROGEN

Liquid rocket fuel that develops a specific impulse, when oxidized by liquid oxygen, ranging between 317 and 364 seconds depending upon the mixture ratio.

LIQUID OXYGEN

Oxygen supercooled and kept under pressure so that its physical state is liquid. Used as an oxidizer in a liquid-fuel rocket.

LITTLE JOE (I, II)

A solid-rocket test vehicle developed by General Dynamics. I was used especially to test the Mercury capsule, and II will be used to test the Apollo spacecraft.

LUNAR EXCURSION MODULE

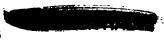
The two-man vehicle that will land on the moon after the Apollo spacecraft enters lunar orbit.

LUNAR ORBITAL RENDEZVOUS

The concept for manned lunar landing adopted by NASA wherein the lunar excursion module leaves the spacecraft, lands on the moon, and later returns to the orbiting spacecraft. The excursion module will be jettisoned as the spacecraft leaves lunar orbit.

MANNED SPACECRAFT CENTER (MSC)

NASA headquarters responsible for development and operation of manned space vehicles (Mercury, Gemini, Apollo), located in Houston, Texas.





MARSHALL SPACE FLIGHT CENTER (MSFC) NASA operation responsible for design and development of space launch vehicles (Saturn, Advanced Saturn, Nova), located in Huntsville, Alabama.

MOCK-UP

A full-scale, three-dimensional representation of a complete spacecraft, individual module, and/or related equipment. Based on permanence and difficulty of alteration, mock-ups are graded as "soft," "semi-hard," and "hard."

MODULE

A combination of components, contained in one package or so arranged that together they are common to one mounting, which provides a complete function. (See command module, service module, lunar excursion module, etc.)

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION (NASA) Civilian agency, sponsored by the U.S. Government, with research and development jurisdiction in aeronautical and space activities except those activities peculiar to or primarily associated with the development of weapon systems, military operations, or the defense of the United States.

NAUTICAL MILE (NM)

A measure of distance equal to 6,076, 103 feet or approximately 1.15 mile.

OBTAIN DATA

Denotes gathering engineering information that is to be measured to augment the general knowledge required in the development of the over-all spacecraft. This category may also be used for supplemental investigation, such as environmental studies, ground equipment studies, etc. The degree of instrumentation is not implied by this definition.

OPTICAL STAR TRACKER

· - 2.5

A star tracker that locks onto the light of a particular celestial body. Distinguished from a radiometric star tracker. (See star tracker.)

OXIDIZER

A rocket propellant component, such as liquid oxygen, nitric acid, fluorine, and others, that supports the combustion of a fuel.

PAD

A permanent or semipermanent load-bearing surface constructed or designed as a base upon which a launcher can be placed. Short for launch pad.

PITCH

The movement about an axis that is at once perpendicular to the Apollo longitudinal axis and horizontal to the Y-axis of the spacecraft.

PRE-QUALIFIED

A pre-qualified part or component is one that has been scheduled as the one most likely to succeed in the qualification program and will be used in production runs as well as during developmental test or early flight test prior to qualification.

PRESSURIZED SUIT

A garment designed to provide pressure upon the body so that respiratory and circulatory functions may continue normally, or nearly so, under low-pressure conditions, such as occur at high altitudes or in space without benefit of a pressurized cabin.

PROGRAMMED ROLL

An automatically controlled roll of a ballistic missile or satellite, usually executed during its vertical ascent before pitch-over.

PROGRAMMED TURN

The turn of a ballistic missile from vertical motion, after lift-off, to a curved path approximating the desired powered flight trajectory prior to the initiation of guidance.

PROPELLANT

A liquid or solid substance burned in a rocket for the purpose of developing thrust.

·PROTOTYPE

~1

A model suitable for complete evaluation of mechanical and electrical form, design, and performance. It is in final mechanical and electrical form, employing approved parts, and completely representative of the final equipment.

QUALIFICATION OF PART, COMPONENT, OR SYSTEM

A part, component, or system is considered qualified by definition after it has successfully completed all of the prescribed tests associated with relevant control specifications.



* \$ \$,

READOUT

A radio transmitter transmitting data either instantaneously with computation of the data or by play of a magnetic tape on which the data have been recorded.

RECOVERY

The act of retrieving a portion of a launched missile or satellite that has survived reentry.

REENTRY

Return of a part of a space vehicle to the atmosphere after flight above the sensible atmosphere.

RELIABILITY

Reliability is the probability of performing without failure a specified function, under given conditions, for a specified period of time. It deals with the failure rates in time of specific items.

RETROROCKET

Relatively small rocket unit, usually solid propellant, installed on a rocket-propelled vehicle and fired in a direction opposite to the main motion to decelerate main unit.

ROLL

The movement of Apollo about its longitudinal (X) axis.

SATURN

The sun's sixth planet. A NASA rocket engine cluster in research and development expected to develop some 1,500,000 pounds of first-stage thrust. The Apollo launch vehicle.

SEPARATION

Moment when a full stage, half stage, a warhead, or a nose cone is separated from the remainder of the rocket vehicle; the moment when staging is accomplished.

SERVICE MODULE

Apollo module carrying propulsion equipment, fuel, reaction control systems, and communications power. It is used for thrust after booster separation, mid-course correction, lunar orbit, lunar orbit ejection, and earth return midcourse correction. It is jettisoned prior to reentry.

SERVICE PROPULSION SYSTEM

Engine and associated equipment providing thrust for service module functions. (See SERVICE MODULE.)



サークの大きなでは、カンプを取り、大

SOFT LANDING

Landing on the moon or other spatial body at such slow speed as to avoid damage of landing vehicle. Soft landings on moon are anticipated by use of retrorockets.

SOLAR FLARE

Solar phenomenon that gives rise to intense ultraviolet and corpuscular emission from the associated region of the sun. This affects the structure of the ionosphere and interferes with communications.

SOLID PROPELLANT

A propellant in solid condition including all the ingredients necessary for sustained chemical combustion, such as a compound of fuel and oxidizer, usually in plastic caked form. It burns on its exposed surface, generating hot exhaust gases to produce a reaction force.

SPACECRAFT

In the Apollo program, any component or combined components of the flight vehicle not part of the launch vehicle: launch escape subsystem, command module, service module, adapter, or any combination of these.

SPECIFIC IMPULSE

The thrust produced by a jet-reaction engine per unit weight of propellant burned per unit time, or per mass of working fluid passing through the engine in unit time. It is equal to thrust in pounds divided by weight flow rate in pounds per second.

STABILIZATION AND CONTROL SUBSYSTEM (SCS)

An Apollo monitor system linked to navigation and guidance system, display system, and reaction control subsystem indicating spacecraft attitude (roll, yaw, or pitch).

STAGE

In a rocket vehicle powered by successive units, one or other of the separate propulsion units.

STAGNATION POINT

The location on a surface in an airstream where the air flow is zero.





STAR TRACKER

A telescopic instrument on a missile or spacecraft that locks onto a celestial body and gives guidance to the missile or other object during flight.

STATIC TESTING

Testing of a missile or other device in a stationary or holddown position, to verify structural integrity, to determine the effects of limit loads, or to measure thrust.

SYSTEMS ENGINEERING

Process of applying science and technology to the study and planning of an over-all aerospace vehicle system, whereby relationships of various parts of the system and the use of various subsystems are fully planned and integrated prior to time hardware designs are committed.

TELEMETERING

The technique of recording space data by radioing an instrument reading from a rocket to a recording machine on the ground.

THEODOLITE

A sighting and measuring telescopic instrument that gives a reading on horizontal or vertical angles.

TRAJECTORY

The path described by a missile or a space vehicle.

TRANSFER ELLIPSE

Path followed by a body moving from one elliptical orbit to another.

ULLAGE

The amount of fluid by which a tank falls short of being full; the loss through evaporation, spilling, or consumption; the amount remaining that cannot be drained from an emptied tank or container.

UMBILICAL

Any one of several electrical or fluid lines connected between the ground support operation and an uprighted rocket missile or space vehicle before launch.

UNSYMMETRICAL DIMETHYLHYDRAZINE (UDMH) Rocket fuel which with aerozine will power the Apollo spacecraft.







VECTOR STEERING

Vernacular for a steering method where one or more thrust chambers are gimbal mounted so that the direction of the thrust force (thrust vector) may be tilted in relation to the center of gravity of the missile to produce turning.

VELOCITY VECTOR

Combination of two ballistic missile trajectory values: the speed of the missile's center of gravity at a designated point on the trajectory and angle between local vertical and the direction of the speed.

WHITE SANDS MISSILE RANGE (WSMR)

A proving ground in New Mexico under the control of the Army Ordnance Missile Command; supports Apollo abort tests.

YAW

Lateral movement of the Apollo spacecraft along the Z-axis in line of flight.





REFERENCES

MIL Specs

MIL-E-4970A

MIL-E-5151

MIL-E-5272C

MIL-R-27542

S&ID Documents

MC 999-0002B

SID 62-204

SID 62-1405

NASA Document

NCP 200-2

U.S. Government Printing Office

Reliability of Military Electronic Equipment, dated 4 June 1957.



DISTRIBUTION FOR TEST PLAN* (PARAGRAPH 3.3)

Address	Copies
National Aeronautics and Space Administration Atlantic Missile Range Operations Port Canaveral, Florida Attn: Mr. B.P. Brown	5
NASA Headquarters 1520 H Street Washington, D. C. Attn: Mr. G.M. Low, MD(P)	6
Grumman Aircraft Engineering Corporation Bethpage, Long Island, New York Attn: P. Gardiner	1
MIT Instrumentation Laboratory 75 Cambridge Parkway Cambridge 39, Massachusetts	1
NASA Resident Apollo Spacecraft Project Officer Grumman Aircraft Engineering Corporation Bethpage, Long Island, New York Attn: Mr. Jack Small	1
National Aeronautics and Space Administration Post Office Drawer D White Sands Missile Range White Sands, New Mexico	2
National Aeronautics and Space Administration Manned Spacecraft Center Transportation Officer Elington Building 381 Houston, Texas Attn: Apollo Document Control Center Elington 336 - TO BE OPENED BY ADDRESSEE ONLY	40

The distribution for this report has been accomplished in compliance with paragraph 1. 2 of Exhibit I of contract NAS9-150 and the NASA Apollo Documentation Distribution List (NASA-MSC letter SP-63-478, dated 2 October 1963).

Address	Copies
National Aeronautics and Space Administration Headquarters NASA Plant Officer P.O. Box 2500 Daytona Beach, Florida Attn: Administrative Contracting Officer	2
National Aeronautics and Space Administration Manned Spacecraft Center Resident Apollo Spacecraft Project Office NAA 12214 Lakewood Boulevard	4
Downey, California National Aeronautics and Space Administration	2
Ames Research Center Moffett Field, California Attn: Library	
National Aeronautics and Space Administration Lewis Research Center Cleveland, Ohio Attn: Library	2
National Aeronautics and Space Administration Flight Research Center Edwards AFB, California Attn: Research Library	2
National Aeronautics and Space Administration Jet Propulsion Laboratory Pasadena, California Attn: Library	2
National Aeronautics and Space Administration Langley Research Center Langley AFB, Virginia Attn: Mr. A.T. Mattson	2
National Aeronautics and Space Administration Goddard Space Flight Center Greenbelt, Maryland Attn: Manned Flight Support Office, Code 512	2
National Aeronautics and Space Administration George C. Marshall Space Flight Center Huntsville, Alabama Attn: M-SAT-AP	2
National Aeronautics and Space Administration Resident Apollo Spacecraft Project Office MIT Instrumentation Laboratory 75 Cambridge Parkway Cambridge 39 Massachusetts	1